

# Hysteresis in Piezoelectric Ceramics

# *Introduction*

Many piezoelectric materials are ferroelectric. Ferroelectric materials exhibit nonlinear polarization behavior such as hysteresis and saturation at large applied electric fields. In addition, the polarization and mechanical deformations in such materials can be strongly coupled due to the electrostriction effect. This model uses Ferroelectroelasticity interface to analyze a simple actuator made of PZT piezoelectric ceramic material, which is subjected to applied electric field and mechanical load.

# *Model Definition*

The direct electrostrictive effect for a material of arbitrary symmetry can be represented as the following additive contribution to the strain:

$$
\varepsilon_{em} = Q : (\mathbf{P} \otimes \mathbf{P})
$$

which is quadratic in polarization **P**. Due to the symmetry, the fourth order tensor Q can be effectively represented by a 6-by-6 coupling matrix. For piezoelectric ceramics, the matrix can be characterized by three independent components: *Q*11, *Q*12, and *Q*44.

For ferroelectroelastic materials, the polarization vector is nonlinear function of the electric field and possible mechanical stress in the material. The Jiles–Atherton model is available in COMSOL Multiphysics for modeling ferroelectric hysteresis. It assumes that the total polarization can be represented as a sum of reversible and irreversible parts. The polarization change is computed from the following incremental equation:

$$
d\mathbf{P} = \mathbf{c}_{\mathrm{r}} d\mathbf{P}_{\mathrm{an}} + (\mathbf{I} - \mathbf{c}_{\mathrm{r}}) d\mathbf{P}_{\mathrm{irr}}
$$

where the reversibility is characterized by the parameter  $c_r$ , and the anhysteretic polarization is found from a relation:

$$
\mathbf{P}_{an} = P_{s}L(|\mathbf{E}_{eff}|)\frac{\mathbf{E}_{eff}}{|\mathbf{E}_{eff}|}
$$

where  $P_s$  is the saturation polarization. The polarization shape is characterized by the Langevin function

$$
L = \coth\left(\frac{E_{\text{eff}}}{a}\right) - \frac{a}{|E_{\text{eff}}|}
$$

where  $\alpha$  is a material parameter called the domain wall density.

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<span id="page-2-0"></span>The effective electric field is given by

$$
\mathbf{E}_{\rm eff} = \mathbf{E} + \alpha \mathbf{P} + 2(\sigma_{\rm m} : \mathbf{Q})\mathbf{P}
$$
 (1)

where **E** is the applied electric field,  $\alpha$  is a material parameter called the inter-domain coupling, and the mechanics stress is computed assuming mechanically linear material as

$$
\sigma_m = C : (\epsilon - \epsilon_{em})
$$

where C is the fourth order elasticity tensor. The last term in [Equation 1](#page-2-0) represents the inverse electrostrictive effect.

Finally, the change of the irreversible polarization is computed from the following incremental relation:

$$
d\mathbf{P}_{irr} = \max(\zeta \cdot d\mathbf{E}_{eff0}) \frac{\zeta}{|\zeta|}
$$

$$
\zeta = k_{\rm p}^{-1} (\mathbf{P}_{\rm an} - \mathbf{P}_{irr})
$$

where the pinning loss is characterized by the parameter  $k_p$ .

The ferroelectroelastic actuator in this model example is a rectangular plate with dimensions of 1.5 in-by-0.25 in-by-0.015 in, which is composed of PZT-5H piezoelectric ceramic material. The following polarization parameter values have been estimated in [Ref. 1](#page-8-0) based on experimental data:

<b>MATERIAL PROPERTY</b>	<b>VALUE</b>	<b>DESCRIPTION</b>
$P_{\rm s}$	$0.425 \text{ C/m}^2$	Saturation polarization
$\alpha$	6.410 <sup>5</sup> V/m	Domain wall density
$\alpha$	$4.2 \cdot 10^6$ m/F	Inter-domain coupling
$c_{\rm r}$	0.2	Polarization reversibility
	$1.10^6$ V/m	Pinning loss

TABLE 1: MATERIAL PROPERTIES OF PZT-5H.

The mechanical properties for PZT-5H are available in the Material Library of COMSOL.

The coupling coefficients for PZT ceramics can vary with the material composition and temperature. The reference values used in this example are give in the table below ([Ref. 2](#page-8-1)):

<b>MATERIAL PROPERTY</b>	<b>VALUE</b>	
Q/11	$3.579 \cdot 10^{-2}$ m <sup>4</sup> /C <sup>2</sup>	
$Q_{12}$	$-5.33510^{-3}$ m <sup>4</sup> /C <sup>2</sup>	
	$1.923 \cdot 10^{-2}$ m <sup>4</sup> /C <sup>2</sup>	

TABLE 2: ELECTROSTRICTIVE COUPLING COEFFICIENTS.

