

# Stationary Analysis of a Biased Resonator — 2D

Silicon micromechanical resonators have long been used for designing sensors and are now becoming increasingly important as oscillators in the consumer electronics market. In this sequence of models, a surface micromachined MEMS resonator, designed as part of a micromechanical filter, is analyzed in detail. The resonator is based on that developed in Ref. 1.

This model performs a stationary analysis of the resonator, with an applied DC bias. It is used as a basis for all the subsequent analyses.

# Model Definition

Ref. 1 describes a polysilicon resonator, which is manufactured through a surface micromachining process. The details of this process are outlined in the Stationary Analysis of a Biased Resonator — 3D documentation. For this 2D study, a simplified version of the 3D geometry is considered. For simplicity, the resonator is modeled as a 2 µm thick rectangular beam with a length of 45 µm. A Fixed Constraint boundary is applied to each end of the resonator to act as the anchor points at which the resonator is attached to the substrate wafer. The wafer substrate is not explicitly modeled, instead only a 0.1985 µm thick air gap between the resonator and the substrate is included. The effects of the driving electrode are included using Electric Potential boundary conditions applied directly to the underside of the air gap, as shown in Figure 1.

Note that although the structure has a plane of symmetry, which vertically bisects the device, we do not use a symmetry boundary condition. A subsequent model considers the normal modes of the structure, and a symmetry condition eliminates the anti-symmetric modes from this analysis.

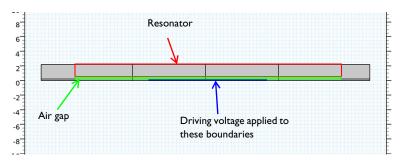


Figure 1: The model geometry. The rectangular resonator and the air gap are highlighted in red and green outline, respectively. The boundaries to which the driving voltage is applied are

highlighted in blue. Note that the vertical dividing lines are not part of the physical geometry of the resonator, but are included to allow a suitable swept mesh to be easily created.

In operation the silicon resonator is grounded (using the Domain Terminal feature) and a driving electrode applies an electric potential to the central portion of the air gap, as shown in Figure 1. Typically a DC bias of 35 V is applied in normal operation of the device. In this model the deformation of the structure is computed with the applied DC bias.

#### **ELECTROMECHANICAL FORCES**

Within a vacuum or other medium, forces between charged bodies can be computed on the assumption that a fictitious state of stress exists within the field. The Electromagnetic or Maxwell stress tensor can be used to compute the induced stresses in a material as a result of an electric field as well as surface forces acting on bodies in air or vacuum. Within a material, COMSOL Multiphysics uses the following form of the stress tensor  $T_{\rm EM,S}$ , which is appropriate for isotropic materials (Ref. 2):

$$T_{EM,S} = -\frac{1}{2}(\mathbf{E} \cdot \mathbf{D} + \alpha_2 \mathbf{E} \cdot \mathbf{E})I + \mathbf{E}\mathbf{D}^T + \frac{1}{2}(\alpha_2 - \alpha_1)\mathbf{E}\mathbf{E}^T$$

where  ${\bf E}$  is the electric field,  ${\bf D}$  is the electric displacement field, I is the identity tensor, and  $\epsilon_0$  is the permittivity of free space and  $a_1$  and  $a_2$  are material parameters that specify the electrostrictive properties of the material (for this device, assume  $a_1=a_2=0$  because the field is in any case very low within the material). This additional stress is applied to the material by the electromechanical solid node. Note that mechanical stresses are usually induced in the material as a result of the net forces acting on the surfaces, in addition to the stress induced by the electric field.

The forces on the surfaces of a solid body can be computed by applying a similar stress term within the vacuum of the form:

$$T_{\text{EM, }V} = -\frac{1}{2}(\mathbf{E} \cdot \mathbf{D})I + \mathbf{ED}^{T}$$

A net force on the surface typically results from the discontinuity of the stress tensor at the interface. However, since it is undesirable to apply a stress term throughout the vacuum, the force is only available on the surface of solid bodies, via the electromechanical interface node. The surface force is given by:

$$\mathbf{n}_1 T_{\mathrm{EM},\,V} = - \bigg(\frac{1}{2} \mathbf{E} \cdot \mathbf{D}\bigg) \mathbf{n}_1 + (\mathbf{n}_1 \cdot \mathbf{E}) \mathbf{D}$$

where  $\mathbf{n}_1$  is the surface normal, pointing out from the mechanical body.

Figure 2 shows the y displacement of the structure with an applied DC bias. As expected the structural displacement is maximal at the center of the geometry. The maximum displacement is 11.2 nm.

