

# Mechanism Submerged in Fluid

## Introduction

Fluid-structure interaction (FSI) is a common class of multiphysics problems. The coupling is in general bidirectional; the fluid exerts an external load on the structure, leading to deformation of structural components, and, conversely, the motion or deformation of the structural components changes the flow field. Depending on the type of interaction between fluids and solid objects, FSI problems can be categorized as either one-way problems or fully coupled problems.

This example demonstrates the dynamics of a moving mechanism, with two rotating fins, submerged in a fluid channel. The fluid domain is modeled using the Laminar Flow interface, and the mechanism is modeled using the Multibody Dynamics interface. A Fluid-Structure Interaction, Pair multiphysics coupling is used to model the interaction between the fluid and solid domains, and an ALE formulation through a Moving Mesh node is used to control the geometrical changes of the fluid domain. A time-dependent study is used to simulate the forward motion of the mechanism through the fluid channel induced by the fin rotation.

## Model Definition

The model geometry consists of a mechanism with a central body and two fins. The mechanism is submerged in a flow channel. The fins are located at the back of the body, symmetrically placed on both sides of the longitudinal axis at an initial angle of 30°. The fins are connected to the central body through hinge joints, which allow in-plane rotation of the fins, as shown in Figure 1. The mechanism is submerged in a flow channel of 25 cm width, 15 cm depth, and 5 cm height.

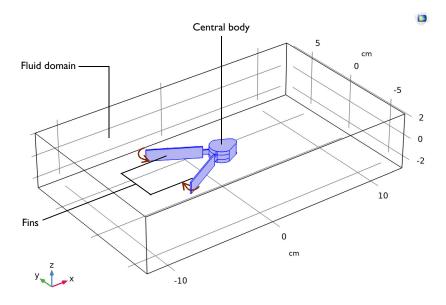


Figure 1: Geometry of the mechanism submerged in a fluid channel.

## MATERIALS

The components of the mechanism are built of structural steel and the fluid around the mechanism is taken as water.

#### FLUID-STRUCTURE INTERACTION

The interaction between the fluid and the solid domains is modeled using a Fluid-Multibody Interaction, Assembly interface. This interface consists of a predefined Laminar Flow interface, a Multibody Dynamics interface, and a Moving Mesh node with a Deforming **Domain** subnode. In addition, a **Multiphysics Couplings** node is added. It contains the multiphysics coupling Fluid-Structure Interaction, Pair. Additional details about the interface can be found in the documentation for Multiphysics Couplings in the Multibody Dynamics Module User's Guide.

The interaction between the fluid and the structural mechanism is specified through the interface boundaries between the two domains. The two identity pairs between the fluid and solid domains are selected in the Fluid-Structure Interaction, Pair node to incorporate the multiphysics coupling between the two physics.

#### FLUID FLOW

The fluid in the channel is described by the incompressible Navier-Stokes equations for the velocity field and the pressure in the spatial (deformed) coordinate system. A **Pressure Point Constraint** is used at one of the corner points of the fluid domain, setting the value of the pressure to zero at this point.

#### MULTIBODY DYNAMICS

The Multibody Dynamics interface is used to model the structural assembly. In this analysis, the solid central body is assumed to be a rigid object, while the fins are modeled as flexible bodies. The motion of the mechanism is initiated by a prescribed rotation of the fins about the central body in a time-dependent manner. The rotation is prescribed in such a way that during the initial 0.25 s, the fins rotate toward each other, resulting in the closing of the mechanism. After 0.25 s, their rotation is kept constant at 15°. Figure 7 shows the rotation of the fins as a function of time.

#### MOVING MESH

The geometrical changes in the fluid domain are modeled using an ALE formulation. A deforming-domain condition is assigned to the fluid domain, where the shape of the domain is controlled by the moving boundaries and a smoothing equation in the interior. In the present example, two types of mesh boundary conditions are used to specify the motion of the spatial mesh:

- On all fluid-solid interface boundaries, except at the curved boundaries at the back of the solid body, a **Prescribed Mesh Displacement** boundary condition is used to transfer the motion of the adjoining solid to the moving mesh. As shown in Figure 2, this boundary condition sets the displacement of the mesh boundaries equal to the mapped solid boundaries of the identity pairs.
- At the back side of the solid body as shown in Figure 3, the contact area between solid and fluid boundaries continuously changes because of the rotational motion of the fins. Using a **Prescribed Normal Mesh Displacement** boundary condition at these boundaries, allows the mesh to move freely in the tangential direction and to follow the solid normal motion in the normal direction.

