

# Axial Magnetic Bearing Using Permanent Magnets

# Introduction

Permanent magnet bearings are used in turbomachinery, pumps, motors, generators, and flywheel energy storage systems, to mention a few application areas. Contactless operation, low maintenance, and the ability to operate without lubrication are some key benefits compared to conventional mechanical bearings. This example illustrates how to calculate design parameters like magnetic forces and stiffness for an axial permanent magnet bearing.

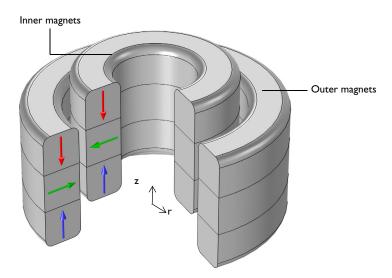


Figure 1: Model illustration of an axial magnetic bearing using permanent magnets. The black arrows show the magnetization direction of the permanent magnets.

# Model Definition

Set up the problem in a 2D axisymmetric modeling space. Figure 1 shows a 3D view of the model with the magnetization directions of the magnets indicated. COMSOL Multiphysics calculates the total magnetic force on an object by integrating the vector expression

$$\mathbf{f} = \mathbf{n} \cdot T = -\frac{1}{2}\mathbf{n}(\mathbf{H} \cdot \mathbf{B}) + (\mathbf{n} \cdot \mathbf{H})\mathbf{B}^{\mathrm{T}}$$

where  $\mathbf{n}$  is the outward normal vector and T is the Maxwell stress tensor, over the object's outer boundaries.

The negative of the derivative of the total magnetic force with respect to the position is referred to as the magnetic stiffness. By this definition, the axial magnetic stiffness of the bearing is

$$k_z = -\frac{dF_z}{dz} \tag{1}$$

where  $F_z$  is the total axial magnetic force on the bearing. This model calculates the magnetic stiffness in the axial direction only; calculating the magnetic stiffness in the radial direction as well as the coupled stiffness coefficients requires a complete 3D model.

The model parameters are taken from Ref. 1.

## Results

A steady-state study is performed to calculate the magnetic forces and the axial magnetic stiffness coefficient. Figure 2 shows the magnetic flux density norm and the magnetic vector potential for an axial displacement of the inner magnets of z = 40 mm. Figure 3 illustrates the axial component of the magnetic force on the inner magnets as a function of axial displacement. Figure 4 displays the sensitivity of the axial magnetic force with respect to the axial displacement. The negative of this plot is the axial magnetic stiffness coefficient. Finally, Figure 5 shows the magnetic flux density norm in 3D at an axial displacement of 8 mm.

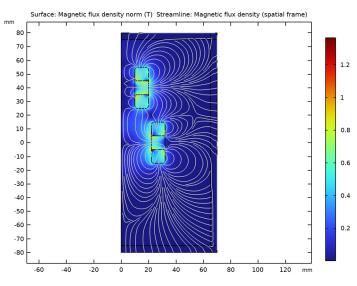


Figure 2: Magnetic flux density norm and magnetic vector potential for an axial displacement of the inner magnets of 40 mm.

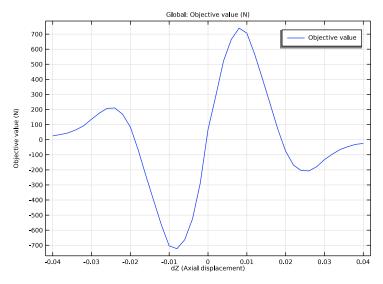


Figure 3: Axial component of the magnetic force versus axial displacement.

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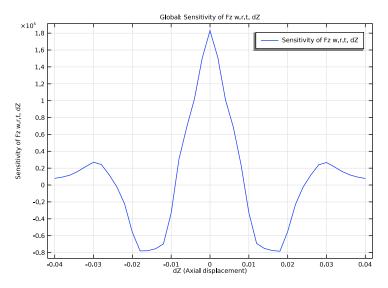


Figure 4: Sensitivity of the axial magnetic force with respect to axial displacement versus axial displacement. The negative of this quantity is the axial magnetic stiffness coefficient.

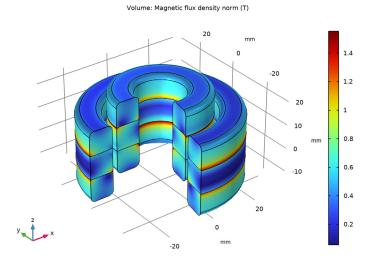


Figure 5: Magnetic flux density norm at an axial displacement of 8 mm.