The electric potential contours are shown in Figure 3. The fringing fields extend approximately 1 µm into the gap either side of the driving electrode. Note that the fringing fields are not well resolved due to the structure of the swept mesh. In order to investigate these fields the mesh must be refined on either side of the electrode. Also note that the silicon is assumed to be a perfect conductor. Although the author's of Ref. 1 do not explicitly give the doping in the polysilicon, it is likely that this assumption is relatively poor given the estimated depletion region width of approximately 0.7 µm that is quoted. This model could be extended to include the effects of semiconductor transport and an improvement on this assumption could be made by adding the electric currents which are induced inside the resonator.

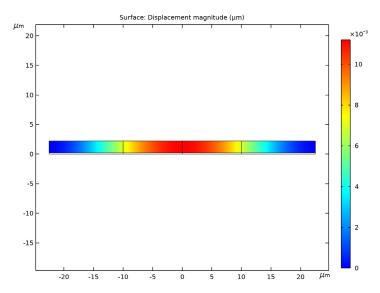


Figure 2: The y-displacement of the resonator as a function of position. The maximum displacement occurs in the center of the resonator, immediately over the biasing electrode.

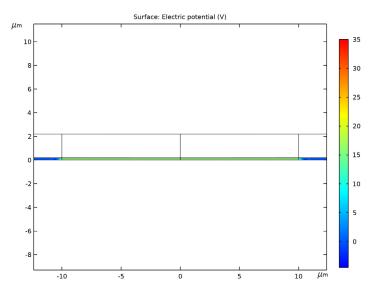


Figure 3: Electric potential contours in the gap between the grounded resonator and the biased driving electrode.

# References

- 1. F.D. Bannon III, J.R. Clark, and C.T.-C. Nguyen, "High-Q HF Microelectromechanical Filters," IEEE Journal of Solid State Circuits, vol. 35, no. 4, pp. 512-526, 2000.
- 2. J.A. Stratton, Electromagnetic Theory, McGraw-Hill, New York, 1941.

Application Library path: MEMS Module/Actuators/biased resonator 2d basic

# Modeling Instructions

From the File menu, choose New.

#### NEW

In the New window, click Model Wizard.

#### MODEL WIZARD

- I In the Model Wizard window, click **2** 2D.
- 2 In the Select Physics tree, select Structural Mechanics>Electromagnetics-Structure Interaction>Electromechanics>Electromechanics.
- 3 Click Add.
- 4 Click Study.
- 5 In the Select Study tree, select General Studies>Stationary.
- 6 Click **Done**.

#### **GLOBAL DEFINITIONS**

## Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
Vdc	35[V]	35 V	DC bias voltage

#### **GEOMETRY I**

- I In the Model Builder window, under Component I (compl) click Geometry I.
- 2 In the Settings window for Geometry, locate the Units section.
- 3 From the Length unit list, choose µm.

## Rectangle I (rI)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type 22.5.
- 4 In the Height text field, type 2.
- **5** Locate the **Position** section. In the **x** text field, type -22.5.
- 6 In the y text field, type 0.1985.

## Rectangle 2 (r2)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type 22.5.
- 4 In the Height text field, type 0.1985.
- 5 Locate the **Position** section. In the **x** text field, type -22.5.

#### Rectangle 3 (r3)

- I In the Geometry toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- 3 In the Width text field, type 10.
- 4 In the **Height** text field, type 2.1985.
- **5** Locate the **Position** section. In the **x** text field, type -10.

#### Mirror I (mir I)

- I In the Geometry toolbar, click \( \sum\_{i} \) Transforms and choose Mirror.
- 2 Click in the **Graphics** window and then press Ctrl+A to select all objects.
- 3 In the Settings window for Mirror, locate the Input section.
- **4** Select the **Keep input objects** check box.
- 5 Click **Build All Objects**.
- 6 Click the **Zoom Extents** button in the **Graphics** toolbar.

Add materials to the model.

#### ADD MATERIAL

- I In the Home toolbar, click Radd Material to open the Add Material window.
- 2 Go to the Add Material window.
- 3 In the tree, select MEMS>Semiconductors>Si Polycrystalline silicon.
- 4 Click Add to Component in the window toolbar.
- 5 In the tree, select Built-in>Air.
- **6** Click **Add to Component** in the window toolbar.
- 7 In the Home toolbar, click **‡ Add Material** to close the **Add Material** window.

#### MATERIALS

Air (mat2)

- I Select Domains 1, 3, 5, and 7 only.
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- 3 Click **\( \)** Create Selection.
- 4 In the Create Selection dialog box, type Air in the Selection name text field.
- 5 Click OK.
- 6 In the Settings window for Material, click to expand the Material Properties section.