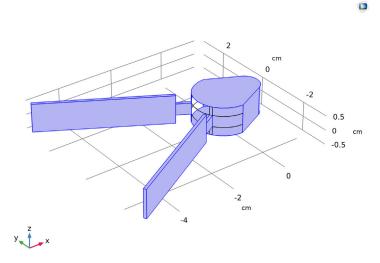


Figure 2: Solid motion (all components) transferred to the moving mesh boundaries.

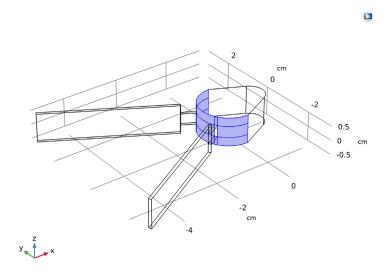


Figure 3: Normal component of solid motion transferred to the moving mesh boundaries. The mesh is free to slide in these boundaries in the tangential direction.

## STUDY

A time dependent study is performed for 1 s to analyze the interaction of the mechanism and the fluid.

## Results and Discussion

The velocity field and pressure distribution in the central xy-plane of the fluid domain are plotted in Figure 4 for six different time steps. Additionally, the variation of the structural displacement and velocity are plotted for each of these time steps. A similar plot for the distribution of the fluid velocity and pressure in the central xz-plane at t = 0.3 s is shown in Figure 5.

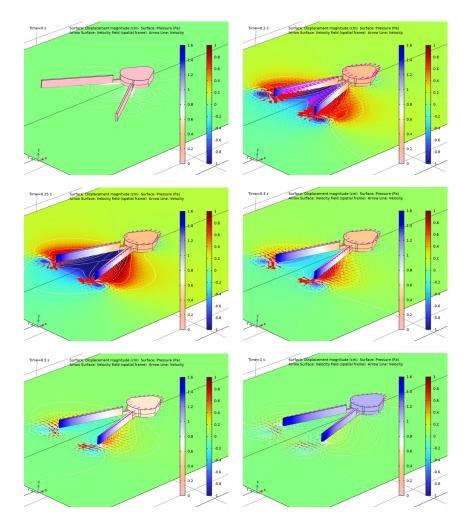


Figure 4: Velocity field (arrow) and pressure (surface) in the fluid in the xy-plane together with displacement (surface) and velocity (arrow) in the mechanism at different time steps.

The time-dependent rotational motion of the fins are shown in Figure 7. Initially, when the fins start to rotate and approach each other, they force the surrounding fluid either to compress or expand. After t = 0.25 s, the rotation of the fins are kept at a constant angle of 15°. The transmission of velocity from the structure to the fluid results in a net forward motion of the structure as shown in Figure 7.

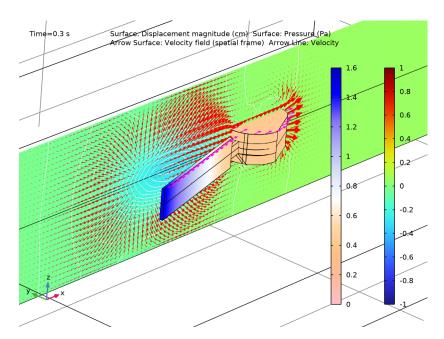


Figure 5: Velocity field (arrow) and pressure (surface) in the fluid in the xz-plane together with displacement (surface) and velocity (arrow) in the mechanism at t = 0.3 s.

Figure 6 shows the finite-element mesh in the mechanism and the lower half of the fluid domain at the initial and final time steps. Because of the forward motion of the structure in the x direction, you can observe a stretching of the elements in this direction in the deformed mesh plot. If the displacements were even larger, remeshing would have to be considered.

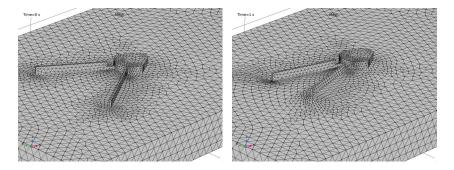


Figure 6: Mesh at t = 0 and 1 s.

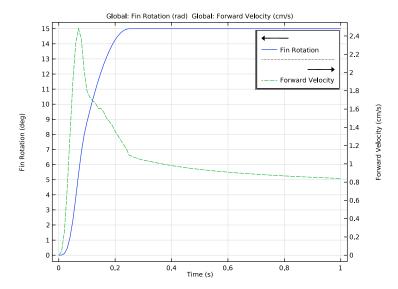


Figure 7: Fin rotation and forward velocity of the mechanism as functions of time.