# Notes About the COMSOL Implementation

In this model, use the Magnetic Fields interface to model the magnetic field. Also, add an Infinite Element Domain to model the open region of free space surrounding the magnets. You can then calculate the total magnetic force components with the Maxwell stress tensor method by adding a Force Calculation node in the inner magnet domains. Also, add Deformed Geometry and Sensitivity interfaces to calculate the axial magnetic stiffness coefficient as defined by Equation 1. With the Deformed Geometry interface you parameterize the axial displacement of the inner magnets. Then, use the axial component of the magnetic force as a global objective and the axial displacement parameter as a global control variable for the Sensitivity interface to obtain the derivative  $dF_z/dz$ . Using a Parametric Sweep study node, you finally compute the axial magnetic stiffness as a function of the axial displacement.

# Reference

1. R. Ravaud and G. Lemarquand, "Halbach Structures for Permanent Magnet Bearings", *Progress In Electromagnetics Research M*, vol. 14, pp. 236–277, 2010.

**Application Library path:** ACDC\_Module/Devices,\_Transducers\_and\_Actuators/ axial\_magnetic\_bearing

# Modeling Instructions

From the File menu, choose New.

#### NEW

In the New window, click 🙆 Model Wizard.

#### MODEL WIZARD

- I In the Model Wizard window, click 🚈 2D Axisymmetric.
- 2 In the Select Physics tree, select AC/DC>Magnetic Fields, No Currents>Magnetic Fields, No Currents (mfnc).
- 3 Click Add.
- 4 Click 🔿 Study.
- 5 In the Select Study tree, select General Studies>Stationary.

# 6 Click M Done.

# GEOMETRY I

Define all the necessary parameters here.

## **GLOBAL DEFINITIONS**

#### Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.

In the table		

Name	Expression	Value	Description
R1	10[mm]	0.01 m	Inner radius of inner magnet
R2	20[mm]	0.02 m	Outer radius of inner magnet
R3	22[mm]	0.022 m	Inner radius of outer magnet
R4	32[mm]	0.032 m	Outer radius of outer magnet
h0	10[mm]	0.01 m	Magnet height
Br	1[T]	ΙT	Remanent flux density of magnet
dZ	O[mm]	0 m	Axial displacement

Later, dZ will be used as a global control variable for a sensitivity analysis and the parameter of a **Parametric Sweep** node in order to compute the axial magnetic stiffness.

# GEOMETRY I

Follow the instructions below to construct the model geometry.

- I In the Model Builder window, under Component I (compl) click Geometry I.
- 2 In the Settings window for Geometry, locate the Units section.
- 3 From the Length unit list, choose mm.

#### Rectangle 1 (r1)

- I In the **Geometry** toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type R2-R1.
- 4 In the **Height** text field, type h0\*3.
- **5** Locate the **Position** section. In the **r** text field, type **R1**.
- 6 In the z text field, type -h0/2-h0+dZ.

## 7 Click 틤 Build Selected.

8 Click to expand the Layers section. In the table, enter the following settings:

Layer name	Thickness (mm)	
Layer 1	h0	

9 Select the Layers on top check box.

10 Click 📄 Build Selected.

Rectangle 2 (r2)

- I Right-click **Rectangle I (rI)** and choose **Duplicate**.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Width** text field, type R4-R3.
- **4** Locate the **Position** section. In the **r** text field, type **R3**.
- **5** In the **z** text field, type -h0/2-h0.
- 6 Click 틤 Build Selected.

Rectangle 3 (r3)

- I In the Geometry toolbar, click 📃 Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Width** text field, type 70.
- 4 In the **Height** text field, type 160.
- **5** Locate the **Position** section. In the **z** text field, type -80.
- 6 Locate the Layers section. In the table, enter the following settings:

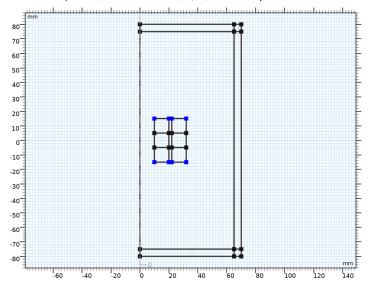
Layer name	Thickness (mm)
Layer 1	5

- 7 Select the Layers to the right check box.
- 8 Select the Layers on top check box.
- 9 Click 📄 Build Selected.

