

# Electric Motor Noise: Permanent Magnet Synchronous Motor

Electric motors are ubiquitous in many different industries. Cars, white goods, heating, ventilation, and air conditioning (HVAC) systems require electric motors that not only have the right electromechanical characteristics, but also limit the noise generated during its operation. This model demonstrates how to analyze the noise generated by an electric motor during its operation at different speeds of rotation. The type of electric motor analyzed, a permanent magnet synchronous motor (PMSM) uses permanent magnets in the rotor and a variable frequency current traveling through the stator to generate torque.

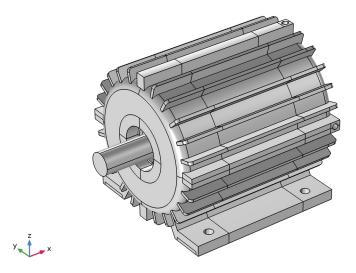


Figure 1: Geometry of the electric motor without the surrounding domains.

The geometry of the electric motor is shown in Figure 1. The electromagnetic forces generated during its operation result in vibrations not only at the frequency of rotation of the rotor but also at higher frequencies or harmonics. A transient analysis is used to determine the electromagnetic forces in the time domain. A Fourier transform is used to determine the contributions in the frequency domain. The vibroacoustic response of the PMSM casing and its acoustic radiation is computed. A Campbell diagram is generated showing the main harmonics contributing to the acoustic response of the PMSM at various speeds of rotation.

The electromagnetic characteristics of a PMSM are typically well approximated by simulating a 2D section of the motor. In order to reduce the computational cost of the current analysis, the model uses this approximation and computes the electromagnetic forces using a 2D model. The section of the PMSM, shown in Figure 2, is used to compute the transient electromagnetic forces developed during its rotation. This transient simulation covers a rotation of  $60^{\circ}$ . This is the minimum angle of rotation that brings back the geometry to an equivalent of the initial position, based on the number of poles and coils.

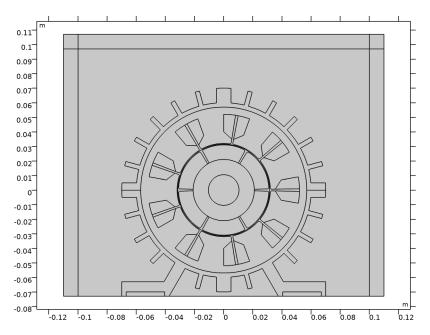


Figure 2: 2D section the electric motor with the surrounding air domains.

This analysis produces a spatial distribution of forces that are computed in the time domain and are transformed in the frequency domain by using the *Time to Frequency FFT* Solver. This solver performs a discrete Fourier transformation of a time-dependent variable and transforms it into a series of complex coefficients given by Equation 1.

$$\omega(f_k) = \sum_{j=0}^{N-1} u(t_j) e^{-\frac{2\pi i j k}{N}}$$

$$\tag{1}$$

Where  $\omega(f_k)$  is the complex Fourier coefficients for the frequency  $f_k$ ,  $u(t_i)$  is the input signal at the time  $t_j$ , i denotes the imaginary unit and N is the total number of samples of the input signal. For each frequency  $f_k$ , this transformation produces a spatial distribution of complex forces. The fact that these forces are complex valued means that the excitation includes both the force magnitude and its phase, so different parts of the model will be excited at different phases.

The frequency at which these electromagnetic forces are created is directly proportional to the speed of rotation of the rotor. As these forces produce an almost constant torque, the mechanical power generated by the motor is in fact proportional to the speed of rotation. This is usually true for small rotational speeds. The thermal losses in the coils are proportional to the mechanical power of the engine. As the rotational speed increases, these losses become substantial and the passive cooling is not able to keep up. This is what is called the thermal limit of the motor. Most motors control the torque-speed curve to avoid reaching the thermal limit. This curve usually keeps a constant torque for low rotational speeds and then a constant power at higher speeds. The model uses the torquespeed curve shown on Figure 3, but any other curve could be used instead.

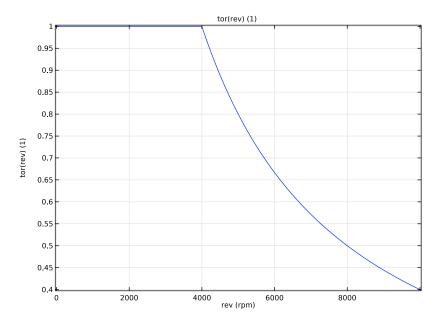


Figure 3: Torque-Speed of rotation curve.

The electromagnetic forces generated at different multiples of the rotor speed are called harmonics. Each of these harmonics will have a different contribution to the total noise at various driving frequencies. In the following step, the 2D harmonic forces are applied to the 3D model of the electric engine with the acoustic domains surrounding the motor. Figure 4 shows the 3D geometry including the surrounding acoustic domains.

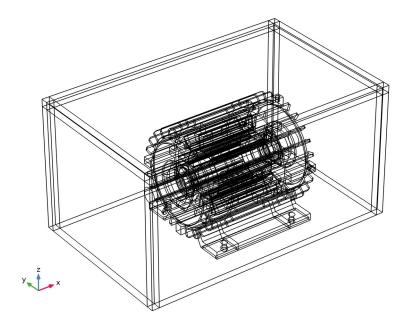


Figure 4: 3D geometry including the acoustic domains representing an open domain.

Once the frequency response to each of the harmonic excitation is known, it is possible to create a Campbell diagram, sometimes called Waterfall plot. The Campbell diagram shows, for a given location, the contribution of the different harmonics to the total noise level as a function of the rotational speed. This allows the identification of undesirable characteristics like frequencies where the casing is very efficient at radiating noise or harmonics which are dominant in the total noise.

Another method to present these results is to generate a time signal of the acoustic response at a given point as the rotational speed of the motor varies. Figure 5 shows the variation of the rotational speed during the duration of the acoustic signal used to generate the time signal. Any other duration of the time signal or variation profile of the rotational speed could be used.

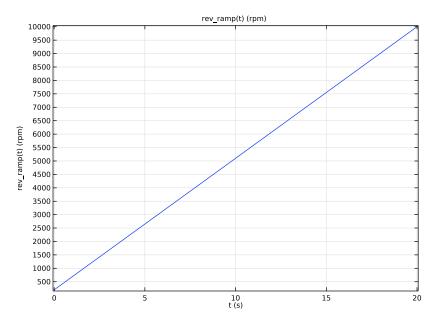


Figure 5: Variation of the motor rotational speed during the duration of the acoustic signal.

This model presents a quick and efficient method to analyze the harmonic content of the sound generated by a PMSM. Other acoustic sources like the gear noise or the wind induced noise due to the refrigeration are not considered. Due to the limited frequency content of the harmonic noise, it is usually the noise that stands out in an electric motor and thus the main source that is tuned during the design of an electric motor.

# Results and Discussion

Figure 6 shows the magnetic flux density norm and streamlines at four different times of the time dependent step. Note the rotation of the rotor and how the magnetic flux is concentrated in the areas close to the magnets and in the outer part of the coils.

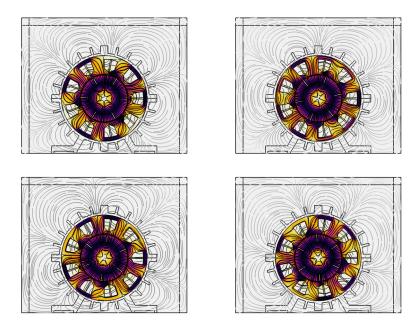


Figure 6: Magnetic flux density norm and streamlines at 0 ms, 10 ms, 20 ms, and 30 ms.

The time-domain analysis produces a distribution of forces in the stator and rotor. As an example of the time variation of these forces, Figure 7 shows the components of the electromagnetic forces for two points in the model. This time signal is a periodic signal that will be repeated 6 times during a complete rotation of the rotor.

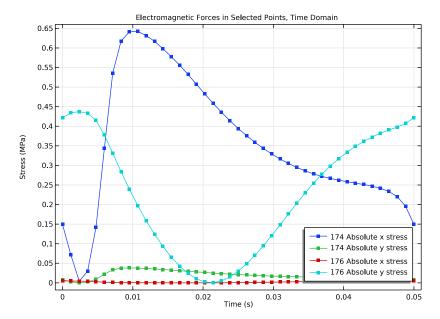


Figure 7: Time domain signal of the components of the electromagnetic forces at two points.

This time signal can be easily transformed into the frequency domain and normalized to the value of the first harmonic. Figure 8 shows how the FFT of the forces normalized to the first harmonic at 20 Hz, has decreasing values as the frequency increases. The eighth harmonic has a contribution that is below 5% of the first harmonic, so considering seven harmonics in the analysis seems reasonable, as any higher order harmonics are likely to have very limited influence.

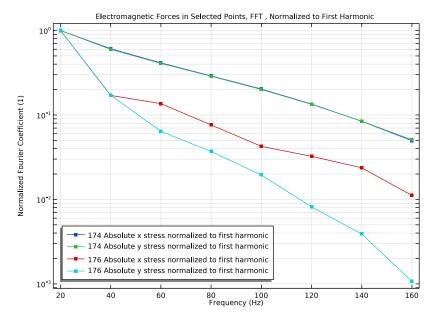


Figure 8: Frequency domain components of the electromagnetic forces at two points, normalized to the first harmonic value.

It is also relevant to analyze the spatial distribution of the different harmonics, not only its variation with frequency for a single point. Figure 9 shows the spatial distribution of the seventh harmonic, the last harmonic solved for. Harmonics above this one will require a finer mesh, as the higher the harmonic, the finer the spatial distribution of the electromagnetic forces. In order to solve harmonics above the seventh, the model would need to have a finer mesh, which would increase the computational time and will not add substantial contributions to the noise.

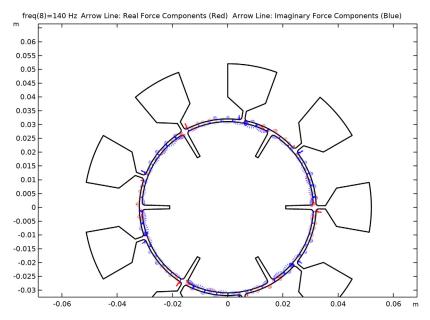


Figure 9: Spatial distribution of the electromagnetic forces in the frequency domain, showing both real (red arrows) and imaginary (blue arrows) parts.

The electromagnetic forces obtained in the 2D model can be translated to the 3D model using the General Extrusion feature. Figure 10 shows the 3D model and the forces generated by the third harmonic.

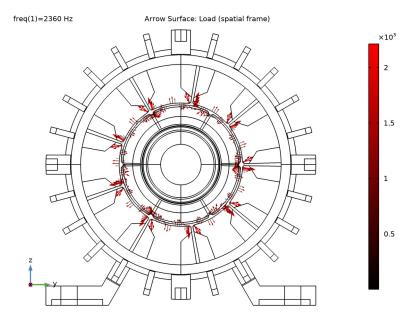


Figure 10: Real part of the electromagnetic forces applied to the 3D model for the third harmonic.

This forces, although compensated globally due to the symmetry of the motor, produce displacements in the structure that in turn are converted to acoustic pressure.

Figure 11shows the displacement and acoustic pressure generated by the third harmonic at 2,360 Hz.



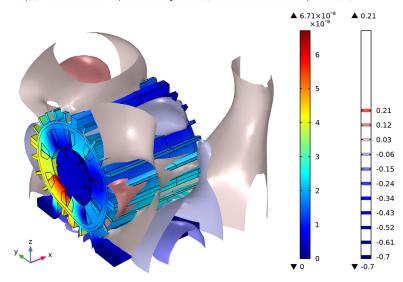


Figure 11: Displacements and acoustic pressures generated by the third harmonic at 2,360 Hz.

The Exterior Field feature permits the evaluation of the acoustic pressure at any point outside of the computational domain. Figure 12 shows the sound pressure level (SPL) at the surface of the motor and at 0.5 m away from the motor. Note how this radiation pattern has many lobes, meaning that the acoustic response will depend greatly on the position of the listening point.

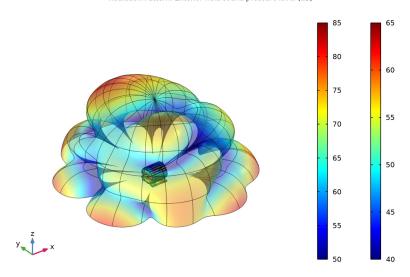


Figure 12: Sound pressure level at the surface of the motor and 0.5 m away.

The contribution of the different harmonics can be seen in a Campbell diagram. A Campbell diagram shows, for a given listening point, the sound pressure level of each harmonic as a function of the speed of rotation of the motor. Figure 13 shows how the two microphones present very different Campbell diagrams. Note how the first and third harmonics have the largest influence on the noise level for both microphone positions. Note as well how the first microphone shows increased noise levels around 2,500 Hz for most of the harmonics, indicating that there is a casing mode making this frequency stand out. A similar effect is found for the second microphone slightly below 2,500 Hz and around 1800 Hz.

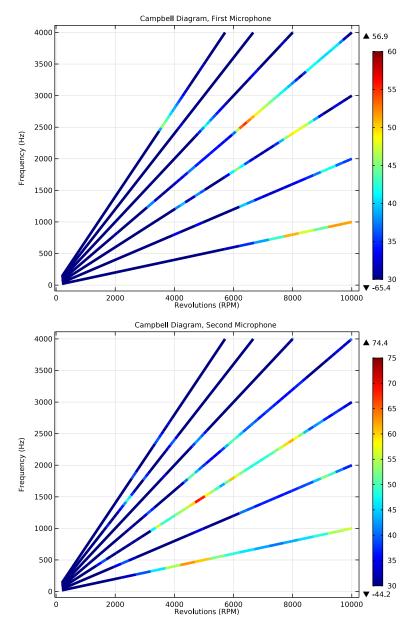


Figure 13: Campbell diagrams at the microphones.

The electromagnetic model contains two different objects forming an assembly. Having independent meshes in each of the objects permits the rotation of the rotor using the Rotating Domain feature.

The electromagnetic analysis study composes two steps, a stationary analysis and a time dependent analysis. The stationary analysis is used to initialize the electromagnetic field as the system contains permanent magnets and nonzero currents at the initial time. Trying to solve the time dependent analysis without the stationary part assumes that the currents are switched on and the magnets added at first time step. This will make the convergence almost impossible. Turning the Jacobian update to every iteration on the time dependent analysis reduces the total running time.

The electromagnetic forces are computed through the use of the Force Calculation feature available in the Magnetic Fields physics. A Weak Form Boundary PDE is used to store the electromagnetic forces at the interfaces and produce a FFT only of this forces, instead of the complete solution.

The Time to Frequency FFT study is used to transform a spatial and time dependent variable into a complex variable in the frequency domain. Once that the electromagnetic forces are expressed in the frequency domain, it is simpler to produce frequency response analysis for a varying excitation.