# Notes About the COMSOL Implementation

- The Fluid-Structure Interaction, Pair node operates on the geometry in the assembly state. Pairs between different geometry parts can then be automatically generated.
- All the pairs in the geometry appear in the **Pair Selection** section of the **Fluid-Structure** Interaction, Pair node. Select only those pairs which couple the fluid and solid physics interfaces.
- In order to transfer the deformation of the solid to the moving mesh, the built-in variables (fsip1.u\_solid, fsip1.v\_solid, and fsip1.w\_solid) are available. These variables are equal to the solid displacement.

Application Library path: Multibody\_Dynamics\_Module/Tutorials/ mechanism\_submerged\_in\_fluid

## Modeling Instructions

From the File menu, choose New.

#### NEW

In the New window, click Model Wizard.

#### MODEL WIZARD

- I In the Model Wizard window, click **1** 3D.
- 2 In the Select Physics tree, select Fluid Flow>Fluid-Structure Interaction>Fluid-Multibody Interaction, Assembly.
- 3 Click Add.
- 4 Click Study.
- 5 In the Select Study tree, select General Studies>Time Dependent.
- 6 Click **Done**.

#### **GLOBAL DEFINITIONS**

#### Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
th_max	15[deg]	0.2618 rad	Maximum fin rotation

#### **GEOMETRY I**

- I In the Model Builder window, under Component I (compl) click Geometry I.
- 2 In the Settings window for Geometry, locate the Units section.
- 3 From the Length unit list, choose cm.

## Import I (impl)

You can import the geometry of the mechanism by browsing to the model's Application Libraries folder.

- I In the Home toolbar, click Import.
- 2 In the Settings window for Import, locate the Import section.
- 3 Click **Browse**.
- 4 Browse to the model's Application Libraries folder and double-click the file mechanism submerged in fluid.mphbin.
- 5 Click Import.

Copy I (copy I)

- I In the Geometry toolbar, click Transforms and choose Copy.
- 2 Click in the **Graphics** window and then press Ctrl+A to select both objects.
- 3 In the Settings window for Copy, click P Build Selected.

Block I (blk I)

- I In the Geometry toolbar, click Block.
- 2 In the Settings window for Block, locate the Size and Shape section.
- 3 In the Width text field, type 25.
- 4 In the **Depth** text field, type 15.
- 5 In the Height text field, type 5.
- 6 Locate the Position section. From the Base list, choose Center.
- 7 Click **Build Selected**.

Work Plane I (wpl)

- I In the Geometry toolbar, click Swork Plane.
- 2 In the Settings window for Work Plane, click 📳 Build Selected.

Work Plane 2 (wp2)

- I Right-click Work Plane I (wpI) and choose Duplicate.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane list, choose xz-plane.
- 4 Click | Build Selected.

Partition Domains I (pard I)

- I In the Geometry toolbar, click Booleans and Partitions and choose Partition Domains.
- 2 On the object blk1, select Domain 1 only.
- 3 In the Settings window for Partition Domains, locate the Partition Domains section.
- 4 From the Work plane list, choose Work Plane I (wpl).
- 5 Click **Build Selected**.

Partition Domains 2 (pard2)

- I Right-click Partition Domains I (pard I) and choose Duplicate.
- 2 On the object pard1, select Domains 1 and 2 only.
- 3 In the Settings window for Partition Domains, locate the Partition Domains section.

- 4 From the Work plane list, choose Work Plane 2 (wp2).
- 5 Click | Build Selected.

Difference I (dif1)

- I In the Geometry toolbar, click Booleans and Partitions and choose Difference.
- 2 Select the object pard2 only.
- 3 In the Settings window for Difference, locate the Difference section.
- 4 Find the **Objects to subtract** subsection. Click to select the **Description** Activate Selection toggle button.
- 5 Select the objects copyl(1) and copyl(2) only.
- 6 Click **Parity** Build Selected.

Form Union (fin)

- I In the Model Builder window, under Component I (compl)>Geometry I click Form Union (fin).
- 2 In the Settings window for Form Union/Assembly, locate the Form Union/Assembly section.
- 3 From the Action list, choose Form an assembly.
- 4 Click **Build Selected**.

For better visualization, you can hide the top part of the fluid domain and view the mechanism using wireframe rendering.

- 5 In the Model Builder window, click Geometry 1.
- 6 Click the 🗬 Click and Hide button in the Graphics toolbar.
- 7 In the **Graphics** window toolbar, click ▼ next to **Select Objects**, then choose Select Domains.
- 8 On the object fin, select Domains 2 and 4 only.
- 9 Click the Wireframe Rendering button in the Graphics toolbar.