**10** Click the 4 **Zoom Extents** button in the **Graphics** toolbar.

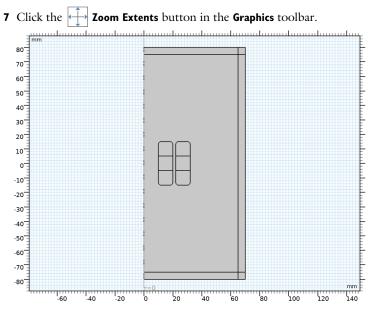
# Fillet I (fill)

- I In the **Geometry** toolbar, click *Fillet*.
- 2 On the object rl, select Points 1, 4, 5, and 8 only.



3 On the object r2, select Points 1, 4, 5, and 8 only.

- 4 In the Settings window for Fillet, locate the Radius section.
- 5 In the Radius text field, type 2.
- 6 Click 🟢 Build All Objects.



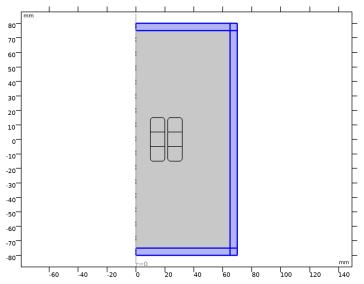
The model geometry should look like the one shown in the figure above. Enclose the inner air domain by an **Infinite Element Domain** to model the surrounding space.

# DEFINITIONS

Infinite Element Domain 1 (ie1)

- I In the Definitions toolbar, click 🙋 Infinite Element Domain.
- **2** Select Domains 1, 3, and 10–12 only.
- 3 In the Settings window for Infinite Element Domain, locate the Geometry section.

4 From the Type list, choose Cylindrical.



# MATERIALS

Use air as the material for all domains and override it in permanent magnets with a material that will be created based on a modification of an existing entry from library.

#### ADD MATERIAL

- I In the Home toolbar, click 🙀 Add Material to open the Add Material window.
- 2 Go to the Add Material window.
- 3 In the tree, select Built-in>Air.
- 4 Click Add to Component in the window toolbar.
- 5 In the tree, select AC/DC>Hard Magnetic Materials> Sintered NdFeB Grades (Chinese Standard)>N50 (Sintered NdFeB).
- 6 Right-click and choose Add to Component I (compl).
- 7 In the Home toolbar, click 🙀 Add Material to close the Add Material window.

## MATERIALS

Generic Magnet

- I Select Domains 4–9 only.
- 2 In the Settings window for Material, locate the Material Contents section.

**3** In the table, enter the following settings:

Property	Variable	Value	Unit	Property group
Recoil permeability	murec_iso ; murecii = murec_iso, murecij = 0	1	I	Remanent flux density
Remanent flux density norm	normBr	Br	Т	Remanent flux density

4 In the Label text field, type Generic Magnet.

Now set up the physics for the magnetic field: use the default **Magnetic Flux Conservation** node with default settings for the air domains and add separate nodes for the magnets (one per magnetization direction).

#### MAGNETIC FIELDS, NO CURRENTS (MFNC)

Magnetic Flux Conservation 2

- In the Model Builder window, under Component I (compl) right-click Magnetic Fields, No Currents (mfnc) and choose Magnetic Flux Conservation.
- **2** Select Domains 6 and 9 only.
- **3** In the **Settings** window for **Magnetic Flux Conservation**, locate the **Constitutive Relation B-H** section.
- 4 From the Magnetization model list, choose Remanent flux density.
- 5 Specify the **e** vector as

0	r
0	phi
- 1	z

Magnetic Flux Conservation 3

- I In the Physics toolbar, click 🔵 Domains and choose Magnetic Flux Conservation.
- **2** Select Domains 4 and 7 only.
- **3** In the **Settings** window for **Magnetic Flux Conservation**, locate the **Constitutive Relation B-H** section.
- 4 From the Magnetization model list, choose Remanent flux density.

5 Specify the **e** vector as

0	r
0	phi
1	z

Magnetic Flux Conservation 4

- I In the Physics toolbar, click 🔵 Domains and choose Magnetic Flux Conservation.
- **2** Select Domain 5 only.
- **3** In the **Settings** window for **Magnetic Flux Conservation**, locate the **Constitutive Relation B-H** section.
- 4 From the Magnetization model list, choose Remanent flux density.

Magnetic Flux Conservation 5

- I In the Physics toolbar, click 🔵 Domains and choose Magnetic Flux Conservation.
- **2** Select Domain 8 only.
- **3** In the **Settings** window for **Magnetic Flux Conservation**, locate the **Constitutive Relation B-H** section.
- **4** From the Magnetization model list, choose Remanent flux density.
- **5** Specify the **e** vector as

- 1	r
0	phi
0	z

# Force Calculation 1

Add a Force Calculation feature to compute the total magnetic force on the inner magnets.