The General Extrusion feature is used to transform variables existing in a component to another component with different coordinates or even different number of dimensions. In this case, the 2D results are translated to the 3D component using the comp.genext() operator.

The operator withsol() is used to select the right harmonic of the excitation forces in the frequency sweep. As an example, the expression, withsol('sol3',Fy,setval(freq, 20[Hz]\*(harm exc))), takes the variable Fy from the sol3 (The results of the FFT) with the frequency matching 20 Hz times the number of the harmonic excited.

The frequency request in the vibroacoustic analysis uses the expression range (f0\* harm exc,fdelta,min(fmax,rpm max/rpm0\*f0\*harm exc)) min(fmax,rpm max/ rpm0\*f0\*harm exc) which is a frequency sweep starting at f0 times the number of the harmonic excited, taking steps every fdelta and stopping when the rotational speed reaches 10,000 rpm or the frequency reaches 4,000 Hz, whatever happens first.

The solver in the vibroacoustic analysis is set manually to a segregated solver with 1 iteration, meaning that the displacements will be obtained first and the acoustic pressure will be computed based on these displacements, without back coupling of the acoustic pressure into the structural problem. This is an adequate approach for problems where vibrating structures radiate noise into the environment, and allows for a reduction in the running times. This assumption should always be confirmed with a fully coupled analysis.

The model takes approximately 8 hours to run on a workstation with a sweep of 7 harmonics and outputs every 50 Hz. This run time can be significantly reduced by using distributed cluster computation or reducing the number of frequencies or harmonics requested.

The acoustic signal is exported to a .wav file that could be listened to or postprocess with any other tool.

**Application Library path:** Acoustics\_Module/Automotive/ electric motor noise pmsm

# Modeling Instructions

From the File menu, choose New.

# NEW

In the New window, click Model Wizard.

#### MODEL WIZARD

- I In the Model Wizard window, click **2** 2D.
- 2 In the Select Physics tree, select AC/DC>Electromagnetic Fields>Magnetic Fields (mf).
- 3 Click Add.
- 4 In the Select Physics tree, select Mathematics>PDE Interfaces>Lower Dimensions> Weak Form Boundary PDE (wb).
- 5 Click Add.
- 6 Click 🗪 Study.
- 7 In the Select Study tree, select General Studies>Stationary.
- 8 Click M Done.

#### ROOT

The first study uses the cross section of the electric engine to compute the electromagnetic excitation. Proceed to add a 3D component and import the geometry of the engine.

# ADD COMPONENT

In the **Home** toolbar, click **Add Component** and choose **3D**.

#### GEOMETRY 2

- I In the Geometry toolbar, click Insert Sequence.
- 2 Browse to the model's Application Libraries folder and double-click the file electric\_motor\_noise\_pmsm\_geom\_sequence.mph.
- 3 In the Geometry toolbar, click **Build All**.
- 4 Click the Wireframe Rendering button in the Graphics toolbar.
- 5 Click the Show Grid button in the Graphics toolbar. Wireframe rendering allows for an easier visualization of the geometry. The geometry should look like Figure 4.

The imported COMSOL file includes a set of parameters which facilitate the update of the electric engine. Update the name of the parameter group.

#### GLOBAL DEFINITIONS

#### Geometry parameters

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, type Geometry parameters in the Label text field.

Add a new parameter group and populate this group with the parameters imported from an external file. This second parameter group includes parameter related to the modeling.

#### Model Parameters

- I In the Home toolbar, click Pi Parameters and choose Add>Parameters.
- 2 In the Settings window for Parameters, type Model Parameters in the Label text field.
- 3 Locate the Parameters section. Click **Load from File**.
- 4 Browse to the model's Application Libraries folder and double-click the file electric\_motor\_noise\_pmsm\_parameters.txt.

Add a Cross Section feature to generate the 2D geometry. As the rotor will be rotating through a Rotating Domain feature, it is necessary that the 2D geometry is created as an assembly.

#### **GEOMETRY I**

In the Model Builder window, under Component I (compl) click Geometry I.

Cross Section I (crol)

- I In the Geometry toolbar, click A Cross Section.
- 2 In the Settings window for Cross Section, click 📳 Build Selected.

Form Union (fin)

- I In the Model Builder window, under Component I (compl)>Geometry I click Form Union (fin).
- 2 In the Settings window for Form Union/Assembly, locate the Form Union/Assembly section.
- 3 From the Action list, choose Form an assembly.
- 4 In the Geometry toolbar, click **Build All**. The geometry should look like Figure 2.

Now proceed to create some selections that will be used during the model definition.

# **DEFINITIONS (COMPI)**

Shaft

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Shaft in the Label text field.
- **3** Select Domain 40 only.

Laminated rotor

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Laminated rotor in the Label text field.
- **3** Select Domain 39 only.

Magnets A

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Magnets A in the Label text field.
- 3 Select Domains 33, 36, and 37 only.

# Magnets B

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Magnets B in the Label text field.
- 3 Select Domains 34, 35, and 38 only.

# Magnets

- I In the **Definitions** toolbar, click **Union**.
- 2 In the Settings window for Union, type Magnets in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Magnets A and Magnets B.
- 5 Click OK.

# Inner air gab

- I In the **Definitions** toolbar, click **\( \bigcap\_{\bigcap} \) Explicit**.
- 2 In the Settings window for Explicit, type Inner air gap in the Label text field.
- **3** Select Domain 32 only.

#### Rotor

- I In the **Definitions** toolbar, click **I Union**.
- 2 In the Settings window for Union, type Rotor in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Shaft, Laminated rotor, and Magnets.
- 5 Click OK.

# Rotating parts

- I In the **Definitions** toolbar, click **Union**.
- 2 In the Settings window for Union, type Rotating parts in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Inner air gap and Rotor.
- 5 Click OK.

#### Fixed Parts

- I In the **Definitions** toolbar, click **Complement**.
- 2 In the Settings window for Complement, type Fixed Parts in the Label text field.
- 3 Locate the Input Entities section. Under Selections to invert, click + Add.

- 4 In the Add dialog box, select Rotating parts in the Selections to invert list.
- 5 Click OK.

#### Coils A

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Coils A in the Label text field.
- **3** Select Domains 12, 15, 18, 20, 25, and 27 only.

- I In the **Definitions** toolbar, click **\( \bigcap\_{\bigcap} \) Explicit**.
- 2 In the Settings window for Explicit, type Coils B in the Label text field.
- **3** Select Domains 13, 16, 17, 19, 26, and 28 only.

#### Coils C

- I In the **Definitions** toolbar, click **\( \) Explicit**.
- 2 In the Settings window for Explicit, type Coils C in the Label text field.
- **3** Select Domains 9, 10, and 21–24 only.

#### Coils

- I In the **Definitions** toolbar, click **Union**.
- 2 In the Settings window for Union, type Coils in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Coils A, Coils B, and Coils C.
- 5 Click OK.

#### Outer air gab

- I In the **Definitions** toolbar, click **\( \) Explicit**.
- 2 In the Settings window for Explicit, type Outer air gap in the Label text field.
- **3** Select Domain 11 only.

#### Exterior air

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Exterior air in the Label text field.
- **3** Select Domains 1–4, 14, 30, and 31 only.

# Casing

- I In the **Definitions** toolbar, click **\( \frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Casing in the Label text field.

**3** Select Domains 5–7 and 29 only.

#### Air

- I In the **Definitions** toolbar, click **I Union**.
- 2 In the Settings window for Union, type Air in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Inner air gap, Outer air gap, and Exterior air.
- 5 Click OK.

# Stator forces

- I In the **Definitions** toolbar, click **Difference**.
- 2 In the Settings window for Difference, type Stator forces in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, select Fixed Parts in the Selections to add list.
- 5 Click OK.
- 6 In the Settings window for Difference, locate the Input Entities section.
- 7 Under Selections to subtract, click + Add.
- 8 In the Add dialog box, in the Selections to subtract list, choose Coils, Casing, and Air.
- 9 Click OK.

### External boundaries

- I In the Model Builder window, right-click Selections and choose Disk.
- 2 In the Settings window for Disk, type External boundaries in the Label text field.
- 3 Locate the Geometric Entity Level section. From the Level list, choose Boundary.
- 4 Locate the Size and Shape section. In the Outer radius text field, type inf.
- 5 In the Inner radius text field, type r\_stator.

# Adjacent to rotor forces

- I In the **Definitions** toolbar, click **Adjacent**.
- 2 In the Settings window for Adjacent, type Adjacent to rotor forces in the Label text field.
- 3 Locate the Input Entities section. Under Input selections, click + Add.
- 4 In the Add dialog box, select Rotor in the Input selections list.
- 5 Click OK.

Adjacent to stator forces

- I In the **Definitions** toolbar, click **\bigcip\_a Adjacent**.
- 2 In the Settings window for Adjacent, type Adjacent to stator forces in the Label text field.
- 3 Locate the Input Entities section. Under Input selections, click + Add.
- 4 In the Add dialog box, select Stator forces in the Input selections list.
- 5 Click OK.

#### Force calculation

- I In the **Definitions** toolbar, click **Difference**.
- 2 In the Settings window for Difference, type Force calculation in the Label text field.
- 3 Locate the Geometric Entity Level section. From the Level list, choose Boundary.
- 4 Locate the Input Entities section. Under Selections to add, click + Add.
- 5 In the Add dialog box, in the Selections to add list, choose Adjacent to rotor forces and Adjacent to stator forces.
- 6 Click OK.
- 7 In the Settings window for Difference, locate the Input Entities section.
- 8 Under Selections to subtract, click + Add.
- 9 In the Add dialog box, select External boundaries in the Selections to subtract list.
- IO Click OK.

#### Adjacent to air gaps and coils

- I In the **Definitions** toolbar, click **Adjacent**.
- 2 In the Settings window for Adjacent, type Adjacent to air gaps and coils in the **Label** text field.
- 3 Locate the Input Entities section. Under Input selections, click + Add.
- 4 In the Add dialog box, in the Input selections list, choose Inner air gap, Coils, and Outer air gap.
- 5 Click OK.

#### Iron

- I In the **Definitions** toolbar, click  **Union**.
- 2 In the Settings window for Union, type Iron in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.

- 4 In the Add dialog box, in the Selections to add list, choose Shaft, Laminated rotor, and Stator forces.
- 5 Click OK.

# Force calculation domains

- I In the **Definitions** toolbar, click  **Union**.
- 2 In the Settings window for Union, type Force calculation domains in the Label text field.
- 3 Locate the Input Entities section. Under Selections to add, click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Inner air gap, Coils, and Outer air gap.
- 5 Click OK.

# Adjacent to air gap in the stator

- I In the **Definitions** toolbar, click **Difference**.
- 2 In the Settings window for Difference, type Adjacent to air gap in the stator in the Label text field.
- 3 Locate the Geometric Entity Level section. From the Level list, choose Boundary.
- 4 Locate the Input Entities section. Under Selections to add, click + Add.
- 5 In the Add dialog box, select Adjacent to stator forces in the Selections to add list.
- 6 Click OK.
- 7 In the Settings window for Difference, locate the Input Entities section.
- 8 Under Selections to subtract, click + Add.
- 9 In the Add dialog box, select External boundaries in the Selections to subtract list.
- IO Click OK.

Add a variable that will define the rotation both in a stationary and a time dependent step.

#### Variables 1

- I In the Model Builder window, right-click Definitions and choose Variables.
- 2 In the Settings window for Variables, locate the Variables section.
- **3** In the table, enter the following settings:

| Name     | Expression                              | Unit | Description |
|----------|---|------|-------------|
| rotation | <pre>if(isdefined(t),w0*t+ang0,0)</pre> | rad  | Rotation    |

The General Extrusion coupling operator to map the 2D results into the 3D geometry. This operator allows to map geometries even when the coordinate axes are not alligned.

General Extrusion 1 (genext1)

- I In the Definitions toolbar, click // Nonlocal Couplings and choose General Extrusion.
- 2 In the Settings window for General Extrusion, locate the Source Selection section.
- 3 From the Geometric entity level list, choose Boundary.
- 4 From the Selection list, choose Force calculation.
- **5** Locate the **Destination Map** section. In the **x-expression** text field, type y.
- **6** In the **y-expression** text field, type z.
- 7 Locate the Source section. Select the Use source map check box.
- 8 Click to expand the Advanced section. From the Mesh search method list, choose Closest point.
- 9 Select the Use NaN when mapping fails check box.

Add a **Clindrical System** that will be used to define the orientation of the magnets.

Cylindrical System 3 (sys3)

In the **Definitions** toolbar, click  $\bigvee_{x}^{z}$  Coordinate Systems and choose Cylindrical System.

The **Rotating Domain** allows for the rotor to move independently of the stator.

Rotating Domain I

- I In the Definitions toolbar, click Moving Mesh and choose Rotating Domain.
- 2 In the Settings window for Rotating Domain, locate the Domain Selection section.
- 3 From the Selection list, choose Rotating parts.
- **4** Locate the **Rotation** section. In the  $\alpha$  text field, type rotation.

In the next steps, add the materials that make the section of the engine.

#### MATERIALS

Non-magnetic parts

- I In the Model Builder window, under Component I (compl) right-click Materials and choose Blank Material.
- 2 In the Settings window for Material, type Non-magnetic parts in the Label text field. Populate the missing properties of the material.

**3** Locate the **Material Contents** section. In the table, enter the following settings:

| Property                | Variable   | Value | Unit | Property group |
|-------------------------|--|-------|------|----------------|
| Relative permeability   | mur_iso; murii<br>= mur_iso,<br>murij = 0                        | 1     | I    | Basic          |
| Electrical conductivity | sigma_iso ; sigmaii = sigma_iso, sigmaij = 0                     | 0     | S/m  | Basic          |
| Relative permittivity   | epsilonr_iso;<br>epsilonrii =<br>epsilonr_iso,<br>epsilonrij = 0 | 1     | I    | Basic          |

4 In the Home toolbar, click Windows and choose Add Material from Library.

# ADD MATERIAL

- I Go to the Add Material window.
- 2 In the tree, select AC/DC>Soft Iron (Without Losses).
- 3 Click Add to Component in the window toolbar.

#### MATERIALS

Soft Iron (Without Losses) (mat2)

- I In the Settings window for Material, locate the Geometric Entity Selection section.
- 2 From the Selection list, choose Iron. Add a relative permeability of 1 to the material.
- **3** Locate the **Material Contents** section. In the table, enter the following settings:

| Property                 | Variable   | Value  | Unit | Property group |
|--------------------------|--|--------|------|----------------|
| Relative<br>permeability | mur_iso; murii<br>= mur_iso,<br>murij = 0            | 1      | I    | Basic          |
| Electrical conductivity  | sigma_iso;<br>sigmaii =<br>sigma_iso,<br>sigmaij = 0 | 0[S/m] | S/m  | Basic          |

| Property                             | Variable   | Value                  | Unit | Property group      |
|--------------------------------------|--|------------------------|------|---------------------|
| Relative permittivity                | epsilonr_iso;<br>epsilonrii =<br>epsilonr_iso,<br>epsilonrij = 0 | 1                      | I    | Basic               |
| Magnetic flux density norm           | normB  | BH(normHin)            | Т    | B-H curve           |
| Magnetic field norm                  | normH  | BH_inv(normBin)        | A/m  | B-H curve           |
| Magnetic coenergy density            | Wpm  | BH_prim(normHin)       | J/m³ | B-H curve           |
| Effective magnetic flux density norm | normBeff   | BHeff(normHeffin )     | Т    | Effective B-H curve |
| Effective magnetic field norm        | normHeff   | BHeff_inv(normBe ffin) | A/m  | Effective B-H curve |

#### ADD MATERIAL

- I Go to the Add Material window.
- 2 In the tree, select AC/DC>Copper.
- **3** Click **Add to Component** in the window toolbar.