# SOLID MECHANICS (SOLID)

- I In the Model Builder window, under Component I (compl) click Solid Mechanics (solid).
- 2 Select Domains 2, 4, 6, and 8 only.

# **ELECTROSTATICS (ES)**

In the Model Builder window, under Component I (compl) click Electrostatics (es).

# Charge Conservation 2

- I In the Physics toolbar, click **Domains** and choose **Charge Conservation**.
- 2 In the Settings window for Charge Conservation, locate the Domain Selection section.
- **3** From the **Selection** list, choose **Air**.

#### DEFINITIONS

Deforming Domain I

- In the Model Builder window, under Component I (compl)>Definitions>Moving Mesh click Deforming Domain 1.
- 2 In the Settings window for Deforming Domain, locate the Domain Selection section.

3 From the Selection list, choose Air.
Set up the solid mechanics and electrostatics boundary conditions.

# SOLID MECHANICS (SOLID)

In the Model Builder window, under Component I (compl) click Solid Mechanics (solid).

Fixed Constraint I

- I In the Physics toolbar, click Boundaries and choose Fixed Constraint.

  Apply a Fixed Constraint to both ends of the resonator.
- **2** Select Boundaries 3 and 22 only.

# **ELECTROSTATICS (ES)**

With the assumption that the silicon membrane is a good conductor, use the Domain Terminal feature to ground the Si domains. Note: The Domain Terminal feature will be very handy for a conducting domain with a complex shape and many exterior boundaries - instead of selecting all the boundaries to set up the Ground, Terminal, or Electric Potential boundary condition, we only need to select the domain to specify the Domain Terminal with the same effect. In addition, the computation load is reduced, because the electrostatic degrees of freedom within the Domain Terminal do not need to be solved for.

I In the Model Builder window, under Component I (compl) click Electrostatics (es).

Terminal I

- I In the Physics toolbar, click **Domains** and choose **Terminal**.
- **2** Select Domains 2, 4, 6, and 8 only.
- 3 In the Settings window for Terminal, locate the Terminal section.
- 4 From the Terminal type list, choose Voltage.
- **5** In the  $V_0$  text field, type 0.

Electric Potential I

- I In the Physics toolbar, click Boundaries and choose Electric Potential.

  Set the bias voltage on the driving electrode with the Electric Potential feature.
- 2 In the Settings window for Electric Potential, locate the Electric Potential section.
- **3** In the  $V_0$  text field, type Vdc.

4 Select Boundaries 7 and 12 only.

Modify the default mesh settings to suit the model geometry.

A mapped mesh allows good resolution of the small air gap between the driving electrode and the resonator.

#### MESH I

# Mabbed I

In the Mesh toolbar, click Mapped.

#### Distribution I

- I Right-click Mapped I and choose Distribution.
- 2 In the Settings window for Distribution, locate the Boundary Selection section.
- 3 Click Paste Selection.
- 4 In the Paste Selection dialog box, type 5 10 15 20 in the Selection text field.
- 5 Click OK.
- 6 In the Settings window for Distribution, locate the Distribution section.
- 7 In the Number of elements text field, type 15.

#### Distribution 2

- I In the Model Builder window, right-click Mapped I and choose Distribution.
- 2 In the Settings window for Distribution, locate the Boundary Selection section.
- 3 Click Paste Selection.
- 4 In the Paste Selection dialog box, type 1 3 in the Selection text field.
- 5 Click OK.
- 6 In the Settings window for Distribution, locate the Distribution section.
- 7 In the Number of elements text field, type 10.
- 8 Click Build All.
- 9 Click the Zoom Extents button in the Graphics toolbar.

# STATIONARY

- I In the Model Builder window, right-click Study I and choose Rename.
- 2 In the Rename Study dialog box, type Stationary in the New label text field.
- 3 Click OK.
- 4 In the Home toolbar, click **Compute**.

#### RESULTS



- I In the Settings window for 2D Plot Group, type Biased Displacement in the Label text field.
- 2 In the Biased Displacement toolbar, click  **Plot**.
- 3 Click the Zoom Extents button in the Graphics toolbar.

Compare the resulting plot with that in Figure 2.

# Selection I

- I In the Model Builder window, expand the Results>Electric Potential (es) node.
- 2 Right-click Surface I and choose Selection.
- 3 In the Settings window for Selection, locate the Selection section.
- 4 From the Selection list, choose Air.
- 5 In the Electric Potential (es) toolbar, click Plot.
- **6** Click the **Zoom Extents** button in the **Graphics** toolbar.
- 7 Click the **Q** Zoom In button in the Graphics toolbar.

Compare the resulting plot with that in Figure 3.