I In the Physics toolbar, click **Domains** and choose Force Calculation.

**2** Select Domains 4–6 only.

Keeping the default force name, 0, the axial force component can be accessed as mfnc.Forcez\_0, where mfnc is the identifier for the Magnetic Fields, No Currents interfaces.

Specify a reference level for the magnetic scalar potential by constraining its value in one point.

## Zero Magnetic Scalar Potential 1

I In the Physics toolbar, click 💭 Points and choose Zero Magnetic Scalar Potential.

**2** Select Point 30 only.

Next, add the **Moving Mesh** and **Sensitivity** interfaces to use for calculating the axial magnetic stiffness coefficient as defined by Equation 1 of the Model Definition section.

## ADD PHYSICS

- I In the Physics toolbar, click 🙀 Add Physics to open the Add Physics window.
- 2 Go to the Add Physics window.
- 3 In the tree, select Mathematics>Optimization and Sensitivity>Sensitivity (sens).
- 4 Click Add to Component I in the window toolbar.
- 5 In the Physics toolbar, click 🙀 Add Physics to close the Add Physics window.

### SENSITIVITY (SENS)

With the **Sensitivity** interface you can compute the right-hand side of Equation 1 as the derivative of the global objective defined as the axial force component mfnc.Forcez\_0 with respect to the global control variable defined as the axial displacement dZ.

Global Control Variables I

- I Right-click Component I (comp1)>Sensitivity (sens) and choose Global Control Variables.
- 2 In the Settings window for Global Control Variables, locate the Control Variables section.
- 3 In the **Control variables** table, enter the following settings:

Variable	Initial value	
dZ	0	

Global Objective I

- I In the Physics toolbar, click 🖗 Global and choose Global Objective.
- 2 In the Settings window for Global Objective, locate the Global Objective section.
- **3** In the *q* text field, type mfnc.Forcez\_0.

# COMPONENT I (COMPI)

Deforming Domain 1

- I In the Definitions toolbar, click Moving Mesh and choose Domains> Deforming Domain.
- **2** Select Domain 2 only.
- 3 In the Settings window for Deforming Domain, locate the Smoothing section.
- 4 From the Mesh smoothing type list, choose Laplace.

## Prescribed Deformation 1

- I In the Definitions toolbar, click Moving Mesh and choose Domains> Prescribed Deformation.
- 2 Click the **Select All** button in the **Graphics** toolbar.
- **3** In the **Settings** window for **Prescribed Deformation**, locate the **Geometric Entity Selection** section.
- 4 Click Clear Selection.
- 5 Click the Select Box button in the Graphics toolbar.
- **6** Select Domains 4–6 only.
- 7 Locate the Prescribed Deformation section. Specify the dx vector as

0	R
dZ	Z

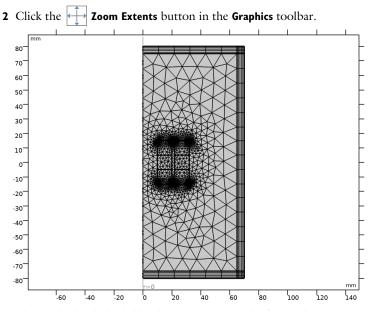
Prescribed Mesh Displacement I

I In the Definitions toolbar, click Moving Mesh and choose Boundaries> Prescribed Mesh Displacement.

2 Select Boundaries 3, 4, 6, 18, 19, 21, 23–27, 30, and 42–45 only.

# MESH I

I In the Model Builder window, under Component I (compl) right-click Mesh I and choose Build All.



The mesh should look like the one shown in the figure above. Notice that the physics controlled meshing automatically produced a mapped mesh in the infinite elements.

# STUDY I

Add a **Parametric Sweep** study step to calculate the axial and radial force components for different axial positions of the inner magnets. Vary the axial displacement from z = -40 mm to z = 40 mm.

#### Parametric Sweep

- I In the Study toolbar, click **Parametric Sweep**.
- 2 In the Settings window for Parametric Sweep, locate the Study Settings section.
- 3 Click + Add.
- 4 From the list in the **Parameter name** column choose **dZ** (Axial displacement), and set the **Parameter unit** to mm.
- 5 Click Range.
- 6 In the Range dialog box, type -40 in the Start text field.
- 7 In the **Step** text field, type 2.
- 8 In the **Stop** text field, type 40.
- 9 Click Replace.
- IO In the Model Builder window, click Study I.