### MATERIALS

Copper (mat3)

- I In the Settings window for Material, locate the Geometric Entity Selection section.
- **2** From the **Selection** list, choose **Coils**.

# ADD MATERIAL

- I Go to the Add Material window.
- 2 In the tree, select AC/DC>Hard Magnetic Materials> Sintered NdFeB Grades (Chinese Standard)>N40 (Sintered NdFeB).
- 3 Click Add to Component in the window toolbar.
- 4 In the tree, select Built-in>Aluminum 6063-T83.
- 5 Click Add to Component in the window toolbar.
- 6 In the Home toolbar, click 4 Add Material to close the Add Material window.

#### MATERIALS

N40 (Sintered NdFeB) (mat4)

- I In the Model Builder window, under Component I (compl)>Materials click N40 (Sintered NdFeB) (mat4).
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- 3 From the Selection list, choose Magnets.

Aluminum 6063-T83 (mat5)

- I In the Model Builder window, click Aluminum 6063-T83 (mat5).
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- 3 From the Selection list, choose Casing.

# MAGNETIC FIELDS (MF)

Specify the length of the engine.

- I In the Model Builder window, under Component I (compl) click Magnetic Fields (mf).
- 2 In the Settings window for Magnetic Fields, locate the Thickness section.
- **3** In the d text field, type Ltransv. Use linear discretization to reduce the computation time.
- 4 Click to expand the Discretization section. From the Magnetic vector potential list, choose Linear.

Non magnetic domains

- I In the Model Builder window, under Component I (compl)>Magnetic Fields (mf) click Ampère's Law I.
- 2 In the Settings window for Ampère's Law, type Non magnetic domains in the Label text field.

As part of these domains will be rotating, it is necessary to change the material type to solid.

3 Locate the Material Type section. From the Material type list, choose Solid.

#### Iron domains

- I In the Physics toolbar, click **Domains** and choose Ampère's Law.
- 2 In the Settings window for Ampère's Law, type Iron domains in the Label text field.
- 3 Locate the Domain Selection section. From the Selection list, choose Iron. As the rotor is partially composed of iron parts, it is necessary to change the material type to solid.

- 4 Locate the Material Type section. From the Material type list, choose Solid.
- 5 Locate the Constitutive Relation B-H section. From the Magnetization model list, choose B-H curve.

#### Magnets A

- I In the Physics toolbar, click **Domains** and choose Ampère's Law.
- 2 In the Settings window for Ampère's Law, type Magnets A in the Label text field.
- 3 Locate the Domain Selection section. From the Selection list, choose Magnets A.
- 4 Locate the Material Type section. From the Material type list, choose Solid. The magnets are oriented along the tangent direction of the rotor.
- 5 Locate the Coordinate System Selection section. From the Coordinate system list, choose Cylindrical System 3 (sys3).
- 6 Locate the Constitutive Relation B-H section. From the Magnetization model list, choose Remanent flux density.
- 7 Locate the Constitutive Relation Jc-E section. From the  $\sigma$  list, choose User defined.

# Magnets B

- I Right-click Magnets A and choose Duplicate.
- 2 In the Settings window for Ampère's Law, type Magnets B in the Label text field.
- 3 Locate the Domain Selection section. From the Selection list, choose Magnets B.
- **4** Locate the **Constitutive Relation B-H** section. Specify the **e** vector as

| - 1 | r   |
|-----|-----|
| 0   | phi |
| 0   | a   |

Proceed to define the engine coil groups.

#### Coils A

- I In the Physics toolbar, click **Domains** and choose **Coil**.
- 2 In the Settings window for Coil, type Coils A in the Label text field.
- 3 Locate the Domain Selection section. From the Selection list, choose Coils A.
- 4 Locate the Material Type section. From the Material type list, choose Solid.
- 5 Locate the Coil section. From the Conductor model list, choose Homogenized multiturn.
- 6 Select the Coil group check box.
- **7** In the  $I_{\text{coil}}$  text field, type IO\*cos(3\*rotation).

- **8** Locate the **Homogenized Multiturn Conductor** section. In the N text field, type Ncoil.
- **9** In the  $a_{coil}$  text field, type a\_coil.

Add a **Reversed Current Direction** feature to represent the part of the coil with current travelling in the opposing direction.

Reversed Current Direction 1

- I In the Physics toolbar, click **Attributes** and choose **Reversed Current Direction**.
- 2 Select Domains 15, 18, and 27 only.

Coils B

- I In the Model Builder window, right-click Coils A and choose Duplicate.
- 2 In the Settings window for Coil, type Coils B in the Label text field.
- 3 Locate the Domain Selection section. From the Selection list, choose Coils B.
- **4** Locate the **Coil** section. In the  $I_{\text{coil}}$  text field, type I0\*cos(3\*rotation-120[deg]).

Reversed Current Direction I

- I In the Model Builder window, expand the Coils B node, then click Reversed Current Direction 1.
- 2 In the Settings window for Reversed Current Direction, locate the Domain Selection section.
- 3 Click Clear Selection.
- 4 Select Domains 13, 19, and 26 only.

Coils C

- I In the Model Builder window, right-click Coils B and choose Duplicate.
- 2 In the Settings window for Coil, type Coils C in the Label text field.
- 3 Locate the Domain Selection section. From the Selection list, choose Coils C.
- **4** Locate the **Coil** section. In the  $I_{\text{coil}}$  text field, type I0\*cos(3\*rotation-240[deg]).

Reversed Current Direction 1

- I In the Model Builder window, expand the Coils C node, then click Reversed Current Direction 1.
- 2 In the Settings window for Reversed Current Direction, locate the Domain Selection section.
- 3 Click Clear Selection.
- 4 Select Domains 9, 22, and 23 only.

Add a **Continuity** feature to make sure that the electromagnetic fields are continuous through the identity pair.

# Continuity 1

- I In the Physics toolbar, click Pairs and choose Continuity.
- 2 In the Settings window for Continuity, locate the Pair Selection section.
- 3 Under Pairs, click Add.
- 4 In the Add dialog box, select Identity Boundary Pair 2 (ap2) in the Pairs list.
- 5 Click OK.

Add a Force Calculation feature to define the force and torque variables from the rotor and stator.

# Force Calculation Rotor

- I In the Physics toolbar, click **Domains** and choose Force Calculation.
- 2 In the Settings window for Force Calculation, type Force Calculation Rotor in the Label text field.
- 3 Locate the **Domain Selection** section. From the **Selection** list, choose **Rotor**.
- **4** Locate the **Force Calculation** section. In the **Force name** text field, type rot.

# Force Calculation Stator

- I Right-click Force Calculation Rotor and choose Duplicate.
- 2 In the Settings window for Force Calculation, type Force Calculation Stator in the Label text field.
- 3 Locate the **Domain Selection** section. From the **Selection** list, choose **Stator forces**.
- 4 Locate the Force Calculation section. In the Force name text field, type stat.

The Weak Form Boundary PDE physics is used for the single purpose of limiting the output of the model. The forces at the boundaries will be stored from the time dependent analysis and transformed into the frequency domain through a Time to Frequency FFT study step.

# WEAK FORM BOUNDARY PDE (WB)

- I In the Model Builder window, under Component I (compl) click Weak Form Boundary PDE (wb).
- 2 In the Settings window for Weak Form Boundary PDE, locate the Boundary Selection section.
- 3 From the Selection list, choose Force calculation.
- 4 Click to expand the **Discretization** section. From the **Element order** list, choose **Linear**.

- 5 Click to expand the Dependent Variables section. In the Number of dependent variables text field, type 2.
- **6** In the **Dependent variables** table, enter the following settings:

Fx Fy

- 7 Locate the Units section. Click Define Dependent Variable Unit.
- 8 In the Dependent variable quantity table, enter the following settings:

| Dependent variable quantity | Unit  |
|-----------------------------|-------|
| Custom unit                 | N/m^2 |

9 Click Define Source Term Unit.

**10** In the **Source term quantity** table, enter the following settings:

| Source term quantity | Unit  |
|----------------------|-------|
| Custom unit          | N/m^2 |

Fx and Fy take their values from the electromagnetic forces computed through the Force **Calculation** feature. As the rotor is rotating, some coordinate transformation is required.

# Initial Values 1

- I In the Model Builder window, under Component I (compl)> Weak Form Boundary PDE (wb) click Initial Values I.
- 2 In the Settings window for Initial Values, locate the Initial Values section.
- 3 In the Fx text field, type if (isnan(mf.nTx\_stat), mf.nTx\_rot\*cos(rotation)+ mf.nTy rot\*sin(rotation), mf.nTx stat).
- 4 In the Fy text field, type if (isnan(mf.nTy stat), -mf.nTx rot\*sin(rotation)+ mf.nTy\_rot\*cos(rotation),mf.nTy\_stat).

Now proceed to mesh the Component 1.

#### MESH I

- I In the Model Builder window, under Component I (compl) click Mesh I.
- 2 In the Settings window for Mesh, locate the Mesh Settings section.
- 3 From the Sequence type list, choose User-controlled mesh.

#### Size

I In the Model Builder window, under Component I (compl)>Mesh I click Size.

- 2 In the Settings window for Size, locate the Element Size section.
- **3** Click the **Custom** button.
- 4 Locate the Element Size Parameters section. In the Maximum element size text field, type
- 5 In the Minimum element size text field, type 1 [mm].
- 6 In the Maximum element growth rate text field, type 1.15.
- 7 In the Curvature factor text field, type 0.1.

#### Size 1

- I In the Model Builder window, right-click Free Triangular I and choose Size.
- 2 In the Settings window for Size, locate the Geometric Entity Selection section.
- 3 From the Geometric entity level list, choose Boundary.
- 4 From the Selection list, choose Force calculation.
- 5 Locate the Element Size section. Click the Custom button.
- 6 Locate the Element Size Parameters section. Select the Maximum element size check box.
- 7 In the associated text field, type 0.3[mm].
- 8 Select the Minimum element size check box.
- **9** In the associated text field, type 0.15[mm].
- 10 Select the Maximum element growth rate check box.
- II In the associated text field, type 1.05.
- **12** Select the **Curvature factor** check box.
- 13 In the associated text field, type 0.05.
- 14 Click Build All.

Add a **Boundary Layer** feature to make the force calculation more precise.

#### Boundary Layers 1

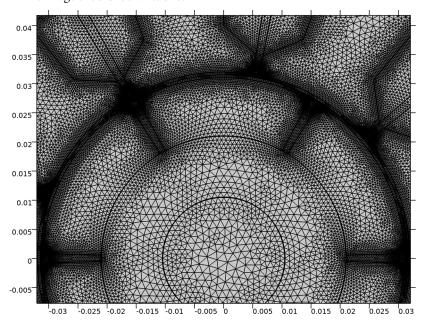
- I In the Mesh toolbar, click Boundary Layers.
- 2 In the Settings window for Boundary Layers, click to expand the Transition section.
- 3 Clear the Smooth transition to interior mesh check box.

# Boundary Layer Properties

- I In the Model Builder window, click Boundary Layer Properties.
- 2 In the Settings window for Boundary Layer Properties, locate the Boundary Selection section.

- 3 From the Selection list, choose Force calculation.
- 4 Locate the Boundary Layer Properties section. In the Number of boundary layers text field, type 1.
- 5 Click Build All.

The image should look like this.



#### STUDY I

Time Dependent

- I In the Study toolbar, click Study Steps and choose Time Dependent> Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- 3 In the Output times text field, type range(0,1/6/n\_harmonics,1)\*t\_tot.
- 4 Locate the Physics and Variables Selection section. In the table, clear the Solve for check box for Weak Form Boundary PDE (wb).
- 5 Click to expand the Values of Dependent Variables section. Find the Initial values of variables solved for subsection. From the Settings list, choose User controlled.
- 6 From the Method list, choose Solution.

- 7 From the Study list, choose Study I, Stationary.
- 8 Click to expand the **Mesh Selection** section. There is no need to use any the mesh coming from the second component.
- **9** In the table, enter the following settings:

| Geometry   | Mesh    |
|------------|---------|
| Geometry 2 | No mesh |

Step 1: Stationary

- I In the Model Builder window, click Step 1: Stationary.
- 2 In the Settings window for Stationary, locate the Physics and Variables Selection section.
- 3 In the table, clear the Solve for check box for Weak Form Boundary PDE (wb).
- 4 Click to expand the **Mesh Selection** section. There is no need to use any the mesh coming from the second component.
- **5** In the table, enter the following settings:

| Geometry   | Mesh    |
|------------|---------|
| Geometry 2 | No mesh |

Change the solver options by showing the default solver.

- 6 In the Model Builder window, click Study 1.
- 7 In the Settings window for Study, type Study 1 Electromagnetic Analysis in the Label text field.

Solution I (soll)

- 2 In the Model Builder window, expand the Solution I (soll) node.
- 3 In the Model Builder window, expand the Study I Electromagnetic Analysis> Solver Configurations>Solution I (soll)>Time-Dependent Solver I node, then click Fully Coupled 1.
- 4 In the Settings window for Fully Coupled, click to expand the Method and Termination section.
- 5 From the Jacobian update list, choose On every iteration. Turning the Jacobian update to every iteration will reduce the running time.
- 6 In the Study toolbar, click = Compute.

#### RESULTS

Magnetic Flux Density Norm (mf)

The following steps guide you through the postprocess of the model.

Study I - Electromagnetic Analysis/Solution I (soll)

In the Model Builder window, expand the Results>Datasets node.

# Surface 1

- I In the Model Builder window, expand the Results>Magnetic Flux Density Norm (mf) node, then click Surface 1.
- 2 In the Settings window for Surface, click to expand the Range section.
- 3 Select the Manual color range check box.
- 4 In the Minimum text field, type 0.
- **5** In the **Maximum** text field, type 1.5.

# Magnetic Flux Density Norm (mf)

- I In the Model Builder window, click Magnetic Flux Density Norm (mf).
- 2 In the Settings window for 2D Plot Group, click to expand the Title section.
- 3 From the Title type list, choose Label.
- 4 Locate the Color Legend section. Clear the Show legends check box.