#### DEFINITIONS

Step I (step I)

- I In the Home toolbar, click f(x) Functions and choose Global>Step.
- 2 In the Settings window for Step, click to expand the Smoothing section.
- 3 Locate the Parameters section. In the Location text field, type 0.05[s].

Analytic I (an I)

I In the Home toolbar, click f(x) Functions and choose Global>Analytic.

- 2 In the Settings window for Analytic, locate the Definition section.
- 3 In the Expression text field, type th max\*(sin(2\*pi\*1\*t)\*(t<0.25)\*step1(t)+(t> =0.25)).
- 4 In the Arguments text field, type t.
- **5** Locate the **Units** section. In the table, enter the following settings:

Argument	Unit
t	S

6 In the Function text field, type rad.

#### Variables 1

- I In the Model Builder window, right-click Definitions and choose Variables.
- 2 In the Settings window for Variables, locate the Variables section.
- **3** In the table, enter the following settings:

Name	Expression	Unit	Description
th	an1(t)	rad	Fin rotation
un_solid	<pre>fsip1.u_solid*(nX)+ fsip1.v_solid*(nY)+ fsip1.w_solid*(nZ)</pre>	m	Normal mesh displacement, sliding boundary

## Identity Boundary Pair I (ap I)

You can group the interface boundaries by creating selections from the source and destination boundaries of the identity pairs. To identify the boundaries of each domain of the assembly, you can hide one of the domains and use selection highlights to see the boundaries of the unhidden domain.

- I In the Model Builder window, click Identity Boundary Pair I (apl).
- 2 In the Settings window for Pair, locate the Source Boundaries section.
- 3 Click **Create Selection**.
- 4 In the Create Selection dialog box, type Fluid Boundaries (Fins) in the Selection name text field.
- 5 Click OK.
- 6 In the Settings window for Pair, locate the Destination Boundaries section.
- 7 Click **Create Selection**.
- 8 In the Create Selection dialog box, type Solid Boundaries (Fins) in the Selection name text field.

- 9 Click OK.
- 10 In the Settings window for Pair, locate the Frame section.
- II From the Source frame list, choose Material (X, Y, Z).
- 12 From the Destination frame list, choose Material (X, Y, Z).

Identity Boundary Pair 2 (ap2)

- I In the Model Builder window, click Identity Boundary Pair 2 (ap2).
- 2 In the Settings window for Pair, locate the Source Boundaries section.
- 3 Click **Create Selection**.
- 4 In the Create Selection dialog box, type Fluid Boundaries (Body) in the Selection name text field.
- 5 Click OK.
- 6 In the Settings window for Pair, locate the Destination Boundaries section.
- 7 Click **\( \)** Create Selection.
- 8 In the Create Selection dialog box, type Solid Boundaries (Body) in the Selection name text field.
- 9 Click OK.
- 10 In the Settings window for Pair, locate the Frame section.
- II From the Source frame list, choose Material (X, Y, Z).
- 12 From the Destination frame list, choose Material (X, Y, Z).

All Fluid Boundaries

- I In the **Definitions** toolbar, click **Union**.
- 2 In the Settings window for Union, type All Fluid Boundaries in the Label text field.
- 3 Locate the Geometric Entity Level section. From the Level list, choose Boundary.
- **4** Locate the **Input Entities** section. Under **Selections to add**, click + **Add**.
- 5 In the Add dialog box, in the Selections to add list, choose Fluid Boundaries (Fins) and Fluid Boundaries (Body).
- 6 Click OK.

Sliding Mesh Boundaries

- I In the Model Builder window, right-click Fluid Boundaries (Fins) and choose Duplicate.
- 2 In the Settings window for Explicit, type Sliding Mesh Boundaries in the Label text field.
- 3 Locate the Input Entities section. Click Clear Selection.

**4** Select Boundaries 49, 50, 53–58, and 61–72 only.

Modify the domain selections and apply boundary conditions to the Laminar Flow and **Multibody Dynamics** physics interfaces.

## LAMINAR FLOW (SPF)

- I In the Model Builder window, under Component I (compl) click Laminar Flow (spf).
- 2 In the Settings window for Laminar Flow, locate the Domain Selection section.
- 3 In the list, choose 5, 6, and 7.
- 4 Click Remove from Selection.
- **5** Select Domains 1–4 only.

#### Wall I

- I In the Model Builder window, under Component I (compl)>Laminar Flow (spf) click Wall I.
- 2 In the Settings window for Wall, locate the Boundary Condition section.
- 3 From the Wall condition list, choose Slip.

## Pressure Point Constraint I

- I In the Physics toolbar, click Points and choose Pressure Point Constraint.
- 2 Select Point 1 only.

