

Gecko Foot

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Introduction

In nature, various species apply advanced techniques for specialized tasks. For instance, gecko lizards use dry adhesion forces such as van der Waals forces to climb walls. Dry adhesion is a phenomenon of interest for sticking because it requires no energy to hold on, and no residue is left on the surface. Gecko lizards have inspired researchers to develop synthetic gecko foot hairs for use in, for example, robots.

A strand of hair on a gecko foot is a very complex biological structure with hierarchical nanosections and microsections. On its feet, a gecko has billions of nanoscale hairs that are in contact with surfaces while it climbs. These nanohairs are attached to microscale hairs, which are on the tip of the gecko's toes.

Critical design parameters for nanohairs to achieve optimal sticking are hair length, detach angle, distance between nanohairs, and the cross-sectional area of a single strand of hair. By varying these parameters, it is possible to design hairs that can stick to very rough surfaces. At the same time, they must be stiff enough to avoid sticking to each other. Proper material choices help achieving the design goals while providing the required adhesion force. Typically the Young's modulus for materials used in synthetic nanohair vary between 1 GPa and 15 GPa.

Model Definition

This model contains the hierarchy of synthetic gecko foot hair where nanoscale and microscale cantilever beams describe the seta and spatula parts of a spatular stalk attached to a gecko foot. The basis of the analyzed structure is a microscale stalk with the following dimensions: width, 4.53 μ m; height, 4.33 μ m; and length, 75 μ m. At the end of the microhair, 169 nanohairs are attached and they have dimensions of 0.18 μ m, 0.17 μ m, and 3 μ m, respectively. The microhair is fixed at the far end, while the contact and friction forces appear as surface loads at the end of each nanohair. The free-body diagram of a micro/nanohair in Figure 1 illustrates the applied forces, which are set to 0.4 μ N for the contact force and 0.2 μ N for the friction force with 60° contact angle to target surface. The structure is made of β -keratin with a Young's modulus of 2 GPa and a Poisson's ratio of 0.4. The model was inspired by Ref. 1.



Figure 1: Model of the tip of a gecko foot hair.

Results and Discussion

The plot in Figure 2 shows the von Mises equivalent stress in the model. Table 1 lists the maximum values of the von Mises stress, total displacement, and principal strain:

TABLE I: STRESS, DISPLACEMENT, AND PRINCIPAL STRAIN RESULTS IGNORING GEOMETRIC NONLINEARI	ILINEARITY.
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MAXIMUM VON MISES STRESS (N/M ²)	MAXIMUM TOTAL DISPLACEMENT (μm)	MAXIMUM FIRST PRINCIPAL STRAIN	
9.52·10 ⁷	12.6	0.0505	

The maximum von Mises stress in the analyzed model is almost twice the value of the material's yield stress, which clearly indicates that further investigation is required.

The deformed plot in Figure 2 shows that displacement is large, while the results in the table above indicate that the maximum strain is moderate. Hence, the next step is to enable the geometric nonlinearity within the linear elastic material model. (An alternative would be to search for a suitable hyperelastic material model, which would require the corresponding material data.)



Figure 2: Deformed shape plot of the von Mises stress in a synthetic gecko foot ignoring geometric nonlinearity. The plot shows the displacements without any scaling.



Figure 3: The result recomputed with the geometric nonlinearity taken into account.

You include the geometric nonlinearity by selecting the corresponding check box in the Linear Elastic Material Model feature node. The resulting changes in the model equations are shown under the Equation section therein.

The plot in Figure 3 shows the resulting von Mises stress distribution and the deformation, and Table 2 below gives the recomputed maximum values.

TABLE 2: STRESS, DISPLACEMENT, AND PRINCIPAL STRAIN RESULTS INCLUDING GEOMETRIC NONLINEARITY EFFECTS.

MAXIMUM VON MISES STRESS (N/M ²)	MAXIMUM TOTAL DISPLACEMENT (μm)	MAXIMUM FIRST PRINCIPAL STRAIN	
1.73·10 ⁷	2.93	8.85·10 ⁻³	

The results show that without the geometric nonlinearity taken into account, the model overpredicts the maximum von Mises stress by more than a factor of five, and the maximum displacement by more than a factor of four. Furthermore, the maximum strain computed with the geometric nonlinearity included becomes less than 1%, which eliminates the need of further analysis involving more complicated hyperelastic material models.