#### Arrow Line 1

- I Right-click Magnetic Flux Density Norm (mf) and choose Arrow Line.
- 2 In the Settings window for Arrow Line, locate the Expression section.
- 3 In the x component text field, type mf.nTx stat.
- **4** In the **y component** text field, type mf.nTy stat.
- 5 Locate the Arrow Positioning section. From the Placement list, choose Gauss points.
- 6 In the Magnetic Flux Density Norm (mf) toolbar, click Plot.

# Arrow Line 2

- I Right-click Magnetic Flux Density Norm (mf) and choose Arrow Line.
- 2 In the Settings window for Arrow Line, locate the Expression section.
- 3 In the x component text field, type mf.nTx rot.
- **4** In the **y** component text field, type mf.nTy\_rot.
- 5 Locate the Arrow Positioning section. From the Placement list, choose Gauss points.
- **6** Click to expand the **Title** section. From the **Title type** list, choose **None**.

- 7 Locate the Coloring and Style section. From the Color list, choose Blue.
- 8 In the Magnetic Flux Density Norm (mf) toolbar, click **Tool** Plot. Loop through the different frequencies to reproduce the plots in Figure 6

Electromagnetic Forces in Selected Points, Time Domain

- I In the Home toolbar, click **Add Plot Group** and choose ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Electromagnetic Forces in Selected Points, Time Domain in the Label text field.
- 3 Locate the Plot Settings section. Select the y-axis label check box.
- **4** In the associated text field, type Stress (MPa).
- **5** Click to expand the **Title** section. From the **Title type** list, choose **Label**.
- 6 Locate the Legend section. From the Position list, choose Lower right.

#### Point Graph 1

- I Right-click Electromagnetic Forces in Selected Points, Time Domain and choose Point Graph.
- **2** Select Point 174 only.
- 3 In the Settings window for Point Graph, locate the y-Axis Data section.
- 4 In the Expression text field, type abs(mf.nTx stat).
- 5 From the Unit list, choose MPa.
- **6** Select the **Description** check box.
- 7 In the associated text field, type Absolute x stress.
- 8 Click to expand the **Legends** section. Select the **Show legends** check box.
- **9** Find the **Include** subsection. Select the **Description** check box.
- 10 Click to expand the Coloring and Style section. Find the Line markers subsection. From the Marker list, choose Point.
- II From the Positioning list, choose In data points.
- 12 In the Electromagnetic Forces in Selected Points, Time Domain toolbar, click  **Plot**.

#### Point Graph 2

- I Right-click Point Graph I and choose Duplicate.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- 3 In the Expression text field, type abs(mf.nTy stat).
- **4** In the **Description** text field, type Absolute y stress.

## Point Graph 3

- I Right-click Point Graph 2 and choose Duplicate.
- 2 In the Settings window for Point Graph, locate the Selection section.
- 3 Click Clear Selection.
- **4** Select Point 176 only.
- 5 Locate the y-Axis Data section. In the Expression text field, type abs(mf.nTx stat).
- **6** In the **Description** text field, type Absolute x stress.

# Point Graph 4

- I Right-click Point Graph 3 and choose Duplicate.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- 3 In the Expression text field, type abs (mf.nTy stat).
- **4** In the **Description** text field, type Absolute y stress.
- 5 In the Electromagnetic Forces in Selected Points, Time Domain toolbar, click Plot. The image should look like Figure 7.

# Electromagnetic Forces in Selected Points, FFT

- I In the Model Builder window, right-click Electromagnetic Forces in Selected Points, **Time Domain** and choose **Duplicate**.
- 2 In the Model Builder window, click Electromagnetic Forces in Selected Points, Time Domain 1.
- 3 In the Settings window for ID Plot Group, type Electromagnetic Forces in Selected Points, FFT in the Label text field.
- 4 Locate the Plot Settings section. Select the x-axis label check box.
- 5 In the associated text field, type Frequency (Hz).
- 6 In the y-axis label text field, type Fourier Coefficient (MPa).
- 7 Locate the Legend section. From the Position list, choose Upper right.

#### Point Graph 1

- I In the Model Builder window, click Point Graph I.
- 2 In the Settings window for Point Graph, locate the x-Axis Data section.
- 3 From the Parameter list, choose Frequency spectrum.
- 4 Select the Frequency range check box.
- 5 In the Minimum text field, type f0/2.
- 6 In the Maximum text field, type f0\*(n\_harmonics+1).

# Point Graph 2

- I In the Model Builder window, click Point Graph 2.
- 2 In the Settings window for Point Graph, locate the x-Axis Data section.
- 3 From the Parameter list, choose Frequency spectrum.
- 4 Select the Frequency range check box.
- 5 In the Minimum text field, type f0/2.
- 6 In the Maximum text field, type f0\*(n\_harmonics+1).

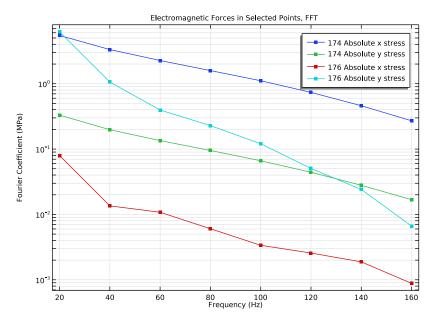
# Point Graph 3

- I In the Model Builder window, click Point Graph 3.
- 2 In the Settings window for Point Graph, locate the x-Axis Data section.
- 3 From the Parameter list, choose Frequency spectrum.
- 4 Select the Frequency range check box.
- 5 In the Minimum text field, type f0/2.
- 6 In the Maximum text field, type f0\*(n harmonics+1).

# Point Graph 4

- I In the Model Builder window, click Point Graph 4.
- 2 In the Settings window for Point Graph, locate the x-Axis Data section.
- 3 From the Parameter list, choose Frequency spectrum.
- 4 Select the Frequency range check box.
- 5 In the Minimum text field, type f0/2.
- 6 In the Maximum text field, type f0\*(n\_harmonics+1).
- 7 Click the y-Axis Log Scale button in the Graphics toolbar.

8 In the Electromagnetic Forces in Selected Points, FFT toolbar, click Plot. The image should look like this.



Electromagnetic Forces in Selected Points, FFT, Normalized to First Harmonic

- In the Model Builder window, right-click Electromagnetic Forces in Selected Points, FFT and choose **Duplicate**.
- 2 In the Settings window for ID Plot Group, type Electromagnetic Forces in Selected Points, FFT, Normalized to First Harmonic in the Label text field.
- 3 Locate the Plot Settings section. In the y-axis label text field, type Normalized Fourier Coefficient (1).
- 4 Locate the Legend section. From the Position list, choose Lower left.

Now proceed to normalize the values using the first harmonic coefficient.

#### Point Graph 1

- I In the Model Builder window, expand the Electromagnetic Forces in Selected Points, FFT, Normalized to First Harmonic node, then click Point Graph 1.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- 3 In the Expression text field, type abs(mf.nTx stat)/5.4675[MPa].

**4** In the **Description** text field, type Absolute x stress normalized to first harmonic.

### Point Graph 2

- I In the Model Builder window, click Point Graph 2.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- 3 In the Expression text field, type abs(mf.nTy\_stat)/0.330696[MPa].
- **4** In the **Description** text field, type Absolute y stress normalized to first harmonic.

#### Point Graph 3

- I In the Model Builder window, click Point Graph 3.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- 3 In the Expression text field, type abs(mf.nTx\_stat)/0.079339[MPa].
- **4** In the **Description** text field, type Absolute x stress normalized to first harmonic.

# Point Graph 4

- I In the Model Builder window, click Point Graph 4.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- 3 In the Expression text field, type abs(mf.nTy\_stat)/6.187[MPa].
- 4 In the Description text field, type Absolute y stress normalized to first harmonic.
- 5 In the Electromagnetic Forces in Selected Points, FFT, Normalized to First Harmonic toolbar, click Plot.

The image should look like Figure 8.

Create a new study to transform the electromagnetic forces to the frequency domain.

#### ROOT

In the **Home** toolbar, click Windows and choose **Add Study**.

#### ADD STUDY

- I Go to the Add Study window.
- 2 Find the Studies subsection. In the Select Study tree, select Empty Study.
- 3 Click Add Study in the window toolbar.
- 4 In the Home toolbar, click Add Study to close the Add Study window.

#### STUDY 2 - ELECTOMAGNETIC FORCES FFT

In the Settings window for Study, type Study 2 - Electomagnetic Forces FFT in the Label text field.

Time to Frequency FFT

- I In the Study toolbar, click Study Steps and choose Frequency Domain> Time to Frequency FFT.
- 2 In the Settings window for Time to Frequency FFT, locate the Study Settings section.
- 3 From the Prescribed by list, choose Initial expression.
- 4 From the Input study list, choose Study I Electromagnetic Analysis, Time Dependent.
- **5** In the **End time** text field, type t tot.
- 6 In the Maximum output frequency text field, type n harmonics/t tot.
- 7 Locate the Physics and Variables Selection section. In the table, clear the Solve for check box for Magnetic Fields (mf).
- 8 In the Study toolbar, click **Compute**.

#### RESULTS

Electromagnetic Forces, FFT

- I In the Settings window for 2D Plot Group, type Electromagnetic Forces, FFT in the Label text field.
- 2 Locate the Plot Settings section. Clear the Plot dataset edges check box.

line l

- I In the Model Builder window, expand the Electromagnetic Forces, FFT node, then click Line I.
- 2 In the Settings window for Line, click to expand the Title section.
- **3** From the **Title type** list, choose **None**.
- 4 Locate the Coloring and Style section. From the Line type list, choose Tube.
- 5 In the Tube radius expression text field, type 0.0002.
- 6 Select the Radius scale factor check box.
- 7 From the Coloring list, choose Uniform.
- 8 From the Color list, choose Black.

Arrow Line 1

I In the Model Builder window, right-click Electromagnetic Forces, FFT and choose Arrow Line.

- 2 In the Settings window for Arrow Line, locate the Expression section.
- 3 In the x component text field, type real(Fx)/t tot.
- **4** In the **y component** text field, type real(Fy)/t tot.
- **5** Select the **Description** check box.
- **6** In the associated text field, type Real Force Components (Red).
- 7 Locate the Arrow Positioning section. From the Placement list, choose Gauss points.
- 8 In the Electromagnetic Forces, FFT toolbar, click **Plot**.

#### Arrow Line 2

- I Right-click Electromagnetic Forces, FFT and choose Arrow Line.
- 2 In the Settings window for Arrow Line, locate the Expression section.
- 3 In the x component text field, type imag(Fx)/t tot.
- 4 In the y component text field, type imag(Fy)/t tot.
- **5** Select the **Description** check box.
- 6 In the associated text field, type Imaginary Force Components (Blue).
- 7 Locate the Arrow Positioning section. From the Placement list, choose Gauss points.
- 8 Locate the Coloring and Style section. From the Color list, choose Blue.
- 9 In the Electromagnetic Forces, FFT toolbar, click  **Plot**. The image should look like Figure 9.

Electromagnetic Forces in Selected Points, FFT, Electromagnetic Forces in Selected Points, FFT, Normalized to First Harmonic, Electromagnetic Forces in Selected Points, Time Domain, Electromagnetic Forces, FFT, Magnetic Flux Density Norm (mf)

- I In the Model Builder window, under Results, Ctrl-click to select Magnetic Flux Density Norm (mf), Electromagnetic Forces in Selected Points, Time Domain, Electromagnetic Forces in Selected Points, FFT, Electromagnetic Forces in Selected Points, FFT, Normalized to First Harmonic, and Electromagnetic Forces, FFT.
- 2 Right-click and choose **Group**.

#### Electromagnetic Results

In the Settings window for Group, type Electromagnetic Results in the Label text field.

# COMPONENT 2 (COMP2)

Add the physics used in the Component 2.

I In the Model Builder window, click Component 2 (comp2).

2 In the Home toolbar, click Windows and choose Add Physics.

#### ADD PHYSICS

- I Go to the Add Physics window.
- 2 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Study I - Electromagnetic Analysis and Study 2 - Electomagnetic Forces FFT.
- 3 In the tree, select Acoustics>Acoustic-Structure Interaction>Acoustic-Solid Interaction, Frequency Domain.
- 4 Click Add to Component 2 in the window toolbar.
- 5 In the Home toolbar, click Add Physics to close the Add Physics window.

# PRESSURE ACOUSTICS, FREQUENCY DOMAIN (ACPR)

- I In the Settings window for Pressure Acoustics, Frequency Domain, locate the **Domain Selection** section.
- 2 From the Selection list, choose Air.

Add the **Exterior Field Calculation** feature to obtain the acoustic field in any distant point.

## Exterior Field Calculation 1

- I Right-click Component 2 (comp2)>Pressure Acoustics, Frequency Domain (acpr) and choose Exterior Field Calculation.
- 2 In the Settings window for Exterior Field Calculation, locate the Boundary Selection section.
- 3 From the Selection list, choose Exterior Field Calculation.
- 4 Locate the Exterior Field Calculation section. From the Condition in the  $z = z^0$  plane list, choose Symmetric/Infinite sound hard boundary.
- **5** In the  $z_0$  text field, type -0.073.

# SOLID MECHANICS (SOLID)

- I In the Model Builder window, under Component 2 (comp2) click Solid Mechanics (solid).
- 2 In the Settings window for Solid Mechanics, locate the Domain Selection section.
- 3 From the Selection list, choose Structure.

#### Fixed Constraint I

- I In the Physics toolbar, click **Boundaries** and choose Fixed Constraint.
- 2 In the Settings window for Fixed Constraint, locate the Boundary Selection section.
- 3 From the Selection list, choose Fixed Boundaries.

Linear Elastic Material I

In the Model Builder window, click Linear Elastic Material 1.

#### Dambing 1

- I In the Physics toolbar, click 🕞 Attributes and choose Damping.
- 2 In the Settings window for Damping, locate the Damping Settings section.
- 3 From the Input parameters list, choose Damping ratios.
- **4** In the  $f_1$  text field, type **f**0.
- **5** In the  $\zeta_1$  text field, type eta\_struct.
- **6** In the  $f_2$  text field, type fmax.
- 7 In the  $\zeta_2$  text field, type eta\_struct.

Use the Boundary Load feature to apply the electromagnetic loads coming from the previous steps. Through the use of the withsol operator, the loads will be taken from the different harmonics of Study 2 and applied to the current physics through a parametric sweep.

# Boundary Load 1

- I In the Physics toolbar, click **Boundaries** and choose **Boundary Load**.
- 2 In the Settings window for Boundary Load, locate the Boundary Selection section.
- 3 From the Selection list, choose Loaded Boundaries. In these expressions, tor(rpm) is the torque-speed normalized curve, comp1.genext1 is the operator that brings variables existing in the Component 1 to Component 2.
- **4** Locate the **Force** section. Specify the  $\mathbf{F}_{\mathbf{A}}$  vector as

| 0   | × |
|---|---|
| <pre>tor(rpm)*comp1.genext1(withsol('sol3',Fx,setval(freq,20[Hz]* (harm_exc))))</pre>   | у |
| <pre>tor(rpm)*comp1.genext1(withsol('sol3',Fy,setval(freq,20[Hz]*   (harm_exc))))</pre> | z |

Add a Continuity feature to make sure that the displacement is continuous through the identity pair.