## MULTIBODY DYNAMICS (MBD)

- I In the Model Builder window, under Component I (compl) click Multibody Dynamics (mbd).
- **2** Select Domains 5–7 only.

## Rigid Material: Body

- I In the Physics toolbar, click **Domains** and choose Rigid Material.
- 2 In the Settings window for Rigid Material, type Rigid Material: Body in the Label text field.
- **3** Select Domain 7 only.

## Attachment: Fin 1

- I In the Physics toolbar, click **Boundaries** and choose **Attachment**.
- 2 In the Settings window for Attachment, type Attachment: Fin 1 in the Label text field.
- **3** Select Boundary 107 only.

## Attachment: Fin 2

- I Right-click Attachment: Fin I and choose Duplicate.
- 2 In the Settings window for Attachment, type Attachment: Fin 2 in the Label text field.
- 3 Locate the Boundary Selection section. Click Clear Selection.
- 4 Select Boundary 108 only.

## Hinge Joint 1

- I In the Physics toolbar, click A Global and choose Hinge Joint.
- 2 In the Settings window for Hinge Joint, locate the Attachment Selection section.
- 3 From the Source list, choose Rigid Material: Body.
- 4 From the Destination list, choose Attachment: Fin 1.
- 5 Locate the Center of Joint section. From the list, choose User defined.
- **6** Locate the **Axis of Joint** section. Specify the  $\mathbf{e}_0$  vector as

0	x
0	у
1	z

#### Prescribed Motion I

- I In the Physics toolbar, click 🖳 Attributes and choose Prescribed Motion.
- 2 In the Settings window for Prescribed Motion, locate the Prescribed Rotational Motion section.
- **3** In the  $\theta_p$  text field, type -th.

## Hinge Joint 2

- I In the Model Builder window, under Component I (compl)>Multibody Dynamics (mbd) right-click Hinge Joint I and choose Duplicate.
- 2 In the Settings window for Hinge Joint, locate the Attachment Selection section.
- 3 From the Destination list, choose Attachment: Fin 2.

## Prescribed Motion 1

- I In the Model Builder window, expand the Hinge Joint 2 node, then click Prescribed Motion I.
- 2 In the Settings window for Prescribed Motion, locate the Prescribed Rotational Motion section.
- **3** In the  $\theta_p$  text field, type th.

Now you can add the moving mesh to the fluid domain.

#### MOVING MESH

Deforming Domain I

- I In the Model Builder window, under Component I (compl)>Moving Mesh click Deforming Domain 1.
- **2** Select Domains 1–4 only.

## COMPONENT I (COMPI)

Prescribed Mesh Displacement I

- I In the Definitions toolbar, click Moving Mesh and choose Boundaries> Prescribed Mesh Displacement.
- 2 In the Settings window for Prescribed Mesh Displacement, locate the Boundary Selection section.
- 3 From the Selection list, choose All Fluid Boundaries.
- 4 Locate the **Prescribed Mesh Displacement** section. Specify the dx vector as

fsip1.u_solid	Х
fsip1.v_solid	Υ
fsip1.w_solid	Z

Prescribed Normal Mesh Displacement I

- I In the Definitions toolbar, click Moving Mesh and choose Boundaries> Prescribed Normal Mesh Displacement.
- 2 In the Settings window for Prescribed Normal Mesh Displacement, locate the Boundary Selection section.
- 3 From the Selection list, choose Sliding Mesh Boundaries.
- 4 Locate the Prescribed Normal Mesh Displacement section. In the  $\mathbf{d}_n$  text field, type un solid.
- 5 Click to expand the Constraint Settings section. From the Constraint type list, choose Nitsche method.

After assigning physics interfaces to all the domains, add materials to the domains.

## ADD MATERIAL

I In the Home toolbar, click **Add Material** to open the Add Material window.

- 2 Go to the Add Material window.
- 3 In the tree, select Built-in>Water, liquid.
- 4 Click Add to Component in the window toolbar.
- 5 In the tree, select Built-in>Structural steel.
- **6** Click **Add to Component** in the window toolbar.

#### MATERIALS

Water, liquid (mat I)

- I In the Model Builder window, under Component I (compl)>Materials click Water, liquid (mat I).
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- 3 In the list, choose 5, 6, and 7.
- 4 Click Remove from Selection.
- **5** Select Domains 1–4 only.

Structural steel (mat2)

- I In the Model Builder window, click Structural steel (mat2).
- 2 Select Domains 5–7 only.
- 3 In the Home toolbar, click Add Material to close the Add Material window.