The upper surface of the actuator is grounded, while the lower one is subjected to an electric potential that can cyclically vary in small increments between  $-V_{\text{max}}$  and  $+V_{\text{max}}$ .

The actuator can be subjected to a compressive stress by applying boundary loads of various magnitude.

Because of the symmetry, it is sufficient to model one quarter of the actual geometry.



*Figure 1: Model geometry.*

Because of the large aspect ratio of the actuator and the unidirectional nature of the electrical and mechanical loading, a course mesh can be used for the discretization.





*Results and Discussion*

Three full cycles have been computed for each value of V<sub>max</sub>. The variation of polarization and electrostrictive strain is studied at the point in the middle of the actuator. The first cycle includes the initial transient, [Figure 3](#page-5-0) and [Figure 4](#page-5-1). The hysteresis loops become fully established after two full cycles, [Figure 5](#page-6-0) and [Figure 6](#page-6-1).

Finally, [Figure 7](#page-7-0) and [Figure 8](#page-7-1) show the effect of the applied compressive stress.



<span id="page-5-0"></span>*Figure 3: Polarization hysteresis loop including the initial transient for the maximum applied voltage of 600 V.* 



<span id="page-5-1"></span>*Figure 4: Electrostrictive strain hysteresis loop including the initial transient for the maximum applied voltage of 600 V.*



<span id="page-6-0"></span>*Figure 5: Polarization hysteresis loops fully established after two initial cycles for different values of the maximum applied voltage.*



<span id="page-6-1"></span>*Figure 6: Electrostrictive strain hysteresis loops fully established after two initial cycles for different values of the maximum applied voltage.*



<span id="page-7-0"></span>*Figure 7: Fully established polarization hysteresis loops for different values of the mechanical load and maximum applied voltage of 1200 V.*



<span id="page-7-1"></span>*Figure 8: Fully established strain hysteresis loops for different values of the mechanical load and maximum applied voltage of 1200 V.*

In this example, you study the hysteresis with respect to the incremental variation of the applied electric potential using a stationary parametric study. The same hysteresis model can be also used for time dependent studies.

# *References*

<span id="page-8-0"></span>1. R.C. Smith and Z. Ounaies. "A Domain Wall Model for Hysteresis in Piezoelectric Materials," *J. Int. Mat. Sys. Struct.*, vol. 11, no. 1, pp. 62–79, 2000.

<span id="page-8-1"></span>2. B. Völker, P. Marton, C. Elsässer, and M. Kamlah, "Multiscale modeling for ferroelectric materials: a transition from the atomic level to phase-field modeling," *Continuum Mech. Thermodyn.*, vol. 23, pp. 435–451, 2011.

**Application Library path:** MEMS\_Module/Piezoelectric\_Devices/ piezoelectric\_hysteresis

# *Modeling Instructions*

From the **File** menu, choose **New**.

### **NEW**

In the **New** window, click  $\bigotimes$  **Model Wizard**.

# **MODEL WIZARD**

- **1** In the **Model Wizard** window, click **3D**.
- **2** In the **Select Physics** tree, select **Structural Mechanics>Electromagnetics-Structure Interaction>Ferroelectroelasticity**.
- **3** Click **Add**.
- **4** Click  $\ominus$  Study.
- **5** In the **Select Study** tree, select **General Studies>Stationary**.
- **6** Click **Done**.

# **GLOBAL DEFINITIONS**

# *Parameters 1*

Define parameters for the geometry, material properties, and applied voltage and mechanical load.

- **1** In the **Model Builder** window, under **Global Definitions** click **Parameters 1**.
- **2** In the **Settings** window for **Parameters**, locate the **Parameters** section.
- **3** In the table, enter the following settings:



# **DEFINITIONS**

*Variables 1*

- **1** In the **Model Builder** window, under **Component 1 (comp1)** right-click **Definitions** and choose **Variables**.
- **2** In the **Settings** window for **Variables**, locate the **Variables** section.

**3** In the table, enter the following settings:



This variation of the potential with respect to the parameter at one of the actuator boundaries will cause the electric field within the material to gradually change between -Vmax and Vmax.

#### **GEOMETRY 1**

## *Block 1 (blk1)*

**1** In the **Geometry** toolbar, click **Block**.

Because of the symmetry, it is sufficient to model one quarter of the actuator.

- **2** In the **Settings** window for **Block**, locate the **Size and Shape** section.
- **3** In the **Width** text field, type W/2.
- **4** In the **Depth** text field, type D/2.
- **5** In the **Height** text field, type H/2.
- **6** Click **Build All Objects**.