References

1. G. Shah and I. Lee, *Finite Element Analysis of Gecko Foot Hairs for Dry Adhesive Design and Fabrication*, Dept. of Mechanical Engineering — NanoRobotics Lab, Carnegie Mellon Univ., Pittsburgh.

2. M. Sitti and R.S. Fearing, "Synthetic Gecko Foot-Hair Micro/Nano-Structures for Future Wall-Climbing Robots", *Proc. IEEE Robotics and Automation Conf.*, Sept. 2003.

3. J. Vincent, Structural Biomaterials, rev. ed., Princeton University Press, 1990.

Application Library path: MEMS_Module/Actuators/gecko_foot

Modeling Instructions

From the File menu, choose New.

NEW

In the New window, click 🙆 Model Wizard.

MODEL WIZARD

- I In the Model Wizard window, click 间 3D.
- 2 In the Select Physics tree, select Structural Mechanics>Solid Mechanics (solid).
- 3 Click Add.
- 4 Click \bigcirc Study.
- 5 In the Select Study tree, select General Studies>Stationary.
- 6 Click M Done.

GLOBAL DEFINITIONS

Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
Fc	0.4[uN]	4E-7 N	Contact force
Ff	0.2[uN]	2E-7 N	Friction force
theta	pi/3	1.0472	Contact angle
Dm	75[um]	7.5E-5 m	Microhair length
Hm	4.33[um]	4.33E-6 m	Microhair width
Wm	4.53[um]	4.53E-6 m	Microhair height
Dn	3[um]	3E-6 m	Nanohair length
Hn	0.17[um]	I.7E-7 m	Nanohair width
Wn	0.18[um]	I.8E-7 m	Nanohair height
Area	Wn*Hn	3.06E-14 m ²	Cross-sectional area of the spatulas

GEOMETRY I

- I In the Model Builder window, under Component I (compl) click Geometry I.
- 2 In the Settings window for Geometry, locate the Units section.
- **3** From the **Length unit** list, choose **µm**.

Nanohair

- I In the **Geometry** toolbar, click 🗍 **Block**.
- 2 In the Settings window for Block, locate the Size and Shape section.

- 3 In the Width text field, type Wn.
- 4 In the **Depth** text field, type Dn.
- 5 In the **Height** text field, type Hn.
- 6 Locate the Position section. In the y text field, type -Dn.
- 7 In the Label text field, type Nanohair.

Next, add object selections for the nanohair's root and end. An object selection is defined by a set of geometric entities at a specified level selected from the geometric objects that precede the object selection feature in the geometry sequence. Their main advantage compared to regular selection features is that object selections propagate through the geometry sequence, which make them robust and convenient to apply in cases like the present one.

Nanohair ends

- I In the Geometry toolbar, click 🝖 Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, locate the Entities to Select section.
- 3 From the Geometric entity level list, choose Boundary.
- 4 On the object **blk1**, select Boundary 3 only.



y x

5 In the Label text field, type Nanohair ends.

Nanohair roots

I In the Geometry toolbar, click 🐚 Selections and choose Explicit Selection.

- 2 Click the 🗮 Wireframe Rendering button in the Graphics toolbar.
- 3 In the Settings window for Explicit Selection, locate the Entities to Select section.
- **4** From the **Geometric entity level** list, choose **Boundary**.
- 5 On the object **blk1**, select Boundary 6 only.
- 6 Click the 🔁 Wireframe Rendering button in the Graphics toolbar.
- 7 Click 틤 Build Selected.
- 8 In the Label text field, type Nanohair roots.

Array I (arr1)

- I In the Geometry toolbar, click 💭 Transforms and choose Array.
- 2 Select the object **blk1** only.
- 3 In the Settings window for Array, locate the Size section.
- 4 In the x size text field, type 13.
- 5 In the z size text field, type 13.
- 6 Locate the Displacement section. In the x text field, type (Wm-Wn)/12.
- 7 In the z text field, type (Hm-Hn)/12.
- 8 Click 📄 Build Selected.
- 9 Click the **Com Extents** button in the **Graphics** toolbar.

Microhair

- I In the **Geometry** toolbar, click 🗍 Block.
- 2 In the Settings window for Block, locate the Size and Shape section.
- 3 In the Width text field, type Wm.
- 4 In the **Depth** text field, type Dm.
- 5 In the **Height** text field, type Hm.
- 6 Click 틤 Build Selected.
- 7 In the Label text field, type Microhair.

Microhair end

- I In the Geometry toolbar, click 🝖 Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, locate the Entities to Select section.
- **3** From the **Geometric entity level** list, choose **Boundary**.