## MESH I

- I In the Settings window for Mesh, locate the Physics-Controlled Mesh section.
- 2 From the Element size list, choose Fine.

Size

Right-click Component I (compl)>Mesh I and choose Edit Physics-Induced Sequence.

Size 2

- I In the Settings window for Size, locate the Geometric Entity Selection section.
- 2 From the Selection list, choose Solid Boundaries (Body).
- 3 Locate the Element Size section. From the Predefined list, choose Fine.
- 4 In the Model Builder window, right-click Mesh I and choose Build All.

#### MULTIPHYSICS

You can choose the pairs on which fluid-structure interaction occurs.

Fluid-Structure Interaction, Pair 1 (fsip1)

- I In the Model Builder window, under Component I (compl)>Multiphysics click Fluid-Structure Interaction, Pair I (fsip I).
- 2 In the Settings window for Fluid-Structure Interaction, Pair, locate the Pair Selection section.
- 3 Under Pairs, click + Add.
- 4 In the Add dialog box, in the Pairs list, choose Identity Boundary Pair I (ap I) and Identity Boundary Pair 2 (ap2).
- 5 Click OK.

#### STUDY I

Step 1: Time Dependent

- I In the Model Builder window, under Study I click Step I: Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- 3 In the Output times text field, type range (0,0.01,0.3) range (0.32,0.02,1).
- 4 From the Tolerance list, choose User controlled.
- 5 In the Relative tolerance text field, type 0.005.

Solution I (soll)

- I In the Study toolbar, click Show Default Solver.
- 2 In the Model Builder window, expand the Solution I (soll) node, then click Time-Dependent Solver I.
- 3 In the Settings window for Time-Dependent Solver, click to expand the Time Stepping section.
- 4 From the Steps taken by solver list, choose Intermediate.
- 5 Find the Algebraic variable settings subsection. In the Fraction of initial step for Backward Euler text field, type 0.01.
- 6 In the Model Builder window, expand the Study I>Solver Configurations> Solution I (soll)>Time-Dependent Solver I>Segregated I node, then click Displacement field.
- 7 In the Settings window for Segregated Step, click to expand the Method and Termination section.
- 8 From the Jacobian update list, choose On every iteration.

## Step 1: Time Dependent

- I In the Model Builder window, under Study I right-click Step I: Time Dependent and choose Get Initial Value for Step.
- 2 In the Settings window for Time Dependent, click to expand the Results While Solving section.
- 3 Select the **Plot** check box.
- 4 From the Plot group list, choose Displacement (mbd).
- 5 In the Study toolbar, click **Compute**.

#### RESULTS

## Velocity (spf)

- I In the Settings window for 3D Plot Group, locate the Data section.
- 2 From the Time (s) list, choose 1.
- 3 In the Velocity (spf) toolbar, click Plot.

## Pressure (sbf)

- I In the Model Builder window, click Pressure (spf).
- 2 In the Settings window for 3D Plot Group, locate the Data section.
- 3 From the Time (s) list, choose 1.
- 4 In the Pressure (spf) toolbar, click Plot.

## Velocity (mbd)

- I In the Model Builder window, click Velocity (mbd).
- 2 In the Settings window for 3D Plot Group, locate the Data section.
- 3 From the Time (s) list, choose 1.

#### Arrow Line

- I In the Model Builder window, expand the Velocity (mbd) node, then click Arrow Line.
- 2 In the Settings window for Arrow Line, locate the Coloring and Style section.
- 3 Select the Scale factor check box. In the associated text field, type 35.
- 4 Locate the Arrow Positioning section. From the Placement list, choose Uniform.
- 5 In the Number of arrows text field, type 4000.
- 6 Locate the Coloring and Style section. From the Color list, choose Cyan.
- 7 In the Velocity (mbd) toolbar, click Plot.

Displacement (mbd), Pressure (spf), Velocity (mbd), Velocity (spf)

- I In the Model Builder window, under Results, Ctrl-click to select Velocity (spf), Pressure (spf), Displacement (mbd), and Velocity (mbd).
- 2 Right-click and choose **Group**.

#### Default Plots

In the **Settings** window for **Group**, type Default Plots in the **Label** text field.

For better visualization of the results, you can also set a new view of the assembly.

## Fluid Pressure (xy) & Solid Displacement

Follow the instructions below to plot the fluid velocity and pressure fields in the xy-plane as well as the displacement and velocity of the mechanism. Compare the resulting plot with the one shown in Figure 4.