### **SOLID MECHANICS (SOLID)**

*Linear Elastic Material 1*

You will prescribe the material stiffness using the data available in the material library for PZT-5H, which is represented by the whole elasticity matrix.

- **1** In the **Model Builder** window, under **Component 1 (comp1)>Solid Mechanics (solid)** click **Linear Elastic Material 1**.
- **2** In the **Settings** window for **Linear Elastic Material**, locate the **Linear Elastic Material** section.
- **3** From the **Solid model** list, choose **Anisotropic**.
- **4** From the **Material data ordering** list, choose **Voigt (11, 22, 33, 23, 13, 12)**.

### **ELECTROSTATICS (ES)**

*Charge Conservation, Ferroelectric 1*

**1** In the **Model Builder** window, under **Component 1 (comp1)>Electrostatics (es)** click **Charge Conservation, Ferroelectric 1**.

- **2** In the **Settings** window for **Charge Conservation, Ferroelectric**, locate the **Ferroelectric Material Properties** section.
- **3** Select the **Hysteresis Jiles-Atherton model** check box.

## **MATERIALS**

In the **Home** toolbar, click **Windows** and choose **Add Material from Library**.

## **ADD MATERIAL**

- **1** Go to the **Add Material** window.
- **2** In the tree, select **Built-in>Lead Zirconate Titanate (PZT-5H)**.
- **3** Click **Add to Component 1 (comp1)**.

# **MATERIALS**

## *Lead Zirconate Titanate (PZT-5H) (mat1)*

Define the remaining ferroelectric properties for the material using the parameters.

- **1** In the **Model Builder** window, under **Component 1 (comp1)>Materials** click **Lead Zirconate Titanate (PZT-5H) (mat1)**.
- **2** In the **Settings** window for **Material**, locate the **Material Contents** section.
- **3** In the table, enter the following settings:



### **SOLID MECHANICS (SOLID)**

In the **Model Builder** window, under **Component 1 (comp1)** click **Solid Mechanics (solid)**.

#### *Symmetry 1*

- **1** In the **Physics** toolbar, click **Boundaries** and choose **Symmetry**.
- **2** Select Boundaries 1–3 only.

#### *Boundary Load 1*

- **1** In the **Physics** toolbar, click **Boundaries** and choose **Boundary Load**.
- **2** Select Boundary 4 only.
- **3** In the **Settings** window for **Boundary Load**, locate the **Force** section.
- **4** Specify the  $\mathbf{F}_A$  vector as



#### **ELECTROSTATICS (ES)**

In the **Model Builder** window, under **Component 1 (comp1)** click **Electrostatics (es)**.

#### *Ground 1*

- **1** In the **Physics** toolbar, click **Boundaries** and choose **Ground**.
- **2** Select Boundary 4 only.

## *Electric Potential 1*

- **1** In the **Physics** toolbar, click **Boundaries** and choose **Electric Potential**.
- **2** Select Boundary 3 only.

Because of the symmetry, the voltage at the horizontal symmetry plane equals to a half of that applied at the bottom surface.

- **3** In the **Settings** window for **Electric Potential**, locate the **Electric Potential** section.
- **4** In the  $V_0$  text field, type V0/2.

# **MULTIPHYSICS**

## *Electrostriction 1 (efe1)*

You study the electrostriction in the material using a fully coupled model.

**1** In the **Model Builder** window, under **Component 1 (comp1)>Multiphysics** click **Electrostriction 1 (efe1)**.

- **2** In the **Settings** window for **Electrostriction**, locate the **Coupling Type** section.
- **3** From the list, choose **Fully coupled**.

Because of certain symmetry in the material microstructure, you need three parameters to characterize the electrostrictive coupling.

- **4** Locate the **Electrostriction** section. From the **Solid model** list, choose **Cubic crystal**.
- **5** In the  $Q_{11}$  text field, type 0.11.
- **6** In the  $Q_{12}$  text field, type Q12.
- **7** In the  $Q_{44}$  text field, type 044.

# **MESH 1**

*Mapped 1*

- **1** In the **Mesh** toolbar, click **Boundary** and choose **Mapped**.
- **2** Select Boundary 4 only.

## *Size*

- **1** In the **Model Builder** window, click **Size**.
- **2** In the **Settings** window for **Size**, locate the **Element Size** section.
- **3** From the **Predefined** list, choose **Coarse**.

## *Swept 1*

In the **Mesh** toolbar, click **Swept**.

#### *Distribution 1*

- **1** Right-click **Swept 1** and choose **Distribution**.
- **2** In the **Settings** window for **Distribution**, locate the **Distribution** section.
- **3** In the **Number of elements** text field, type 2.
- **4** Click **Build All.**

## **STUDY 1**

#### *Step 1: Stationary*

In the first study, no mechanical load is assumed, so that the entire excitation is via the applied electric field.