# Continuity I

- I In the Physics toolbar, click Pairs and choose Continuity.
- 2 In the Settings window for Continuity, locate the Pair Selection section.
- 3 Under Pairs, click Add.

- 4 In the Add dialog box, select Identity Boundary Pair I (ap I) in the Pairs list.
- 5 Click OK.

In the following steps, create a mesh that will minimize the running time while mantaining the accuracy.

#### MESH 2

Free Triangular I

- I In the Mesh toolbar, click A Boundary and choose Free Triangular. Start by meshing a section of the motor.
- 2 In the Settings window for Free Triangular, locate the Boundary Selection section.
- 3 From the Selection list, choose Meshed Section.

## Size

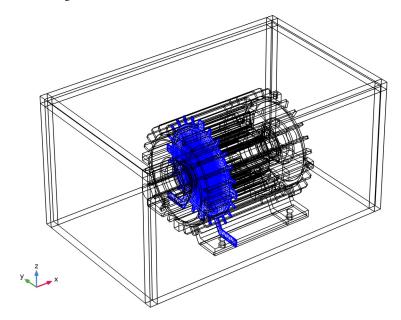
- I In the Model Builder window, click Size.
- 2 In the Settings window for Size, locate the Element Size section.
- **3** Click the **Custom** button.
- 4 Locate the Element Size Parameters section. In the Maximum element size text field, type c0/fmax/5.
- 5 In the Minimum element size text field, type 3[mm].
- 6 Click Build All.

# Size 1

- I In the Model Builder window, right-click Free Triangular I and choose Size.
- 2 In the Settings window for Size, locate the Element Size section.
- **3** Click the **Custom** button.
- 4 Locate the Element Size Parameters section. Select the Maximum element size check box.
- 5 In the associated text field, type 10[mm].
- **6** Select the **Minimum element size** check box.
- 7 In the associated text field, type 0.3 [mm].
- 8 Select the Maximum element growth rate check box.
- **9** In the associated text field, type 1.2.
- 10 Select the Curvature factor check box.
- II In the associated text field, type 0.1.

# 12 Click Build Selected.

The image should look like this.



As the geometry is build using an assembly, it is advisable to copy the mesh so the extrapolation of displacements at the boundary is simpler.

# Copy Face I

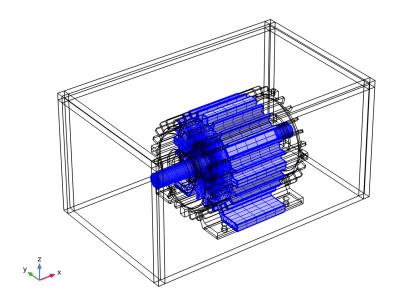
- I In the Mesh toolbar, click Copy and choose Copy Face.
- 2 Select Boundary 431 only.
- 3 In the Settings window for Copy Face, locate the Destination Boundaries section.
- 4 Select the Activate Selection toggle button.
- **5** Select Boundary 916 only.
- 6 Click | Build Selected.

# Swept I

- I In the Mesh toolbar, click & Swept.
- 2 In the Settings window for Swept, locate the Domain Selection section.
- 3 From the Geometric entity level list, choose Domain.
- 4 From the Selection list, choose Sweep Domain.

# 5 Click | Build Selected.

The image should look like this.



# Free Tetrahedral I

- I In the Mesh toolbar, click Free Tetrahedral.
- 2 In the Settings window for Free Tetrahedral, locate the Domain Selection section.
- 3 From the Geometric entity level list, choose Domain.
- 4 From the Selection list, choose Tetrahedral Domains.
- 5 Click **Build Selected**.

# Swept 2

- I In the Mesh toolbar, click & Swept.
- 2 In the Settings window for Swept, locate the Domain Selection section.
- 3 From the Geometric entity level list, choose Domain.
- 4 From the Selection list, choose PML.

#### Distribution I

- I Right-click Swept 2 and choose Distribution.
- 2 In the Settings window for Distribution, locate the Distribution section.

- 3 In the Number of elements text field, type 6.
- 4 Click Build Selected.

# Boundary Layers 1

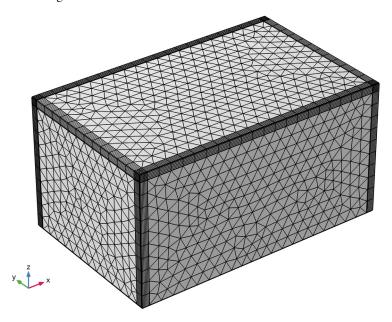
- I In the Mesh toolbar, click Boundary Layers.
- 2 In the Settings window for Boundary Layers, locate the Geometric Entity Selection section.
- 3 From the Geometric entity level list, choose Domain.
- **4** Select Domain 9 only.
- 5 Click to expand the Transition section. Clear the Smooth transition to interior mesh check box.

# Boundary Layer Properties

- I In the Model Builder window, click Boundary Layer Properties.
- 2 In the Settings window for Boundary Layer Properties, locate the Boundary Layer Properties section.
- 3 In the Number of boundary layers text field, type 1.
- 4 Locate the Boundary Selection section. From the Selection list, choose **Exterior Field Calculation.**

# 5 Click | Build Selected.

The image should look like this.



# **DEFINITIONS (COMP2)**

# Variables 2

I In the Model Builder window, under Component 2 (comp2) right-click Definitions and choose Variables.

Add a few variables that will help you to postprocess the model.

- 2 In the Settings window for Variables, locate the Variables section.
- **3** In the table, enter the following settings:

| Name     | Expression  | Unit | Description                          |
|----------|---|------|--------------------------------------|
| rpm      | <pre>acpr.freq/f0*rpm0/ harm_exc</pre>                  | I/s  | Revolutions                          |
| p_mic1   | <pre>subst(abs(acpr.efc1.pex t),x,0,y,0,z,z_mic1)</pre> | Pa   | Absolute pressure at microphone 1    |
| spl_mic1 | <pre>subst(acpr.efc1.Lp_pext ,x,0,y,0,z,z_mic1)</pre>   | dB   | Sound pressure level at microphone 1 |

| Name     | Expression  | Unit | Description                          |
|----------|---|------|--------------------------------------|
| p_mic2   | <pre>subst(abs(acpr.efc1.pex t),x,0,y,y_mic2,z,0)</pre> | Pa   | Absolute pressure at microphone 2    |
| spl_mic2 | <pre>subst(acpr.efc1.Lp_pext ,x,0,y,y_mic2,z,0)</pre>   | dB   | Sound pressure level at microphone 2 |

Add a torque-speed normalized curve.

# Torque curve

- I In the Home toolbar, click f(x) Functions and choose Local>Analytic.
- 2 In the Settings window for Analytic, type Torque curve in the Label text field.
- 3 In the Function name text field, type tor.
- 4 Locate the **Definition** section. In the **Expression** text field, type if (rev<4000,1,4000/ rev).
- 5 In the Arguments text field, type rev.
- **6** Locate the **Units** section. In the **Arguments** text field, type rpm.
- 7 In the Function text field, type 1.
- **8** Locate the **Plot Parameters** section. In the table, enter the following settings:

| Argument | Lower limit | Upper limit |
|----------|-------------|-------------|
| rev      | 0           | 10000[rpm]  |

9 Click Plot.

The image should look like Figure 3.

An acoustic signal will be generated later. This signal is generated as the motor accelerates through time. Proceed to create a revolutions-time curve.

## Revolutions ramp

- I In the Home toolbar, click f(x) Functions and choose Local>Analytic.
- 2 In the Settings window for Analytic, type Revolutions ramp in the Label text field.
- 3 In the Function name text field, type rev\_ramp.
- 4 Locate the **Definition** section. In the **Expression** text field, type 200+9800\*t/20[s].
- 5 In the Arguments text field, type t.
- **6** Locate the **Units** section. In the **Arguments** text field, type **s**.
- 7 In the **Function** text field, type rpm.

**8** Locate the **Plot Parameters** section. In the table, enter the following settings:

| Argument | Lower limit | Upper limit |
|----------|-------------|-------------|
| t        | 0           | 20[s]       |

9 Click To Plot.

The image should look like Figure 5.

Add a Perfectly Matched Layer domain to represent the open domain surrounding the motor.

Perfectly Matched Layer I (pml1)

- I In the Definitions toolbar, click Merfectly Matched Layer.
- 2 In the Settings window for Perfectly Matched Layer, locate the Domain Selection section.
- 3 From the Selection list, choose PML.
- 4 Locate the Scaling section. From the Coordinate stretching type list, choose Rational.

#### MATERIALS

In the Home toolbar, click Windows and choose Add Material from Library.

#### ADD MATERIAL

- I Go to the Add Material window.
- 2 In the tree, select Built-in>Air.
- **3** Click **Add to Component** in the window toolbar.
- 4 In the tree, select Built-in>Steel AISI 4340.
- **5** Click **Add to Component** in the window toolbar.
- 6 In the tree, select Built-in>Aluminum 6063-T83.
- 7 Click Add to Component in the window toolbar.
- 8 In the Home toolbar, click 🤼 Add Material to close the Add Material window.

# MATERIALS

Air (mat6)

- I In the Model Builder window, under Component 2 (comp2)>Materials click Air (mat6).
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- 3 From the Selection list, choose Air.

Steel AISI 4340 (mat7)

- I In the Model Builder window, click Steel AISI 4340 (mat7).
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- **3** From the **Selection** list, choose **Iron**.

Aluminum 6063-T83 (mat8)

- I In the Model Builder window, click Aluminum 6063-T83 (mat8).
- 2 In the Settings window for Material, locate the Geometric Entity Selection section.
- 3 From the Selection list, choose Aluminum.

Coil

- I In the Model Builder window, right-click Materials and choose Blank Material. The coils are made of copper wires. The stiffness of the wire assembly is significantly smaller than that of copper.
- 2 In the Settings window for Material, type Coil in the Label text field.
- 3 Locate the Geometric Entity Selection section. From the Selection list, choose Coils.
- **4** Locate the **Material Contents** section. In the table, enter the following settings:

| Property        | Variable | Value        | Unit  | Property group |
|-----------------|----------|--------------|-------|----------------|
| Young's modulus | E        | 5[GPa]       | Pa    | Basic          |
| Poisson's ratio | nu       | 0.3          | 1     | Basic          |
| Density         | rho      | 8960[kg/m^3] | kg/m³ | Basic          |

## ROOT

In the Home toolbar, click Windows and choose Add Study.

#### ADD STUDY

- I Go to the Add Study window.
- 2 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Magnetic Fields (mf) and Weak Form Boundary PDE (wb).
- 3 Find the Studies subsection. In the Select Study tree, select General Studies> Frequency Domain.
- 4 Click Add Study in the window toolbar.
- 5 In the Model Builder window, click the root node.
- 6 In the Home toolbar, click Add Study to close the Add Study window.

#### STUDY 3

# Step 1: Frequency Domain

This expression gives uniform steps through the sweep up to the maximum revolutions or frequency are reached.

- I In the Settings window for Frequency Domain, locate the Study Settings section.
- 2 In the Frequencies text field, type range (f0\*harm exc, fdelta, min(fmax, rpm max/ rpm0\*f0\*harm exc)) min(fmax,rpm max/rpm0\*f0\*harm exc).
- 3 Click to expand the Values of Dependent Variables section. Find the Store fields in output subsection. From the **Settings** list, choose **For selections**.
- 4 Under Selections, click + Add.
- 5 In the Add dialog box, select Exterior Field Calculation in the Selections list.
- 6 Click OK.
- 7 In the Model Builder window, click Study 3.
- 8 In the Settings window for Study, type Study 3 Vibroacoustic Analysis all Harmonics and Frequencies in the Label text field.
- **9** Locate the **Study Settings** section. Clear the **Generate default plots** check box.

Add a parametric sweep that will sequentially excite the different harmonics.

## Parametric Sweep

- I In the Study toolbar, click Parametric Sweep.
- 2 In the Settings window for Parametric Sweep, locate the Study Settings section.
- 3 Click + Add.
- **4** In the table, enter the following settings:

| Parameter name                | Parameter value list   | Parameter unit |
|-------------------------------|------------------------|----------------|
| harm_exc (Harmonic excited in | range(1,1,n_harmonics) |                |
| the vibroacoustic analysis)   |                        |                |

Change the solver to a segregated solver, where the displacements will be obtained first and then used to compute the acoustic pressure.

# Solution 4 (sol4)

- I In the Study toolbar, click Show Default Solver.
- 2 In the Model Builder window, expand the Solution 4 (sol4) node.

- 3 In the Model Builder window, expand the Study 3 Vibroacoustic Analysis all Harmonics and Frequencies>Solver Configurations>Solution 4 (sol4)> Stationary Solver I node.
- 4 Right-click Stationary Solver I and choose Segregated.
- 5 In the Settings window for Segregated, locate the General section.
- **6** From the Termination technique list, choose Iterations.
- 7 In the Model Builder window, expand the Study 3 Vibroacoustic Analysis all Harmonics and Frequencies>Solver Configurations>Solution 4 (sol4)> Stationary Solver I>Segregated I node, then click Segregated Step.
- 8 In the Settings window for Segregated Step, locate the General section.
- 9 In the Variables list, select Pressure (comp2.p).
- 10 Under Variables, click Delete.
- II In the Model Builder window, right-click Segregated I and choose Segregated Step.
- 12 In the Settings window for Segregated Step, locate the General section.
- 13 Under Variables, click + Add.
- 14 In the Add dialog box, select Pressure (comp2.p) in the Variables list.
- 15 Click OK.
- 16 In the Model Builder window, click Study 3 Vibroacoustic Analysis all Harmonics and Frequencies.
- 17 In the Settings window for Study, locate the Study Settings section.
- **18** Clear the **Generate convergence plots** check box.
  - Due to the many frequencies requested, expect a long runing time.
- 19 In the Study toolbar, click **Compute**.

## RESULTS

- Study 3 Vibroacoustic Analysis all Harmonics and Frequencies/Parametric Solutions I (6) (sol5), Study 3 - Vibroacoustic Analysis - all Harmonics and Frequencies/Solution 4
- (4) (sol4), Study 3 Vibroacoustic Analysis all Harmonics and Frequencies/Solution 4 (5) (sol4)
- I In the Model Builder window, under Results>Datasets, Ctrl-click to select Study 3 -Vibroacoustic Analysis - all Harmonics and Frequencies/Solution 4 (4) (sol4), Study 3 -Vibroacoustic Analysis - all Harmonics and Frequencies/Solution 4 (5) (sol4), and Study 3 -Vibroacoustic Analysis - all Harmonics and Frequencies/Parametric Solutions I (6) (sol5).
- 2 Right-click and choose **Delete**.

Campbell Diagram, First Microphone

- I In the Home toolbar, click **Add Plot Group** and choose ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Campbell Diagram, First Microphone in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 3 Vibroacoustic Analysis all Harmonics and Frequencies/Parametric Solutions I (sol5).
- **4** Locate the **Title** section. From the **Title type** list, choose **Label**.
- 5 Locate the Legend section. Select the Show maximum and minimum values check box.