- I In the Home toolbar, click **Add Plot Group** and choose **3D Plot Group**.
- 2 In the Settings window for 3D Plot Group, type Fluid Pressure (xy) & Solid Displacement in the Label text field.
- 3 Locate the Data section. From the Time (s) list, choose 0.3.
- 4 Locate the Plot Settings section. From the Frame list, choose Spatial (x, y, z).

## Solid Displacement

- I Right-click Fluid Pressure (xy) & Solid Displacement and choose Surface.
- 2 In the Settings window for Surface, type Solid Displacement in the Label text field.
- 3 Click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)>Multibody Dynamics>Displacement>mbd.disp -Displacement magnitude - m.
- 4 Click to expand the Range section. Select the Manual color range check box.
- **5** In the **Maximum** text field, type 1.6.
- 6 Locate the Coloring and Style section. Click Change Color Table.
- 7 In the Color Table dialog box, select Aurora>Twilight in the tree.
- 8 Click OK.

#### Pressure

- I Right-click Solid Displacement and choose Duplicate.
- 2 In the Settings window for Surface, type Pressure in the Label text field.

- **3** Click **Replace Expression** in the upper-right corner of the **Expression** section. From the menu, choose Component I (compl)>Laminar Flow>Velocity and pressure>p - Pressure -Pa.
- 4 Locate the Range section. In the Minimum text field, type -1.
- 5 In the Maximum text field, type 1.
- 6 Locate the Coloring and Style section. Click Change Color Table.
- 7 In the Color Table dialog box, select Rainbow>Rainbow in the tree.
- 8 Click OK.

#### Selection 1

- I Right-click Pressure and choose Selection.
- 2 Select Boundaries 6 and 13 only.

#### Pressure Contour

- I In the Model Builder window, right-click Fluid Pressure (xy) & Solid Displacement and choose **Contour**.
- 2 In the Settings window for Contour, type Pressure Contour in the Label text field.
- 3 Click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)>Laminar Flow>Velocity and pressure>p - Pressure -Pa.
- 4 Click to expand the **Title** section. From the **Title type** list, choose **None**.
- 5 Locate the Coloring and Style section. From the Coloring list, choose Uniform.
- 6 From the Color list, choose White.
- 7 Clear the Color legend check box.

#### Selection 1

- I Right-click Pressure Contour and choose Selection.
- 2 Select Boundaries 6 and 13 only.

## Fluid Velocity

- I In the Model Builder window, right-click Fluid Pressure (xy) & Solid Displacement and choose Arrow Surface.
- 2 In the Settings window for Arrow Surface, type Fluid Velocity in the Label text field.
- 3 Locate the Coloring and Style section.
- 4 Select the Scale factor check box. In the associated text field, type 20.
- 5 Locate the Arrow Positioning section. In the Number of arrows text field, type 4000.

#### Selection 1

- I Right-click Fluid Velocity and choose Selection.
- 2 Select Boundaries 6 and 13 only.

## Solid Velocity

- I In the Model Builder window, right-click Fluid Pressure (xy) & Solid Displacement and choose Arrow Line.
- 2 In the Settings window for Arrow Line, type Solid Velocity in the Label text field.
- 3 Click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)>Multibody Dynamics>Acceleration and velocity> mbd.u\_tX,mbd.u\_tY,mbd.u\_tZ - Velocity.
- 4 Locate the Coloring and Style section.
- **5** Select the **Scale factor** check box. In the associated text field, type **35**.
- 6 Locate the Arrow Positioning section. In the Number of arrows text field, type 50.
- 7 Locate the Coloring and Style section. From the Color list, choose Magenta.

#### Selection 1

- I Right-click Solid Velocity and choose Selection.
- **2** Select Edges 185, 188, 228, 249, 256, 261, 266, and 269 only.
- 3 In the Fluid Pressure (xy) & Solid Displacement toolbar, click Plot.

## Fluid Pressure (xz) & Solid Displacement

Follow the instructions below to plot the fluid velocity and pressure fields in the xz-plane as well as the displacement and velocity of the mechanism. Compare the resulting plot with the one shown in Figure 5.

- I Right-click Selection I and choose Duplicate.
- 2 In the Settings window for 3D Plot Group, type Fluid Pressure (xz) & Solid Displacement in the Label text field.
- 3 In the Model Builder window, expand the Fluid Pressure (xz) & Solid Displacement node.

#### Selection 1

- I In the Model Builder window, expand the Results> Fluid Pressure (xz) & Solid Displacement>Pressure node, then click Selection 1.
- 2 In the Settings window for Selection, locate the Selection section.
- 3 Click Clear Selection.
- 4 Click Paste Selection.

- 5 In the Paste Selection dialog box, type 9 12 in the Selection text field.
- 6 Click OK.