- **1** In the **Model Builder** window, under **Study 1** click **Step 1: Stationary**.
- **2** In the **Settings** window for **Stationary**, click to expand the **Study Extensions** section.
- **3** Select the **Auxiliary sweep** check box.

## **4** Click  $+$  **Add**.

You compute three full cycles for the applied electric potential for each given maximum value.

**5** In the table, enter the following settings:



*Parametric Sweep*

- **1** In the **Study** toolbar, click  $\frac{12}{2}$  **Parametric Sweep**.
- **2** In the **Settings** window for **Parametric Sweep**, locate the **Study Settings** section.
- **3** Click  $+$  **Add**.
- **4** In the table, enter the following settings:



**5** In the **Study** toolbar, click **Compute**.

# **RESULTS**

*Polarization*

- **1** In the Home toolbar, click **Add Plot Group** and choose **1D Plot Group**.
- **2** In the **Settings** window for **1D Plot Group**, type Polarization in the **Label** text field.
- **3** Locate the **Data** section. From the **Dataset** list, choose **Study 1/ Parametric Solutions 1 (sol2)**.
- **4** Locate the **Grid** section. Select the **Manual spacing** check box.
- **5** In the **y spacing** text field, type 0.1.
- **6** Locate the **Legend** section. From the **Position** list, choose **Lower right**.

## *Point Graph 1*

- **1** Right-click **Polarization** and choose **Point Graph**.
- **2** Select Point 1 only.
- **3** In the **Settings** window for **Point Graph**, locate the **y-Axis Data** section.
- **4** In the **Expression** text field, type es.PZ.
- **5** Locate the **x-Axis Data** section. From the **Parameter** list, choose **Expression**.
- In the **Expression** text field, type es.EZ.
- From the **Unit** list, choose **MV/m**.
- Click to expand the **Legends** section. Find the **Include** subsection. Clear the **Point** check box.
- Select the **Show legends** check box.
- In the **Polarization** toolbar, click **O** Plot.

#### *Electrostriction*

- In the **Model Builder** window, right-click **Polarization** and choose **Duplicate**.
- In the **Settings** window for **1D Plot Group**, type Electrostriction in the **Label** text field.
- Locate the **Grid** section. In the **y spacing** text field, type 0.001.

### *Point Graph 1*

- In the **Model Builder** window, expand the **Electrostriction** node, then click **Point Graph 1**.
- In the **Settings** window for **Point Graph**, locate the **y-Axis Data** section.
- In the **Expression** text field, type efe1.emZZ.
- In the **Electrostriction** toolbar, click **Plot**.

## **ROOT**

In the **Home** toolbar, click **Windows** and choose **Add Study**.

## **ADD STUDY**

Go to the **Add Study** window.

Add one more stationary study to analyze the mechanical load effect.

- Find the **Studies** subsection. In the **Select Study** tree, select **General Studies>Stationary**.
- **3** Click  $+$  **Add Study**.

# **STUDY 2**

#### *Step 1: Stationary*

- In the **Model Builder** window, under **Study 2** click **Step 1: Stationary**.
- In the **Settings** window for **Stationary**, locate the **Study Extensions** section.
- Select the **Auxiliary sweep** check box.
- Click  $+$  **Add**.

**5** In the table, enter the following settings:



*Parametric Sweep*

- **1** In the **Study** toolbar, click  $\frac{1}{2}$  **Parametric Sweep**.
- **2** In the **Settings** window for **Parametric Sweep**, locate the **Study Settings** section.
- **3** Click  $+$  **Add**.
- **4** In the table, enter the following settings:



**5** In the **Study** toolbar, click **Compute**.

## **RESULTS**

*Polarization 1*

- **1** In the **Model Builder** window, right-click **Polarization** and choose **Duplicate**.
- **2** In the **Settings** window for **1D Plot Group**, locate the **Data** section.
- **3** From the **Dataset** list, choose **Study 2/Parametric Solutions 2 (sol7)**.
- **4** In the **Polarization I** toolbar, click **O Plot**.

#### *Strain*

- **1** In the **Model Builder** window, right-click **Electrostriction** and choose **Duplicate**.
- **2** In the **Settings** window for **1D Plot Group**, type Strain in the **Label** text field.
- **3** Locate the **Data** section. From the **Dataset** list, choose **Study 2/ Parametric Solutions 2 (sol7)**.
- **4** In the **Strain** toolbar, click **Plot**.

## *Point Graph 1*

- **1** In the **Model Builder** window, expand the **Strain** node, then click **Point Graph 1**.
- **2** In the **Settings** window for **Point Graph**, locate the **y-Axis Data** section.
- **3** In the **Expression** text field, type solid.eZZ.