4 On the object **blk2**, select Boundary 3 only.

It might be easier to select the correct boundary by using the **Selection List** window. To open this window, in the **Home** toolbar click **Windows** and choose **Selection List**. (If you are running the cross-platform desktop, you find **Windows** in the main menu.)



- 5 Click **Build Selected**.
- 6 In the Label text field, type Microhair end.
- 7 Click the $\sqrt[1]{}$ Go to Default View button in the Graphics toolbar.

Form Union (fin)

Use an assembly to connect parts of the geometry of significantly different dimensions.

- I In the Model Builder window, under Component I (compl)>Geometry I click Form Union (fin).
- 2 In the Settings window for Form Union/Assembly, locate the Form Union/Assembly section.
- **3** From the Action list, choose Form an assembly.
- 4 Clear the **Create pairs** check box.
- 5 Click 틤 Build Selected.

The model geometry is now complete.

DEFINITIONS

Because of the use of assembly, you need to add an identity pair to set up the displacement field continuity at the interfaces, where the nanohairs are attached to the microhair. Configure the identity to operate on the material frame, because this is the frame used within the **Solid Mechanics** interface.

Identity Boundary Pair I (p1)

- I In the Definitions toolbar, click H Pairs and choose Identity Boundary Pair.
- 2 In the Settings window for Pair, locate the Source Boundaries section.
- 3 From the Selection list, choose Microhair end.
- **4** Locate the **Destination Boundaries** section. Click to select the **Destination Boundaries** section. toggle button.
- 5 From the Selection list, choose Nanohair roots.

Define a rotated coordinate system to account for the contact angle.

Rotated System 2 (sys2)

- I In the Definitions toolbar, click \sum_{x}^{y} Coordinate Systems and choose Rotated System.
- 2 In the Settings window for Rotated System, locate the Rotation section.
- **3** Find the **Euler angles (Z-X-Z)** subsection. In the β text field, type pi/2-theta.

MATERIALS

Material I (mat1)

- I In the Model Builder window, under Component I (compl) right-click Materials and choose Blank Material.
- 2 In the Settings window for Material, locate the Material Contents section.
- **3** In the table, enter the following settings:

Property	Variable	Value	Unit	Property group
Young's modulus	E	2e9	Pa	Young's modulus and Poisson's ratio
Poisson's ratio	nu	0.4	I	Young's modulus and Poisson's ratio
Density	rho	1200	kg/m³	Basic

DEFINITIONS

Set up a maximum operator to compute maximum values of the von Mises stress, displacement magnitude, and principal strain over the entire geometry.

Maximum I (maxopI)

- I In the Definitions toolbar, click / Nonlocal Couplings and choose Maximum.
- 2 In the Settings window for Maximum, locate the Source Selection section.
- 3 From the Selection list, choose All domains.

Variables I

- I In the **Definitions** toolbar, click $\partial =$ **Local Variables**.
- 2 In the Settings window for Variables, locate the Variables section.
- **3** In the table, enter the following settings:

Name	Expression	Unit	Description
max_v_Mises	<pre>maxop1(solid.mises)</pre>	N/m²	Maximum von Mises stress
max_disp	<pre>maxop1(solid.disp)</pre>	m	Maximum displacement magnitude
max_ep1	<pre>maxop1(solid.ep1)</pre>		Maximum first principal strain

SOLID MECHANICS (SOLID)

Fixed Constraint I

- I In the Model Builder window, under Component I (compl) right-click Solid Mechanics (solid) and choose Fixed Constraint.
- 2 Select Boundary 83 only.

Boundary Load 1

- I In the Physics toolbar, click 🔚 Boundaries and choose Boundary Load.
- 2 In the Settings window for Boundary Load, locate the Boundary Selection section.
- 3 From the Selection list, choose Nanohair ends.
- 4 Locate the Coordinate System Selection section. From the Coordinate system list, choose Rotated System 2 (sys2).
- ${\bf 5}~$ Locate the Force section. Specify the ${\bf F}_A$ vector as

0	хI
-Fc/Area	x2
Ff/Area	x3

Continuity I a

I In the Physics toolbar, click 💭 Pairs and choose Continuity.

- 2 In the Settings window for Continuity, locate the Pair Selection section.
- **3** Under Pairs, click + Add.
- 4 In the Add dialog box, select Identity Boundary Pair I (pl) in the Pairs list.
- 5 Click OK.