#### Selection 1

- I In the Model Builder window, expand the Results> Fluid Pressure (xz) & Solid Displacement>Pressure Contour node, then click Selection I.
- 2 In the Settings window for Selection, locate the Selection section.
- 3 Click Clear Selection.
- 4 Click Paste Selection.
- 5 In the Paste Selection dialog box, type 9 12 in the Selection text field.
- 6 Click OK.

## Fluid Velocity

- In the Model Builder window, under Results>Fluid Pressure (xz) & Solid Displacement click Fluid Velocity.
- 2 In the Settings window for Arrow Surface, locate the Coloring and Style section.
- 3 In the Scale factor text field, type 100.

#### Selection I

- I In the Model Builder window, expand the Fluid Velocity node, then click Selection I.
- 2 In the Settings window for Selection, locate the Selection section.
- 3 Click Clear Selection.
- 4 Click Paste Selection.
- 5 In the Paste Selection dialog box, type 9 12 in the Selection text field.
- 6 Click OK.
- 7 In the Fluid Pressure (xz) & Solid Displacement toolbar, click Plot.

Follow the instructions below to plot the deformed mesh. The resulting plot should match the one shown in Figure 6.

## Deformed Mesh

- I In the Home toolbar, click Add Plot Group and choose 3D Plot Group.
- 2 In the Settings window for 3D Plot Group, type Deformed Mesh in the Label text field.
- 3 Locate the Plot Settings section. From the Frame list, choose Spatial (x, y, z).

## Mesh I

I Right-click **Deformed Mesh** and choose **Mesh**.

- 2 In the Settings window for Mesh, locate the Level section.
- **3** From the **Level** list, choose **Volume**.
- 4 Locate the Coloring and Style section. From the Element color list, choose Gray.
- 5 In the **Deformed Mesh** toolbar, click **Plot**.

Follow the instructions below to plot the fin rotations and forward velocity of the structure. The resulting plot should match the one shown in Figure 7.

## ID Plot Group 8

In the Home toolbar, click Add Plot Group and choose ID Plot Group.

#### Fin Rotation

- I Right-click ID Plot Group 8 and choose Global.
- 2 In the Settings window for Global, type Fin Rotation in the Label text field.
- 3 Locate the y-Axis Data section. In the table, enter the following settings:

Expression	Unit	Description
th*180/pi	rad	Fin Rotation

#### Fin Rotation I

Right-click Fin Rotation and choose Duplicate.

#### Forward velocity

- I In the Model Builder window, expand the Results>ID Plot Group 8>Fin Rotation node, then click Results>ID Plot Group 8>Fin Rotation I.
- 2 In the Settings window for Global, type Forward velocity in the Label text field.
- 3 Locate the y-Axis Data section. In the table, enter the following settings:

Expression	Unit	Description
mbd.rd1.u_tx	cm/s	Forward Velocity

4 Click to expand the Coloring and Style section. Find the Line style subsection. From the Line list, choose Dashed.

## Fin Rotation & Velocity

- I In the Model Builder window, under Results click ID Plot Group 8.
- 2 In the Settings window for ID Plot Group, type Fin Rotation & Velocity in the Label text field.
- 3 Locate the Plot Settings section.
- 4 Select the y-axis label check box. In the associated text field, type Fin Rotation (deg).

- 5 Select the Two y-axes check box.
- 6 In the table, select the Plot on secondary y-axis check box for Forward velocity.

Fluid Pressure (xy) & Solid Displacement

- I In the Results toolbar, click ..... Animation and choose Player.
- 2 In the Settings window for Animation, type Fluid Pressure (xy) & Solid Displacement in the Label text field.
- 3 Locate the Scene section. From the Subject list, choose Fluid Pressure (xy) & Solid Displacement.
- 4 Click the Play button in the Graphics toolbar.

Fluid Pressure (xz) & Solid Displacement

- I Right-click Fluid Pressure (xy) & Solid Displacement and choose Duplicate.
- 2 In the Settings window for Animation, type Fluid Pressure (xz) & Solid Displacement in the Label text field.
- 3 Locate the Scene section. From the Subject list, choose Fluid Pressure (xz) & Solid Displacement.
- **4** Click the **Play** button in the **Graphics** toolbar.

## Deformed Mesh

- I Right-click Fluid Pressure (xz) & Solid Displacement and choose Duplicate.
- 2 In the Settings window for Animation, type Deformed Mesh in the Label text field.
- 3 Locate the Scene section. From the Subject list, choose Deformed Mesh.
- **4** Click the **Play** button in the **Graphics** toolbar.