II In the Settings window for Study, locate the Study Settings section.

12 Clear the Generate default plots check box.

## Solution 1 (soll)

- I In the Study toolbar, click The Show Default Solver.
- 2 In the Model Builder window, expand the Solution I (soll) node.
- 3 Right-click Study I>Solver Configurations>Solution I (solI)>Stationary Solver I and choose Sensitivity.
- **4** In the **Study** toolbar, click **= Compute**.

# RESULTS

In the Model Builder window, expand the Results node.

Study 1/Parametric Solutions 1 (sol2) Create datasets for result visualization in specific domains.

Study I/Parametric Solutions I (3) (sol2)

- I In the Model Builder window, expand the Results>Datasets node.
- 2 Right-click Results>Datasets>Study I/Parametric Solutions I (sol2) and choose Duplicate.
- 3 In the Settings window for Solution, locate the Solution section.
- 4 From the Solution list, choose dZ=8 (sol27).

#### Selection

- I In the Results toolbar, click 🖣 Attributes and choose Selection.
- 2 In the Settings window for Selection, locate the Geometric Entity Selection section.
- 3 From the Geometric entity level list, choose Domain.
- **4** Select Domains 4–9 only.

# Revolution 2D I

- I In the **Results** toolbar, click **More Datasets** and choose **Revolution 2D**.
- 2 In the Settings window for Revolution 2D, locate the Data section.
- 3 From the Dataset list, choose Study I/dZ=8 (sol27).
- 4 Click to expand the **Revolution Layers** section. In the **Start angle** text field, type 100.
- 5 In the **Revolution angle** text field, type 280.

Use the following instructions to get the plots shown in Figure 2 to Figure 5.

2D Plot Group I

In the **Results** toolbar, click **2D Plot Group**.

Surface 1

- I Right-click 2D Plot Group I and choose Surface.
- In the Settings window for Surface, click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)>Magnetic Fields, No Currents>Magnetic>mfnc.normB Magnetic flux density norm T.
- 3 In the 2D Plot Group I toolbar, click 💿 Plot.

Streamline 1

- I In the Model Builder window, right-click 2D Plot Group I and choose Streamline.
- 2 In the Settings window for Streamline, locate the Streamline Positioning section.
- 3 From the Positioning list, choose Uniform density.
- 4 In the Separating distance text field, type 0.02.
- 5 Locate the Coloring and Style section. Find the Point style subsection. From the Color list, choose Gray.
- 6 In the 2D Plot Group I toolbar, click 💽 Plot.
- 7 Click the + Zoom Extents button in the Graphics toolbar.

Compare this plot with Figure 2.

#### ID Plot Group 2

In the Home toolbar, click 🚛 Add Plot Group and choose ID Plot Group.

Global I

- I Right-click ID Plot Group 2 and choose Global.
- 2 In the Settings window for Global, locate the Data section.
- 3 From the Dataset list, choose Study I/Parametric Solutions I (sol2).
- 4 Locate the y-Axis Data section. Click **Clear Table**.
- 5 Click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Component I (compl)>Sensitivity>sens.gobjl Objective value N.
- 6 In the ID Plot Group 2 toolbar, click 💿 Plot.

Compare the plot just created with that shown in Figure 3.

ID Plot Group 3

In the Home toolbar, click 🚛 Add Plot Group and choose ID Plot Group.

Global I

- I Right-click ID Plot Group 3 and choose Global.
- 2 In the Settings window for Global, locate the Data section.
- 3 From the Dataset list, choose Study I/Parametric Solutions I (sol2).
- 4 Locate the y-Axis Data section. Click **Clear Table**.
- **5** In the table, enter the following settings:

Expression	Unit	Description
fsens(dZ)	N/m	Sensitivity of Fz w.r.t. dZ

6 In the ID Plot Group 3 toolbar, click 💿 Plot.

Compare this plot with Figure 4.

3D Plot Group 4

Finally, reproduce Figure 5 using the following steps.

In the Home toolbar, click 🚛 Add Plot Group and choose 3D Plot Group.

# Volume 1

- I Right-click **3D Plot Group 4** and choose **Volume**.
- 2 In the Settings window for Volume, click Replace Expression in the upper-right corner of the Expression section. From the menu, choose mfnc.normB Magnetic flux density norm T.
- 3 In the 3D Plot Group 4 toolbar, click 💿 Plot.