MESH I

Mapped I

- I In the Mesh toolbar, click \bigwedge Boundary and choose Mapped.
- 2 In the Settings window for Mapped, locate the Boundary Selection section.
- 3 From the Selection list, choose Nanohair ends.

Size I

- I Right-click Mapped I and choose Size.
- 2 In the Settings window for Size, locate the Element Size section.
- 3 Click the **Custom** button.
- 4 Locate the Element Size Parameters section.
- 5 Select the Maximum element size check box. In the associated text field, type 0.1.

Mapped I

In the Model Builder window, right-click Mapped I and choose Build Selected.

Swept I

- I In the Mesh toolbar, click 🎄 Swept.
- 2 In the Settings window for Swept, locate the Domain Selection section.
- 3 From the Geometric entity level list, choose Domain.
- 4 From the Selection list, choose All domains.
- **5** Remove Domain 14 from the selection.

Distribution I

Right-click Swept I and choose Distribution.

Swept I

In the Model Builder window, right-click Swept I and choose Build Selected.

Mapped 2

- I In the Mesh toolbar, click \bigwedge Boundary and choose Mapped.
- 2 Select Boundary 83 only.

Distribution I

I Right-click Mapped 2 and choose Distribution.

2 Select Edges 162–164 and 168 only.

Mapped 2

In the Model Builder window, right-click Mapped 2 and choose Build Selected.

Swept 2

In the Mesh toolbar, click 🎪 Swept.

Distribution I

- I Right-click Swept 2 and choose Distribution.
- 2 Right-click Distribution I and choose Build Selected.

The mesh is now complete.

STUDY I

In the **Home** toolbar, click **= Compute**.

RESULTS

Stress (solid)

Reproduce the plot in Figure 2 by following these steps:

I In the Model Builder window, expand the Stress (solid) node.

Deformation

- I In the Model Builder window, expand the Results>Stress (solid)>Volume I node, then click Deformation.
- 2 In the Settings window for Deformation, locate the Scale section.
- **3** Select the **Scale factor** check box. In the associated text field, type 1.
- 4 In the Stress (solid) toolbar, click 💿 Plot.
- **5** Click the **F Zoom Extents** button in the **Graphics** toolbar.

Compare the resulting plot to that in Figure 2.

Next, calculate the maximum values for von Mises stress, displacement magnitude, and first principal strain; compare the results to those shown in Table 1.

Global Evaluation I

I In the Results toolbar, click (8.5) Global Evaluation.

- In the Settings window for Global Evaluation, click Replace Expression in the upper-right corner of the Expressions section. From the menu, choose Component I (compl)> Definitions>Variables>max_v_Mises Maximum von Mises stress N/m².
- 3 Click **= Evaluate**.

Global Evaluation 2

- I In the **Results** toolbar, click (8.5) **Global Evaluation**.
- In the Settings window for Global Evaluation, click Replace Expression in the upper-right corner of the Expressions section. From the menu, choose Component I (compl)>
 Definitions>Variables>max_disp Maximum displacement magnitude m.
- 3 Click next to = Evaluate, then choose Table I Global Evaluation I.

Global Evaluation 3

- I In the **Results** toolbar, click (8.5) **Global Evaluation**.
- In the Settings window for Global Evaluation, click Replace Expression in the upper-right corner of the Expressions section. From the menu, choose Component I (compl)> Definitions>Variables>max_epl Maximum first principal strain.
- **3** Click **•** next to **= Evaluate**, then choose **Table I Global Evaluation I**.

SOLID MECHANICS (SOLID)

Linear Elastic Material 1 Now, switch on geometric nonlinearity.

STUDY I

- Step 1: Stationary
- I In the Model Builder window, under Study I click Step I: Stationary.
- 2 In the Settings window for Stationary, locate the Study Settings section.
- **3** Select the **Include geometric nonlinearity** check box.
- **4** In the **Home** toolbar, click **= Compute**.

RESULTS

Stress (solid) Compare the plot in the **Graphics** window with that in Figure 3.

Global Evaluation 1

Finally, compute the new maximum values and display them in a new table. Compare the results to those in Table 2.

I In the Model Builder window, under Results>Derived Values right-click Global Evaluation I and choose Evaluate>New Table.

Global Evaluation 2

In the Model Builder window, right-click Global Evaluation 2 and choose Evaluate>Table 2 - Global Evaluation 1.

Global Evaluation 3

In the Model Builder window, right-click Global Evaluation 3 and choose Evaluate>Table 2 - Global Evaluation 1.