#### Global I

- I Right-click Campbell Diagram, First Microphone and choose Global.
- 2 In the Settings window for Global, locate the y-Axis Data section.
- **3** In the table, enter the following settings:

| Expression | Unit | Description |
|------------|------|-------------|
| acpr.freq  | Hz   | Frequency   |

- 4 Locate the x-Axis Data section. From the Parameter list, choose Expression.
- **5** In the **Expression** text field, type rpm.
- 6 From the Unit list, choose RPM.
- 7 Click to expand the Coloring and Style section. Set the Width value to 4.
- 8 Click to expand the **Legends** section. Clear the **Show legends** check box.

# Color Expression 1

- I Right-click Global I and choose Color Expression.
- 2 In the Settings window for Color Expression, locate the Expression section.
- **3** In the **Expression** text field, type spl mic1.
- 4 In the Campbell Diagram, First Microphone toolbar, click **Tool** Plot.
- 5 Click to expand the Range section. Select the Manual color range check box.
- 6 In the Minimum text field, type 30.
- 7 In the Maximum text field, type 60.
- 8 In the Campbell Diagram, First Microphone toolbar, click **Tool** Plot.

The image should look like Figure 13.

# Campbell Diagram, Second Microphone

- I In the Model Builder window, right-click Campbell Diagram, First Microphone and choose Duplicate.
- 2 In the Model Builder window, click Campbell Diagram, First Microphone 1.
- 3 In the Settings window for ID Plot Group, type Campbell Diagram, Second Microphone in the Label text field.

# Color Expression 1

- I In the Model Builder window, expand the Results>Campbell Diagram, Second Microphone> Global I node, then click Color Expression I.
- 2 In the Settings window for Color Expression, locate the Expression section.
- **3** In the **Expression** text field, type spl mic2.
- 4 Locate the Range section. In the Maximum text field, type 75.
- 5 In the Campbell Diagram, Second Microphone toolbar, click **Tool** Plot. The image should look like Figure 13.

# Exterior-Field Sound Pressure Level (acpr)

- I In the Home toolbar, click **Add Plot Group** and choose **3D Plot Group**.
- 2 In the Settings window for 3D Plot Group, type Exterior-Field Sound Pressure Level (acpr) in the Label text field.
- 3 Locate the Data section. From the Parameter value (harm\_exc) list, choose 3.
- 4 From the Parameter value (freq (Hz)) list, choose 2360.
- 5 Locate the Color Legend section. Select the Show maximum and minimum values check box.

## Radiation Pattern 1

- In the Exterior-Field Sound Pressure Level (acpr) toolbar, click More Plots and choose Radiation Pattern.
- 2 In the Settings window for Radiation Pattern, locate the Expression section.
- 3 In the Expression text field, type acpr.efc1.Lp pext/80.
- **4** Select the **Description** check box.
- 5 In the associated text field, type Exterior-field sound pressure level.
- **6** Clear the **Use as color expression** check box.
- 7 Click to expand the Range section. Select the Manual color range check box.
- 8 In the Minimum text field, type 40.

- 9 In the Maximum text field, type 65.
- 10 Locate the Evaluation section. Find the Angles subsection. In the Number of elevation angles text field, type 160.
- II In the Number of azimuth angles text field, type 240.
- 12 From the Restriction list, choose Manual.
- **I3** In the  $\theta$  range text field, type 90.
- **I4** In the  $\phi$  start text field, type -90.
- **I5** In the  $\phi$  range text field, type 270.
- 16 Find the Sphere subsection. From the Sphere list, choose Manual.
- 17 In the Radius text field, type 0.5.
- 18 Locate the Coloring and Style section. From the Grid list, choose Fine.
- 19 In the Exterior-Field Sound Pressure Level (acpr) toolbar, click Plot.

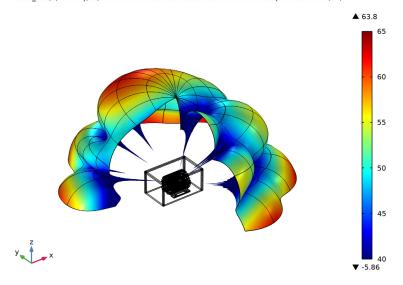
# Exterior-Field Sound Pressure Level (acpr)

- I In the Model Builder window, click Exterior-Field Sound Pressure Level (acpr).
- 2 In the Settings window for 3D Plot Group, locate the Plot Settings section.
- 3 Select the Plot dataset edges check box.
- 4 In the Exterior-Field Sound Pressure Level (acpr) toolbar, click Plot.

**5** Click the **Show Grid** button in the **Graphics** toolbar.

The image should look like this.

harm\_exc(3)=3 freq(47)=2360 Hz Radiation Pattern: Exterior-field sound pressure level (dB)



Campbell Diagram, First Microphone, Campbell Diagram, Second Microphone, Exterior-Field Sound Pressure Level (acpr)

- I In the Model Builder window, under Results, Ctrl-click to select Campbell Diagram, First Microphone, Campbell Diagram, Second Microphone, and Exterior-Field Sound Pressure Level (acpr).
- 2 Right-click and choose Group.

Vibroacoustic Results - all Harmonics and Frequencies

In the Settings window for Group, type Vibroacoustic Results - all Harmonics and Frequencies in the Label text field.

Pressure - Revolutions - 1st Harmonic

- I In the Results toolbar, click **Evaluation Group**.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 1st Harmonic in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 3 Vibroacoustic Analysis all Harmonics and Frequencies/Parametric Solutions I (sol5).
- 4 From the Parameter selection (harm\_exc) list, choose From list.

- 5 In the Parameter values (harm\_exc) list, select 1.
- **6** Click to expand the **Format** section. From the **Include parameters** list, choose **Off**.

Global Evaluation 1

- I Right-click Pressure Revolutions 1st Harmonic and choose Global Evaluation.
- 2 In the Settings window for Global Evaluation, locate the Expressions section.
- **3** In the table, enter the following settings:

| Expression   | Unit | Description                                    |
|--|------|--|
| rpm  | RPM  | Regime for the excited harmonic                |
| <pre>subst(real(acpr.efc1.pext),x, 0.1[m],y,y_mic2,z,0)</pre>  | Ра   | Absolute pressure at microphone 2 - Left Real  |
| <pre>subst(imag(acpr.efc1.pext),x, 0.1[m],y,y_mic2,z,0)</pre>  | Ра   | Absolute pressure at microphone 2 - Left Imag  |
| <pre>subst(real(acpr.efc1.pext),x,- 0.1[m],y,y_mic2,z,0)</pre> | Ра   | Absolute pressure at microphone 2 - Right Real |
| <pre>subst(imag(acpr.efc1.pext),x,- 0.1[m],y,y_mic2,z,0)</pre> | Ра   | Absolute pressure at microphone 2 - Right Imag |

4 In the Pressure - Revolutions - 1st Harmonic toolbar, click **= Evaluate**.

Pressure - Revolutions - 2nd Harmonic

- I In the Model Builder window, right-click Pressure Revolutions 1st Harmonic and choose **Duplicate**.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 2nd Harmonic in the **Label** text field.
- 3 Locate the Data section. In the Parameter values (harm\_exc) list, select 2.
- 4 In the Pressure Revolutions 2nd Harmonic toolbar, click **=** Evaluate.

#### TABLE

Go to the **Table** window.

Pressure - Revolutions - 3rd Harmonic

- I Right-click Pressure Revolutions 2nd Harmonic and choose Duplicate.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 3rd Harmonic in the Label text field.
- 3 Locate the Data section. In the Parameter values (harm\_exc) list, select 3.
- 4 In the Pressure Revolutions 3rd Harmonic toolbar, click **=** Evaluate.

5 Go to the Table window.

Pressure - Revolutions - 4th Harmonic

- I Right-click Pressure Revolutions 3rd Harmonic and choose Duplicate.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 4th Harmonic in the Label text field.
- 3 Locate the Data section. In the Parameter values (harm\_exc) list, select 4.
- 4 In the Pressure Revolutions 4th Harmonic toolbar, click **Evaluate**.
- **5** Go to the **Table** window.

Pressure - Revolutions - 5th Harmonic

- I Right-click Pressure Revolutions 4th Harmonic and choose Duplicate.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 5th Harmonic in the Label text field.
- 3 Locate the Data section. In the Parameter values (harm\_exc) list, select 5.
- 4 In the Pressure Revolutions 5th Harmonic toolbar, click **Evaluate**.
- **5** Go to the **Table** window.

Pressure - Revolutions - 6th Harmonic

- I Right-click Pressure Revolutions 5th Harmonic and choose Duplicate.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 6th Harmonic in the Label text field.
- 3 Locate the Data section. In the Parameter values (harm\_exc) list, select 6.
- 4 In the Pressure Revolutions 6th Harmonic toolbar, click **Evaluate**.
- **5** Go to the **Table** window.

Pressure - Revolutions - 7th Harmonic

- I Right-click Pressure Revolutions 6th Harmonic and choose Duplicate.
- 2 In the Settings window for Evaluation Group, type Pressure Revolutions 7th Harmonic in the Label text field.
- 3 Locate the Data section. In the Parameter values (harm\_exc) list, select 7.
- 4 In the Pressure Revolutions 7th Harmonic toolbar, click **=** Evaluate.

Pressure - Revolutions - 1st Harmonic, Pressure - Revolutions - 2nd Harmonic, Pressure - Revolutions - 3rd Harmonic, Pressure - Revolutions - 4th Harmonic, Pressure -

Revolutions - 5th Harmonic, Pressure - Revolutions - 6th Harmonic, Pressure -Revolutions - 7th Harmonic

- I In the Model Builder window, under Results, Ctrl-click to select Pressure Revolutions -Ist Harmonic, Pressure - Revolutions - 2nd Harmonic, Pressure - Revolutions -3rd Harmonic, Pressure - Revolutions - 4th Harmonic, Pressure - Revolutions -5th Harmonic, Pressure - Revolutions - 6th Harmonic, and Pressure - Revolutions -7th Harmonic.
- 2 Right-click and choose **Group**.

Acoustic Signal

In the **Settings** window for **Group**, type Acoustic Signal in the **Label** text field.

# **DEFINITIONS (COMP2)**

In the Model Builder window, under Component 2 (comp2) click Definitions.

Interpolation I (int I)

- I In the Home toolbar, click f(X) Functions and choose Local>Interpolation.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Data source list, choose Result table.
- **4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real1_l       | 1                |
| imag1_l       | 2                |
| real1_r       | 3                |
| imag1_r       | 4                |

- 5 Locate the Interpolation and Extrapolation section. From the Interpolation list, choose Piecewise cubic.
- 6 From the Extrapolation list, choose Specific value.
- 7 Locate the Units section. In the Arguments text field, type RPM.
- 8 In the Function text field, type Pa.
- 9 Click Plot.

Interpolation 2 (real | \_I, imag | \_I, ...)

- I Right-click Interpolation I (intl) and choose Duplicate.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Table from list, choose Pressure Revolutions 2nd Harmonic.

**4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real2_1       | 1                |
| imag2_l       | 2                |
| real2_r       | 3                |
| imag2_r       | 4                |

5 Click Plot.

Interpolation 3 (real2\_I, imag2\_I, ...)

- I Right-click Interpolation 2 (real I\_I, imag I\_I, ...) and choose Duplicate.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Table from list, choose Pressure Revolutions 3rd Harmonic.
- **4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real3_1       | 1                |
| imag3_l       | 2                |
| real3_r       | 3                |
| imag3_r       | 4                |

5 Click Plot.

Interpolation 4 (real3\_I, imag3\_I, ...)

- I Right-click Interpolation 3 (real2\_I, imag2\_I, ...) and choose Duplicate.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Table from list, choose Pressure Revolutions 4th Harmonic.
- **4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real4_1       | 1                |
| imag4_l       | 2                |
| real4_r       | 3                |
| imag4_r       | 4                |

5 Click Plot.

Interpolation 5 (real4\_I, imag4\_I, ...)

- I Right-click Interpolation 4 (real3\_I, imag3\_I, ...) and choose Duplicate.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Table from list, choose Pressure Revolutions 5th Harmonic.
- **4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real5_l       | 1                |
| imag5_l       | 2                |
| real5_r       | 3                |
| imag5_r       | 4                |

5 Click Plot.

Interpolation 6 (real5\_I, imag5\_I, ...)

- I Right-click Interpolation 5 (real4\_I, imag4\_I, ...) and choose Duplicate.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Table from list, choose Pressure Revolutions 6th Harmonic.
- **4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real6_l       | 1                |
| imag6_l       | 2                |
| real6_r       | 3                |
| imag6_r       | 4                |

5 Click Plot.

Interpolation 7 (real6\_l, imag6\_l, ...)

- I Right-click Interpolation 6 (real5\_I, imag5\_I, ...) and choose Duplicate.
- 2 In the Settings window for Interpolation, locate the Definition section.
- 3 From the Table from list, choose Pressure Revolutions 7th Harmonic.
- **4** Find the **Functions** subsection. In the table, enter the following settings:

| Function name | Position in file |
|---------------|------------------|
| real7_l       | 1                |
| imag7_l       | 2                |

| Function name | Position in file |
|---------------|------------------|
| real7_r       | 3                |
| imag7_r       | 4                |

5 Click **Plot**.

Interpolation I (real I\_I, imag I\_I, ...), Interpolation 2 (real 2\_I, imag 2\_I, ...), Interpolation 3 (real3\_I, imag3\_I, ...), Interpolation 4 (real4\_I, imag4\_I, ...), Interpolation 5 (real5\_I, imag5\_l, ...), Interpolation 6 (real6\_l, imag6\_l, ...), Interpolation 7 (real7\_l, imag7\_l, ...)

- I In the Model Builder window, under Component 2 (comp2)>Definitions, Ctrl-click to select Interpolation I (realI\_I, imagI\_I, ...), Interpolation 2 (real2\_I, imag2\_I, ...), Interpolation 3 (real3\_I, imag3\_I, ...), Interpolation 4 (real4\_I, imag4\_I, ...), Interpolation 5 (real5\_I, imag5\_I, ...), Interpolation 6 (real6\_I, imag6\_I, ...), and Interpolation 7 (real7\_I, imag7\_I, ...).
- 2 Right-click and choose **Group**.

Acoustic Signal

In the Settings window for Group, type Acoustic Signal in the Label text field.

#### ROOT

In the **Home** toolbar, click Windows and choose **Add Study**.

#### ADD STUDY

- I Go to the Add Study window.
- 2 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Magnetic Fields (mf) and Weak Form Boundary PDE (wb).
- 3 Find the Studies subsection. In the Select Study tree, select General Studies> Frequency Domain.
- 4 Click Add Study in the window toolbar.
- 5 In the Model Builder window, click the root node.
- 6 In the Home toolbar, click Add Study to close the Add Study window.

## STUDY 4

Steb 1: Frequency Domain

- I In the Settings window for Frequency Domain, locate the Study Settings section.
- 2 In the Frequencies text field, type 2360.
- 3 In the Model Builder window, click Study 4.

- 4 In the Settings window for Study, type Study 4 Vibroacoustic Analysis 3rd Harmonic 2360 Hz in the Label text field.
- 5 Locate the Study Settings section. Clear the Generate default plots check box.
- **6** Clear the **Generate convergence plots** check box.

Change the solver to a segregated solver, where the displacements will be obtained first and then used to compute the acoustic pressure.

Solution 13 (sol13)

- 2 In the Model Builder window, expand the Solution 13 (sol13) node.
- 3 In the Model Builder window, expand the Study 4 Vibroacoustic Analysis -3rd Harmonic 2360 Hz>Solver Configurations>Solution 13 (sol13)>Stationary Solver I node.
- 4 Right-click Stationary Solver I and choose Segregated.
- 5 In the Settings window for Segregated, locate the General section.
- 6 From the Termination technique list, choose Iterations.
- 7 In the Model Builder window, expand the Study 4 Vibroacoustic Analysis -3rd Harmonic 2360 Hz>Solver Configurations>Solution 13 (sol13)>Stationary Solver I> Segregated I node, then click Segregated Step.
- 8 In the Settings window for Segregated Step, locate the General section.
- 9 In the Variables list, select Pressure (comp2.p).
- 10 Under Variables, click Delete.
- II In the Model Builder window, right-click Segregated I and choose Segregated Step.
- 12 In the Settings window for Segregated Step, locate the General section.
- 13 Under Variables, click + Add.
- 14 In the Add dialog box, select Pressure (comp2.p) in the Variables list.
- I5 Click OK.
- **16** In the **Study** toolbar, click **Compute**.

#### RESULTS

Study 4 - Vibroacoustic Analysis - 3rd Harmonic 2360 Hz/Solution 13 (sol13)

In the Model Builder window, under Results>Datasets right-click Study 4 -

Vibroacoustic Analysis - 3rd Harmonic 2360 Hz/Solution 13 (sol13) and choose Delete.

#### Grid ID I

- I In the Results toolbar, click More Datasets and choose Grid>Grid ID.
- 2 In the Settings window for Grid ID, locate the Data section.
- 3 From the Dataset list, choose Study 4 Vibroacoustic Analysis 3rd Harmonic 2360 Hz/ Solution 13 (sol13).
- **4** Locate the **Parameter Bounds** section. In the **Name** text field, type tt.
- 5 In the Maximum text field, type 20.
- **6** Click to expand the **Resolution** section. In the **Resolution** text field, type 960000.
- 7 Clear the **Adaptive** check box.

# Acoustic Signal

- I In the Results toolbar, click  $\sim$  ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Acoustic Signal in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Grid ID 1.
- 4 Locate the Title section. From the Title type list, choose Label.
- **5** Locate the **Plot Settings** section. Select the **y-axis label** check box.
- **6** In the associated text field, type Signal (Pa).

## Left Channel

- I Right-click Acoustic Signal and choose Line Graph.
- 2 In the Settings window for Line Graph, type Left Channel in the Label text field.
- 3 Locate the y-Axis Data section. Select the Description check box.
- **4** In the associated text field, type Left Channel.
- 5 In the Expression text field, type real((real1 l(rev ramp(tt))+i\* imag1 l(rev ramp(tt)))\*exp(i\*(rev ramp(tt))\*f0/rpm0\*1\*pi\*tt)+ (real2\_1(rev\_ramp(tt))+i\*imag2\_1(rev\_ramp(tt)))\*exp(i\* (rev ramp(tt))\*f0/rpm0\*2\*pi\*tt)+(real3 1(rev ramp(tt))+i\* imag3\_l(rev\_ramp(tt)))\*exp(i\*(rev\_ramp(tt))\*f0/rpm0\*3\*pi\*tt)+ (real4\_l(rev\_ramp(tt))+i\*imag4\_l(rev\_ramp(tt)))\*exp(i\* (rev ramp(tt))\*f0/rpm0\*4\*pi\*tt)+(real5 l(rev ramp(tt))+i\* imag5\_l(rev\_ramp(tt)))\*exp(i\*(rev\_ramp(tt))\*f0/rpm0\*5\*pi\*tt)+ (real6\_1(rev\_ramp(tt))+i\*imag6\_1(rev\_ramp(tt)))\*exp(i\* (rev ramp(tt))\*f0/rpm0\*6\*pi\*tt)+(real7 1(rev ramp(tt))+i\*  $imag7 \ l(rev \ ramp(tt)))*exp(i*(rev \ ramp(tt))*f0/rpm0*7*pi*tt)).$
- 6 Locate the x-Axis Data section. From the Parameter list, choose Expression.

- 7 In the Expression text field, type tt[s/m].
- **8** Select the **Description** check box.
- **9** In the associated text field, type time.
- 10 Click to expand the Legends section. Select the Show legends check box.
- II From the Legends list, choose Manual.
- **12** In the table, enter the following settings:

# Legends Left Channel

13 In the Acoustic Signal toolbar, click Plot.

# Right Channel

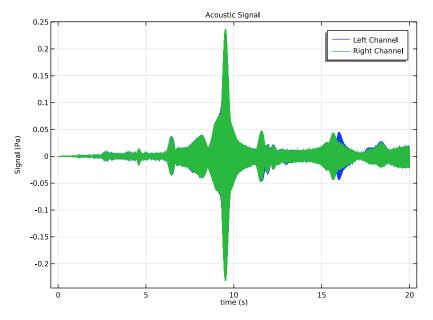
- I Right-click Left Channel and choose Duplicate.
- 2 In the Settings window for Line Graph, locate the y-Axis Data section.
- 3 In the **Description** text field, type Right Channel.
- 4 In the Expression text field, type real((real1 r(rev ramp(tt))+i\* imag1 r(rev ramp(tt)))\*exp(i\*(rev ramp(tt))\*f0/rpm0\*1\*pi\*tt)+ (real2\_r(rev\_ramp(tt))+i\*imag2\_r(rev\_ramp(tt)))\*exp(i\* (rev ramp(tt))\*f0/rpm0\*2\*pi\*tt)+(real3 r(rev ramp(tt))+i\* imag3 r(rev ramp(tt)))\*exp(i\*(rev ramp(tt))\*f0/rpm0\*3\*pi\*tt)+ (real4 r(rev ramp(tt))+i\*imag4 r(rev ramp(tt)))\*exp(i\* (rev ramp(tt))\*f0/rpm0\*4\*pi\*tt)+(real5 r(rev ramp(tt))+i\* imag5 r(rev ramp(tt)))\*exp(i\*(rev ramp(tt))\*f0/rpm0\*5\*pi\*tt)+ (real6\_r(rev\_ramp(tt))+i\*imag6\_r(rev\_ramp(tt)))\*exp(i\* (rev\_ramp(tt))\*f0/rpm0\*6\*pi\*tt)+(real7\_r(rev\_ramp(tt))+i\* imag7\_r(rev\_ramp(tt))) \*exp(i\*(rev\_ramp(tt)) \*f0/rpm0\*7\*pi\*tt)).
- 5 In the Label text field, type Right Channel.
- **6** Locate the **Legends** section. In the table, enter the following settings:

#### Legends

Right Channel

7 In the Acoustic Signal toolbar, click Plot.

The image should look like this.



Left Channel Acoustic Signal

- I In the Model Builder window, under Results>Vibroacoustic Results all Harmonics and Frequencies>Acoustic Signal right-click Left Channel and choose Add Plot Data to Export.
- 2 In the Settings window for Plot, type Left Channel Acoustic Signal in the Label text field.
- 3 Locate the Output section. From the File type list, choose WAVE audio file (\*.wav).
- 4 In the Filename text field, type electric motor noise left.wav. Click on export to produce a way file with the acoustic signal at the left channel.

#### Right Channel Acoustic Signal

- I In the Model Builder window, under Results>Vibroacoustic Results all Harmonics and Frequencies>Acoustic Signal right-click Right Channel and choose Add Plot Data to Export.
- 2 In the Settings window for Plot, type Right Channel Acoustic Signal in the Label text field.
- 3 Locate the Output section. From the File type list, choose WAYE audio file (\*.wav).

4 In the Filename text field, type electric motor noise right.wav. Click on export to produce a way file with the acoustic signal at the right channel.

# Displacement and acoustic pressure

- I In the Home toolbar, click **Add Plot Group** and choose **3D Plot Group**.
- 2 In the Settings window for 3D Plot Group, type Displacement and acoustic pressure in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 4 Vibroacoustic Analysis -3rd Harmonic 2360 Hz/Solution 13 (sol13).
- **4** Locate the **Plot Settings** section. Clear the **Plot dataset edges** check box.
- 5 Locate the Color Legend section. Select the Show maximum and minimum values check box.

# Surface 1

- I Right-click Displacement and acoustic pressure and choose Surface.
- 2 In the Settings window for Surface, locate the Expression section.
- **3** In the **Expression** text field, type solid.disp.

# Deformation I

Right-click Surface I and choose Deformation.

#### Filter I

- I In the Model Builder window, right-click Surface I and choose Filter.
- 2 In the Settings window for Filter, locate the Element Selection section.
- 3 In the Logical expression for inclusion text field, type x>-40.5[mm].
- 4 In the Displacement and acoustic pressure toolbar, click **Tool** Plot.

#### Line 1

- I In the Model Builder window, right-click Displacement and acoustic pressure and choose Line.
- 2 In the Settings window for Line, locate the Expression section.
- **3** In the **Expression** text field, type **0**.
- 4 Click to expand the **Title** section. From the **Title type** list, choose **None**.
- 5 Locate the Coloring and Style section. From the Coloring list, choose Uniform.
- 6 From the Color list, choose Black.

#### Deformation I

In the Model Builder window, right-click Deformation I and choose Copy.

# Deformation I

In the Model Builder window, right-click Line I and choose Paste Deformation.

In the Model Builder window, right-click Filter I and choose Copy.

In the Model Builder window, right-click Line I and choose Paste Filter.

#### Line 1

- I In the Settings window for Line, click to expand the Inherit Style section.
- 2 From the Plot list, choose Surface 1.
- **3** Clear the **Color** check box.
- 4 Clear the Color and data range check box.
- 5 In the Displacement and acoustic pressure toolbar, click **1** Plot.

# Isosurface I

- I In the Model Builder window, right-click Displacement and acoustic pressure and choose Isosurface.
- 2 In the Settings window for Isosurface, locate the Levels section.
- 3 In the Total levels text field, type 11.
- 4 Locate the Coloring and Style section. From the Color table list, choose Wave.
- 5 Select the Symmetrize color range check box.

#### Selection 1

- I Right-click Isosurface I and choose Selection.
- 2 Select Domain 9 only.

#### Filter I

In the Model Builder window, right-click Filter I and choose Copy.

#### Filter 1

In the Model Builder window, right-click Isosurface I and choose Paste Filter.

# Displacement and acoustic pressure

I In the Displacement and acoustic pressure toolbar, click **Tool** Plot.

The image should look like Figure 11.

# SPL and Radiation Pattern

I In the Home toolbar, click **Add Plot Group** and choose **3D Plot Group**.

- 2 In the Settings window for 3D Plot Group, type SPL and Radiation Pattern in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 4 Vibroacoustic Analysis -3rd Harmonic 2360 Hz/Solution 13 (sol13).
- 4 Click to expand the Selection section. From the Geometric entity level list, choose Domain.
- **5** From the **Selection** list, choose **Structure**.
- **6** Locate the **Plot Settings** section. Clear the **Plot dataset edges** check box.

# Surface I

- I Right-click SPL and Radiation Pattern and choose Surface.
- 2 In the Settings window for Surface, locate the Expression section.
- 3 In the Expression text field, type acpr.Lp.
- 4 Click to expand the Range section. Select the Manual color range check box.
- 5 In the Minimum text field, type 50.
- 6 In the Maximum text field, type 85.

# Deformation I

Right-click Surface I and choose Deformation.

#### line l

- I In the Model Builder window, right-click SPL and Radiation Pattern and choose Line.
- 2 In the Settings window for Line, locate the Expression section.
- **3** In the **Expression** text field, type **0**.
- **4** Locate the **Title** section. From the **Title type** list, choose **None**.
- 5 Locate the Coloring and Style section. From the Coloring list, choose Uniform.
- 6 From the Color list, choose Black.
- 7 Locate the Inherit Style section. From the Plot list, choose Surface 1.
- 8 Clear the **Color** check box.
- **9** Clear the Color and data range check box.

# Deformation I

Right-click Line I and choose Deformation.

#### Radiation Pattern 1

I In the Model Builder window, expand the Results>Vibroacoustic Results all Harmonics and Frequencies>Exterior-Field Sound Pressure Level (acpr) node. 2 Right-click Radiation Pattern I and choose Copy.

#### Radiation Pattern I

- I In the Model Builder window, right-click SPL and Radiation Pattern and choose Paste Radiation Pattern.
- 2 In the Settings window for Radiation Pattern, locate the Evaluation section.
- **3** Find the **Angles** subsection. In the  $\phi$  range text field, type 360.

# Transbarency 1

- I Right-click Radiation Pattern I and choose Transparency.
- 2 Click the **Zoom Extents** button in the **Graphics** toolbar.

The image should look like Figure 12.

# Boundary Loads

- I In the Home toolbar, click **Add Plot Group** and choose 3D Plot Group.
- 2 In the Settings window for 3D Plot Group, type Boundary Loads in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 4 Vibroacoustic Analysis -3rd Harmonic 2360 Hz/Solution 13 (sol13).
- 4 Locate the Selection section. From the Geometric entity level list, choose Domain.
- **5** From the **Selection** list, choose **Structure**.
- 6 Select the Apply to dataset edges check box.

# Arrow Surface 1

- I Right-click Boundary Loads and choose Arrow Surface.
- 2 In the Settings window for Arrow Surface, locate the Expression section.
- 3 In the X component text field, type solid.bndl1.F\_Ax.
- **4** In the **Y** component text field, type solid.bndl1.F Ay.
- **5** In the **Z** component text field, type solid.bndl1.F Az.
- 6 Locate the Arrow Positioning section. From the Placement list, choose Gauss points.

# Color Expression 1

- I Right-click Arrow Surface I and choose Color Expression.
- 2 In the Settings window for Color Expression, locate the Expression section.
- 3 In the Expression text field, type comp2.solid.bndl1.F\_A\_Mag.
- 4 Locate the Coloring and Style section. From the Coloring list, choose Gradient.
- **5** From the **Top color** list, choose **Red**.

- 6 Click the Orthographic Projection button in the Graphics toolbar.
- 7 Click the YZ Go to YZ View button in the Graphics toolbar. The image should look like Figure 10.

Boundary Loads, Displacement and acoustic pressure, SPL and Radiation Pattern

- I In the Model Builder window, under Results, Ctrl-click to select Displacement and acoustic pressure, SPL and Radiation Pattern, and Boundary Loads.
- 2 Right-click and choose **Group**.

Vibroacoustic Results - 3rd Harmonic 2360 Hz

In the Settings window for Group, type Vibroacoustic Results - 3rd Harmonic 2360 Hz in the Label text field.

# Geometry Sequence Instructions

From the File menu, choose New.

#### NEW

In the New window, click Model Wizard.

#### MODEL WIZARD

- I In the Model Wizard window, click **3D**.
- 2 Click M Done.

#### **GLOBAL DEFINITIONS**

Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- 3 Click Load from File.
- 4 Browse to the model's Application Libraries folder and double-click the file electric\_motor\_noise\_pmsm\_geom\_sequence\_parameters.txt.

#### GEOMETRY I

Import I (impl)

I In the **Home** toolbar, click **— Import**.

- 2 In the Settings window for Import, locate the Import section.
- 3 From the Source list, choose COMSOL Multiphysics file.
- 4 Click Browse.
- **5** Browse to the model's Application Libraries folder and double-click the file electric\_motor\_noise\_pmsm\_geom\_sequence.mphbin.
- 6 Click Import.
- 7 Click the Wireframe Rendering button in the Graphics toolbar.

Work Plane I (wbl)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane list, choose yz-plane.
- 4 From the Offset type list, choose Through vertex.
- **5** Find the **Offset vertex** subsection. Select the **Activate Selection** toggle button.
- 6 On the object imp1, select Point 372 only.

Work Plane I (wpl)>Plane Geometry

In the Model Builder window, click Plane Geometry.

Work Plane I (wpl)>Circle I (cl)

- I In the Work Plane toolbar, click Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type r\_stator.
- 4 Click to expand the Layers section. In the table, enter the following settings:

| Layer name Thickness (m) |                      |
|--------------------------|----------------------|
| Layer 1 th_out_stator    |                      |
| Layer 2                  | h_stat-th_out_stator |
| Layer 3                  | air_gap/2            |

5 Click Pauld Selected.

Work Plane I (wpl)>Polygon I (poll)

- I In the Work Plane toolbar, click / Polygon.
- 2 In the Settings window for Polygon, locate the Coordinates section.

**3** In the table, enter the following settings:

| xw (m)  | yw (m)   |
|---|--|
| (r_stator-h_stat+th_in_stator)  | 0  |
| <pre>(r_stator-h_stat+th_in_stator+ h_coil_angle)*cos(-angle_coil/2)</pre>    | <pre>(r_stator-h_stat+th_in_stator+<br/>h_coil_angle)*sin(-angle_coil/2)</pre> |
| <pre>(r_stator-th_out_stator)*cos(- angle_coil/2)</pre>                       | <pre>(r_stator-th_out_stator)*sin(- angle_coil/2)</pre>                        |
| (r_stator-th_out_stator/2)  | 0  |
| <pre>(r_stator-th_out_stator)* cos(angle_coil/2)</pre>                        | <pre>(r_stator-th_out_stator)* sin(angle_coil/2)</pre>                         |
| <pre>(r_stator-h_stat+th_in_stator+<br/>h_coil_angle)*cos(angle_coil/2)</pre> | <pre>(r_stator-h_stat+th_in_stator+<br/>h_coil_angle)*sin(angle_coil/2)</pre>  |

# 4 Click | Build Selected.

Work Plane I (wpl)>Polygon 2 (pol2)

- I In the Work Plane toolbar, click / Polygon.
- 2 In the Settings window for Polygon, locate the Coordinates section.
- **3** In the table, enter the following settings:

| xw (m)   | yw (m)   |
|--|--|
| <pre>(r_stator-h_stat)*cos(- angle_teeth_gap/2)</pre>        | <pre>(r_stator-h_stat)*sin(- angle_teeth_gap/2)</pre>        |
| <pre>(r_stator-th_out_stator)*cos(- angle_teeth_gap/2)</pre> | <pre>(r_stator-th_out_stator)*sin(- angle_teeth_gap/2)</pre> |
| <pre>(r_stator-th_out_stator)*cos(+ angle_teeth_gap/2)</pre> | <pre>(r_stator-th_out_stator)*sin(+ angle_teeth_gap/2)</pre> |
| <pre>(r_stator-h_stat)*cos(+ angle_teeth_gap/2)</pre>        | <pre>(r_stator-h_stat)*sin(+ angle_teeth_gap/2)</pre>        |

4 Click Pauld Selected.

Work Plane I (wpI)>Union I (uniI)

- I In the Work Plane toolbar, click Booleans and Partitions and choose Union.
- 2 Select the objects poll and pol2 only.
- 3 In the Settings window for Union, click 📔 Build Selected.

Work Plane I (wp I)>Delete Entities I (del I)

- I Right-click Plane Geometry and choose Delete Entities.
- 2 On the object c1, select Boundaries 1–12 only.

- 3 On the object unil, select Boundaries 1, 4, 5, and 12–14 only.
- 4 In the Settings window for Delete Entities, click | Build Selected.

Work Plane I (wbl)>Rotate I (rot1)

- I In the Work Plane toolbar, click \( \sum\_{\text{int}} \) Transforms and choose Rotate.
- 2 Select the object dell(2) only.
- 3 In the Settings window for Rotate, locate the Rotation section.
- 4 In the Angle text field, type range  $(360/(3*n\_sectors), 360/(3*n\_sectors), 360)$ .
- 5 Click **Build Selected**.

Work Plane I (wb I)>Union 2 (uni2)

- I In the Work Plane toolbar, click Booleans and Partitions and choose Union.
- 2 Click in the **Graphics** window and then press Ctrl+A to select all objects.
- 3 In the Settings window for Union, click | Build Selected.

Work Plane I (wb I)>Delete Entities 2 (del2)

- I Right-click Plane Geometry and choose Delete Entities.
- 2 On the object uni2, select Boundaries 75, 76, 83, 84, 91, 92, 99–102, 113, 114, 121– 124, 127, 128, 135, and 136 only.
- 3 In the Settings window for Delete Entities, click 🖺 Build Selected.

Work Plane I (wb I)>Delete Entities 3 (del3)

- I Right-click Plane Geometry and choose Delete Entities.
- 2 In the Settings window for Delete Entities, locate the Entities or Objects to Delete section.
- 3 From the Geometric entity level list, choose Domain.
- 4 On the object del2, select Domain 21 only.
- 5 Click **Build Selected**.

Work Plane I (wbl)>Fillet I (fill)

- I In the Work Plane toolbar, click Fillet.
- 2 On the object del3, select Points 22–25, 38–41, 54, 55, 58, 59, 70–73, 81, and 82 only.
- 3 In the Settings window for Fillet, locate the Radius section.
- 4 In the Radius text field, type fillet.
- 5 Click | Build Selected.

Extrude I (ext I)

- I In the Model Builder window, under Component I (compl)>Geometry I right-click Work Plane I (wpI) and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- 3 From the Specify list, choose Vertices to extrude to.
- 4 On the object imp1, select Point 490 only.
- 5 Click | Build Selected.

Union I (uni I)

- I In the Geometry toolbar, click Booleans and Partitions and choose Union.
- 2 Click in the **Graphics** window and then press Ctrl+A to select both objects.
- 3 In the Settings window for Union, click **Parallel Build Selected**.

Work Plane 2 (wb2)

- I In the Geometry toolbar, click Swork Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane list, choose yz-plane.
- 4 From the Offset type list, choose Through vertex.
- **5** Find the **Offset vertex** subsection. Select the **Selection Activate Selection** toggle button.
- 6 On the object unil, select Point 422 only.

Work Plane 2 (wp2)>Plane Geometry

In the Model Builder window, click Plane Geometry.

Work Plane 2 (wp2)>Circle 1 (c1)

- I In the Work Plane toolbar, click ( ) Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type r stator-h stat-air gap/2.
- **4** Locate the **Layers** section. In the table, enter the following settings:

| Layer name | Thickness (m)                             |
|------------|---|
| Layer 1    | air_gap/2                                 |
| Layer 2    | th_magnet                                 |
| Layer 3    | r_stator-h_stat-air_gap-th_magnet-r_shaft |

5 Click | Build Selected.

Work Plane 2 (wp2)>Line Segment 1 (ls1)

- I In the Work Plane toolbar, click \* More Primitives and choose Line Segment.
- 2 In the Settings window for Line Segment, locate the Starting Point section.
- 3 From the Specify list, choose Coordinates.
- 4 In the xw text field, type (r\_stator-h\_stat-air\_gap-th\_magnet)\*cos(-angle magnet/2).
- 5 In the yw text field, type (r\_stator-h\_stat-air\_gap-th\_magnet)\*sin(-angle\_magnet/2).
- 6 Locate the Endpoint section. From the Specify list, choose Coordinates.
- 7 In the xw text field, type (r\_stator-h\_stat-air\_gap)\*cos(-angle\_magnet/2).
- 8 In the yw text field, type (r\_stator-h\_stat-air\_gap)\*sin(-angle\_magnet/2).
- 9 Click | Build Selected.

Work Plane 2 (wp2)>Rotate 1 (rot1)

- I In the Work Plane toolbar, click 7 Transforms and choose Rotate.
- 2 Select the object Is I only.
- 3 In the Settings window for Rotate, locate the Rotation section.
- 4 In the Angle text field, type range(360/(n\_poles),360/(n\_poles),360) range(360/(n\_poles)+angle\_magnet,360/(n\_poles),360+angle\_magnet).
- 5 Click **Pauld Selected**.

Work Plane 2 (wp2)>Union 1 (uni1)

- I In the Work Plane toolbar, click Booleans and Partitions and choose Union.
- 2 Select the object cl only.
- 3 Click the Select All button in the Graphics toolbar.
- 4 In the Settings window for Union, click 📳 Build Selected.

Work Plane 2 (wb2)>Delete Entities 1 (del1)

- I Right-click Plane Geometry and choose Delete Entities.
- **2** On the object **unil**, select Boundaries 1, 2, 5, 10–15, 18, 23, 24, 27, 28, 35, 36, 57, 58, 63, and 64 only.
- 3 In the Settings window for Delete Entities, click 📳 Build Selected.

Work Plane 2 (wp2)>Fillet 1 (fil1)

- I In the Work Plane toolbar, click / Fillet.
- 2 On the object **dell**, select Points 2, 3, 7–10, 29–32, 36, and 37 only.

- 3 In the Settings window for Fillet, locate the Radius section.
- 4 In the Radius text field, type fillet.
- 5 Click **Build Selected**.

## Extrude 2 (ext2)

- I In the Model Builder window, under Component I (compl)>Geometry I right-click Work Plane 2 (wp2) and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- 3 From the Specify list, choose Vertices to extrude to.
- 4 On the object unil, select Point 656 only.
- 5 Click **P** Build Selected.

# Work Plane 3 (wb3)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane list, choose yz-plane.
- 4 Click **Parity** Build Selected.

# Form Union (fin)

- I In the Model Builder window, under Component I (compl)>Geometry I click Form Union (fin).
- 2 In the Settings window for Form Union/Assembly, locate the Form Union/Assembly section.
- 3 From the Action list, choose Form an assembly.
- 4 In the Geometry toolbar, click **Build All**.

#### Iron

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Iron in the Label text field.
- 3 On the object fin, select Domains 13, 24, 49, and 60–67 only.

#### Coils

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Coils in the Label text field.
- 3 On the object fin, select Domains 25, 26, and 28–43 only.

#### Aluminum

I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.

- 2 In the Settings window for Explicit Selection, type Aluminum in the Label text field.
- 3 On the object fin, select Domains 14–17, 19–23, 44–47, and 50–52 only.

#### Structure

- I In the Geometry toolbar, click 🔓 Selections and choose Union Selection.
- 2 In the Settings window for Union Selection, type Structure in the Label text field.
- 3 Locate the Input Entities section. Click + Add.
- 4 In the Add dialog box, in the Selections to add list, choose Iron, Coils, and Aluminum.
- 5 Click OK.

# Interior Cavity

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Interior Cavity in the Label text field.
- 3 On the object fin, select Domains 18, 27, 48, and 59 only.

#### PML

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type PML in the Label text field.
- 3 On the object fin, select Domains 1–8, 10–12, and 53–58 only.

#### Air

- I In the Geometry toolbar, click 🔓 Selections and choose Complement Selection.
- 2 In the Settings window for Complement Selection, type Air in the Label text field.
- **3** Locate the **Input Entities** section. Click + Add.
- 4 In the Add dialog box, in the Selections to invert list, choose Structure and Interior Cavity.
- 5 Click OK.

## Loaded Boundaries

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Loaded Boundaries in the Label text field.
- 3 Locate the Entities to Select section. From the Geometric entity level list, choose Boundary.
- 4 On the object fin, select Boundaries 335, 336, 338, 339, 347, 349, 352, 355, 359, 360, 366, 367, 371, 372, 374, 375, 377, 378, 380–385, 389–394, 396, 398, 401, 402, 404, 407, 413-422, 425-428, 438-441, 444, 446-448, 450, 451, 456, 457, 460-463, 466,

469-477, 486-495, 497, 498, 500, 501, 506, 509, 514-517, 520, 521, 523, 524, 526, 529, 532–537, 553–556, 950, 951, 953–956, 958, 959, 962–965, 967, 968, 970–975, 977, 978, 982, 984, 985, 987, 989–992, 994, 997, and 999–1010 only.

#### Exterior Field Calculation

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Exterior Field Calculation in the Label text field.
- 3 Locate the Entities to Select section. From the Geometric entity level list, choose Boundary.
- 4 On the object fin, select Boundaries 31, 32, 36, 39, and 924 only.

## Fixed Boundaries

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Fixed Boundaries in the Label text field.
- 3 Locate the Entities to Select section. From the Geometric entity level list, choose Boundary.
- 4 On the object fin, select Boundaries 213, 214, 217, 247, 249, 257, 291, 292, 294–297, 299, 300, 581, 582, 597, 690, 692, 719, 725, 726, 728–731, 733, and 734 only.

#### Meshed Section

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Meshed Section in the Label text field.
- 3 Locate the Entities to Select section. From the Geometric entity level list, choose Boundary.
- 4 On the object fin, select Boundaries 301, 306, 317, 331, 334, 337, 346, 351, 354, 376, 379, 386, 403, 406, 431, 437, 445, 464, 467, 496, 499, 505, 508, 525, 528, 538, 946, 949, 952, 957, 966, 969, 976, 993, and 996 only.

#### Sweep Domain

- I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Explicit Selection.
- 2 In the Settings window for Explicit Selection, type Sweep Domain in the Label text field.
- 3 On the object fin, select Domains 13, 21–44, 49, and 59–67 only.

# Tetrahedral Domains

I In the Geometry toolbar, click \( \frac{1}{2} \) Selections and choose Complement Selection.

- 2 In the Settings window for Complement Selection, type Tetrahedral Domains in the Label text field.
- 3 Locate the Input Entities section. Click + Add.
- 4 In the Add dialog box, in the Selections to invert list, choose Interior Cavity, PML, and Sweep Domain.
- 5 Click OK.